Linear Motion Systems

THOMSON™

Linear Motion. **Optimized.**

THOMSON™

*Linear Motion. **Optimized.***

Thomson -
Linear Motion. *Optimized.*

Often the ideal design solution is not about finding the fastest, sturdiest, most accurate or even the least expensive option. Rather, the ideal solution is the optimal balance of performance, life and cost.

Thomson is best positioned to help you most quickly configure the optimal linear motion solution for your application.

- **Thomson invented anti-friction linear bearing technology. We own the broadest standard product offering of mechanical motion technologies in the industry.**
- **Modified versions of standard product are routine. White sheet design solutions available across our entire portfolio.**
- **Choose Thomson and gain access to over 70 years of global application experience in diverse industries including packaging, factory automation, material handling, medical, clean energy, printing, automotive, machine tool, aerospace and defense.**
- **As part of Danaher Corporation, we are financially strong and unique in our ability to bring together control, drive, motor, power transmission and precision linear motion technologies.**

Thomson is the name you can trust for quality, innovation, on-time delivery, controlled costs, and reduced risk.

In addition to the information contained in this document, a wealth of product and application information is available online at www.thomsonlinear.com. Also online are downloadable 3D models, software tools, our distributor locator and global contact information for Thomson. For immediate assistance in North America contact us at 1-540-633-3549 or email us at Thomson@thomsonlinear.com.

Talk to us early in the design process to see how Thomson can help identify the optimal balance of performance, life and cost for your next application. And, call us or any of our 2000+ distribution partners around the world for fast delivery of replacement parts.

The Danaher Business System -
Building sustainable competitive advantage into your business

The Danaher Business System (DBS) was established to increase the value we bring to customers. It is a mature and successful set of tools we use daily to continually improve manufacturing operations and product development processes. DBS is based on the principles of Kaizen which continuously and aggressively eliminate waste in every aspect of our business. DBS focuses the entire organization on achieving breakthrough results that create competitive advantages in quality, delivery and performance – advantages that are passed on to you. Through these advantages Thomson is able to provide you faster times to market as well as unsurpassed product selection, service, reliability and productivity.

Local Support Around the Globe
Application Centers Global Manufacturing Operations Global Design & Engineering Centers

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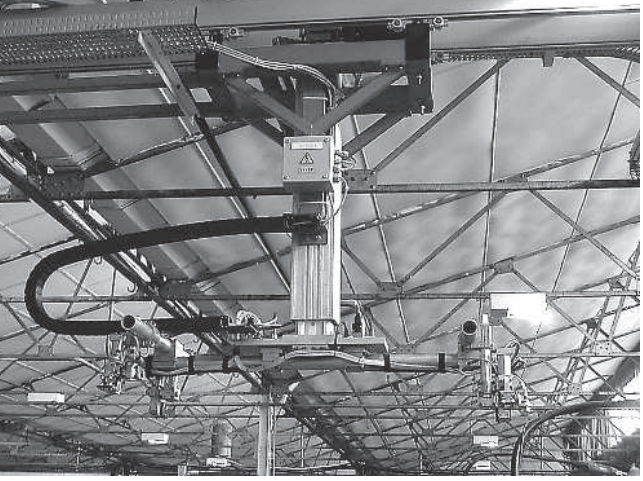
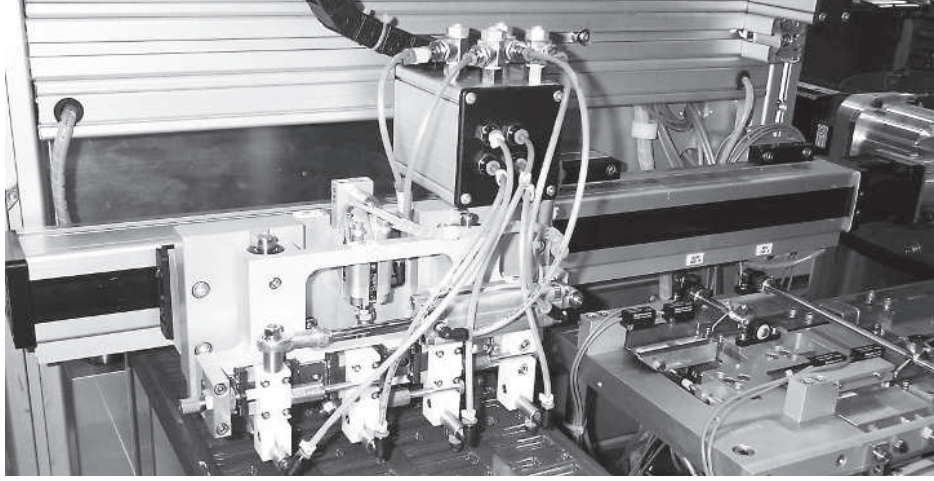
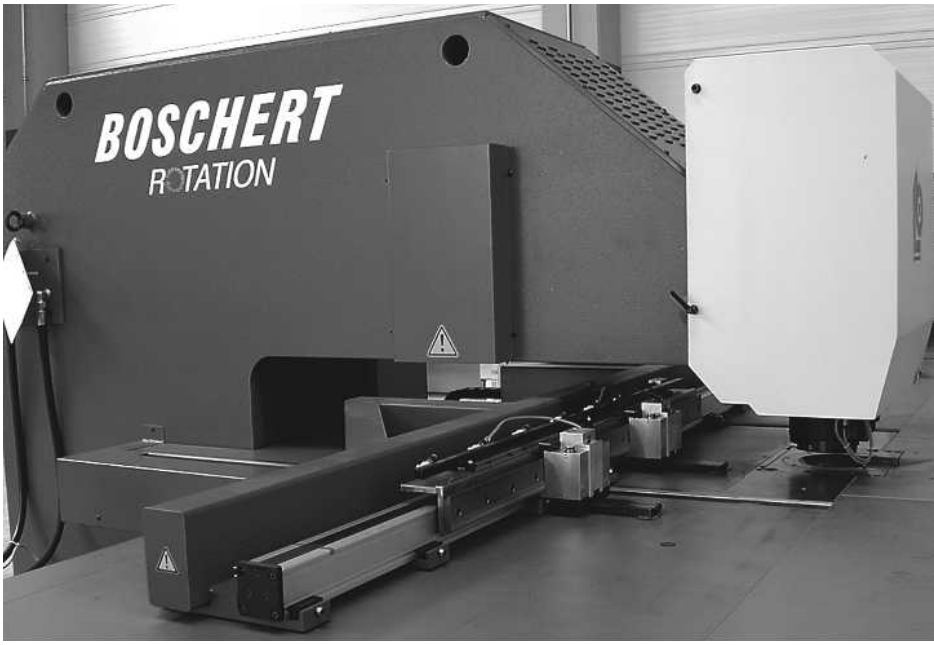
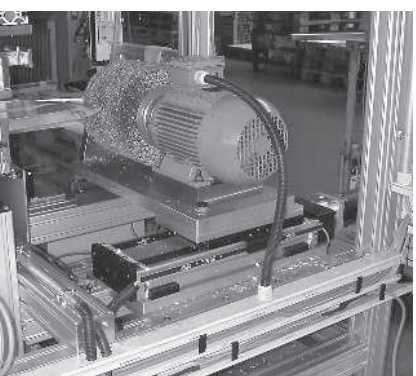
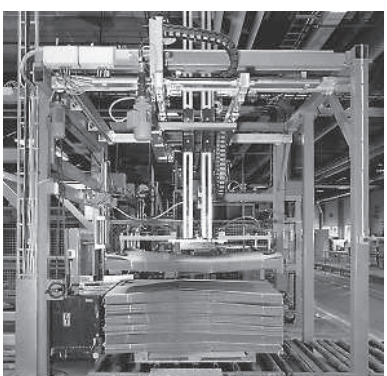


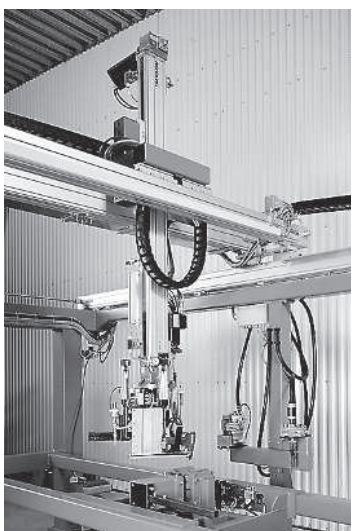


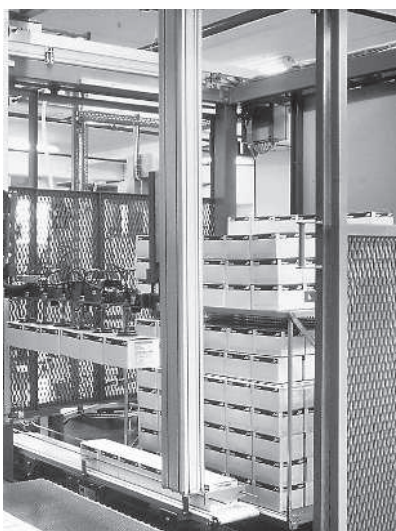

BOSCHERT
ROTATION


125 KG





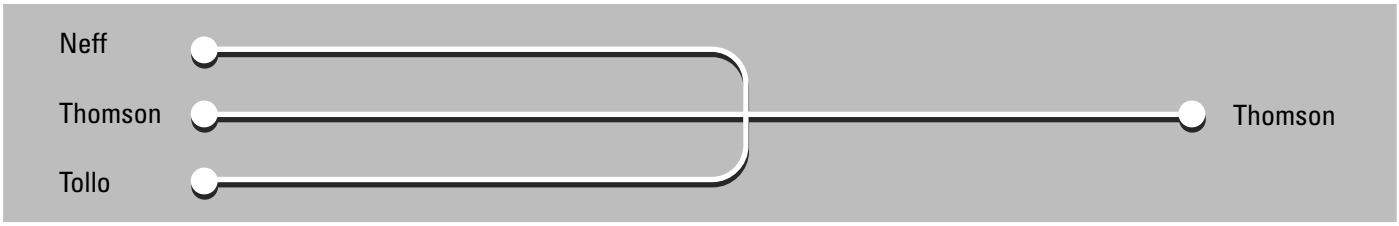




Introduction

Company Introduction

The unmatched breadth of the Thomson linear motion system product line comes from the consolidation of three world-reknowned brands: Thomson, Neff and Tollo. We are product innovators with decades of application experience. Unbiased ownership of the multiple motion system technologies enable Thomson to provide you with the optimal balance of performance versus installed cost for your application.



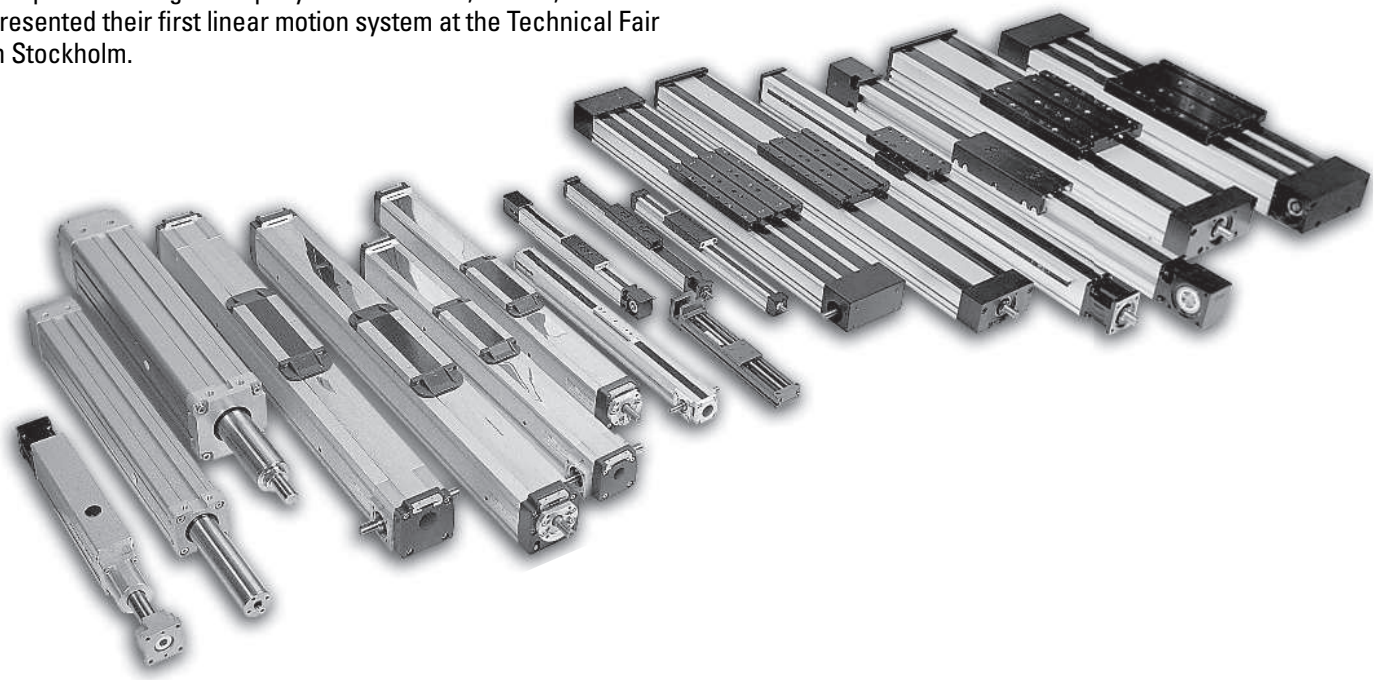
Founded in 1905, Neff offered products for the linear motion market and, over the decades, became a market leader in ball screw technology. The first linear motion system from Neff was presented in 1981 at the FAMETA show in Stuttgart.

Thomson introduced the first ball screw actuator into an aviation application in 1939 and invented the anti-friction Linear Ball Bushing® Bearing in 1945. Thomson has been a market lead with an increasing portfolio of linear motion technologies ever since.

Tollo began in 1981 as a lifting equipment manufacturer. The product line grew rapidly thereafter and, in 1982, Tollo presented their first linear motion system at the Technical Fair in Stockholm.

Thomson has consolidated the most competitive and complementary products from each brand into the most advanced, most comprehensive product portfolio available today. The range covers the smallest and most compact linear motion systems to the biggest and most robust. Our wide range of guide and drive systems can be configured economically and can also work in harsh environments, at high speeds, and in high precision applications.

Thomson is linear motion, optimized.



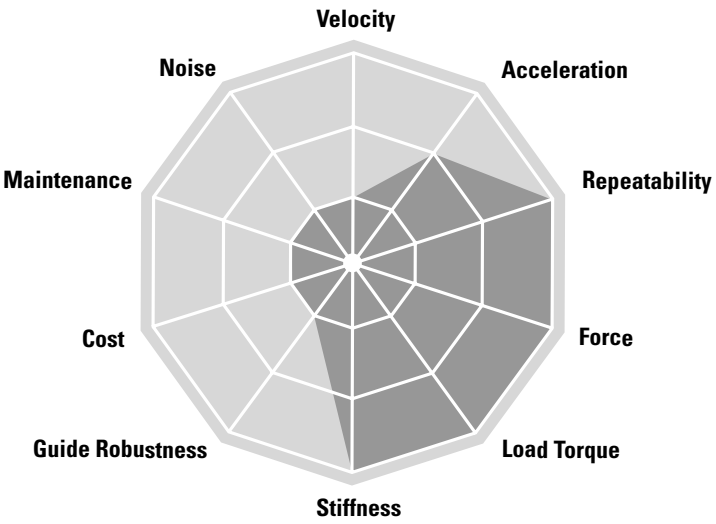
Introduction

How To Choose a Linear Motion System

Thomson offer a wide range of linear units, each designed for a specific purpose and with its own unique features. On www.thomsonlinear.com/selectors you can find a product advisor that will help you specify the unit you need, and our application engineers will be happy to help you with further technical advice.

The diagrams shown here give you a brief overview of the key strengths of each group.

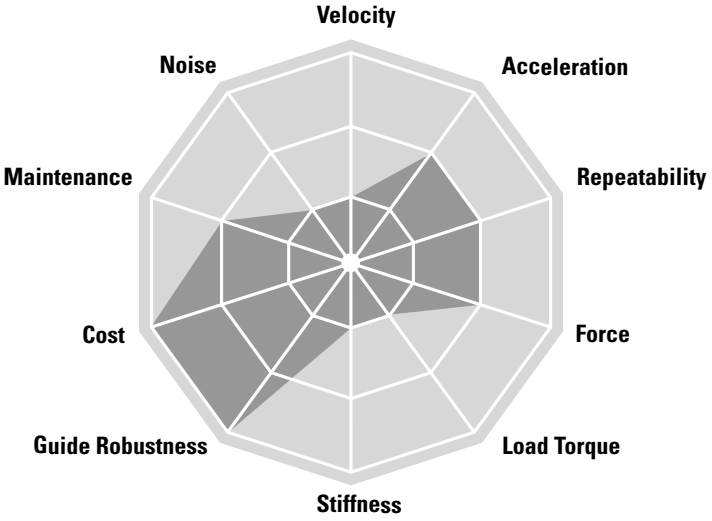
Ball Screw Driven, Ball Guided Units



Units designed for high thrust, payload, high precision and stiffness.

- Force up to 12000 N
- Repeatability down to 0,005mm

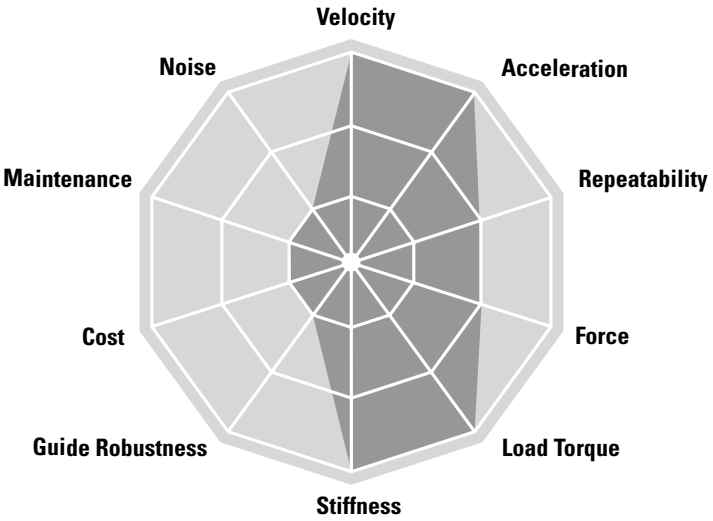
Ball Screw Driven, Slide Guided Units



Designed for low cost, high thrust operations in demanding environments.

- Cost efficient units
- Washdown protected versions
- Durable guide system

Belt Driven, Ball Guided Units



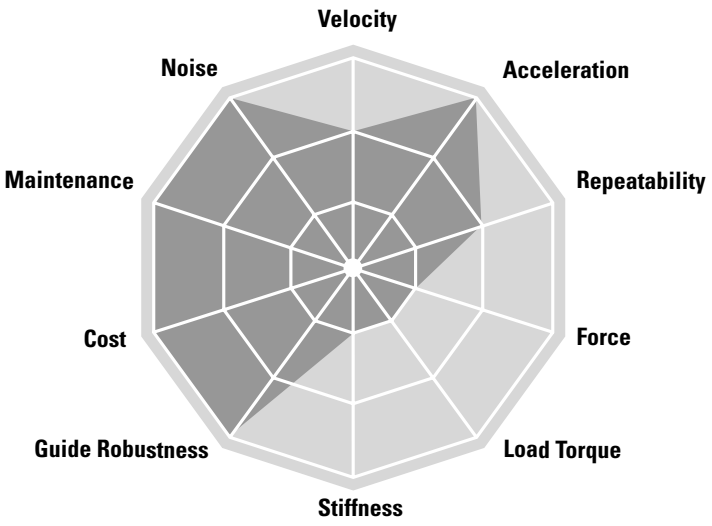
Smooth running units for dynamic applications with high speed, high acceleration and high loads requiring a long lifetime.

- Speed up to 5 m/s
- Acceleration up to 40 m/s^2

Introduction

How To Choose a Linear Motion System

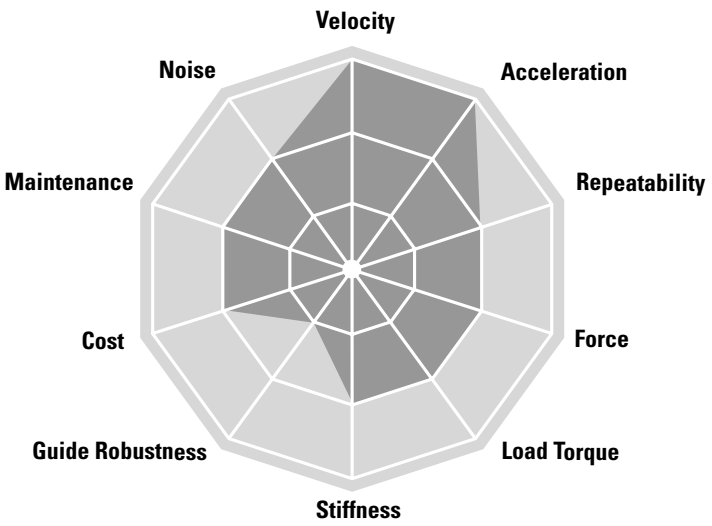
Belt Driven, Slide Guided Units



Units for dynamic applications requiring high speed, high acceleration, low maintenance and smooth travel.

- Cost efficient guide system
- Chemically protected versions

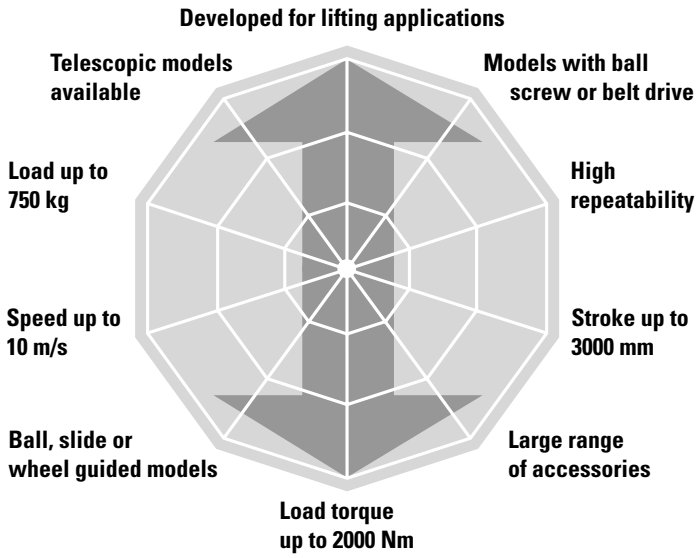
Belt Driven, Wheel Guided Units



Units for dynamic applications with high speed, high acceleration, smooth motion and medium to high loads.

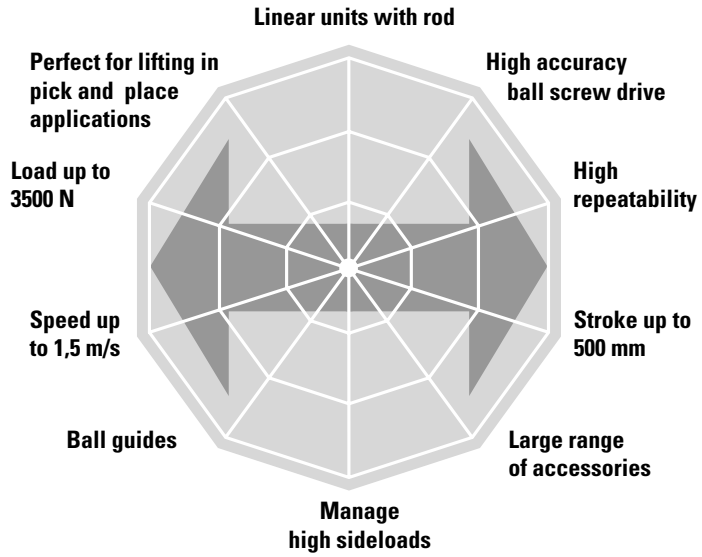
- Speed up to 10 m/s
- Acceleration up to 40 m/s^2

Linear Lifting Systems



Units for lifting applications. Often used in X-Y configurations in combination with other linear units.

Linear Rod Units

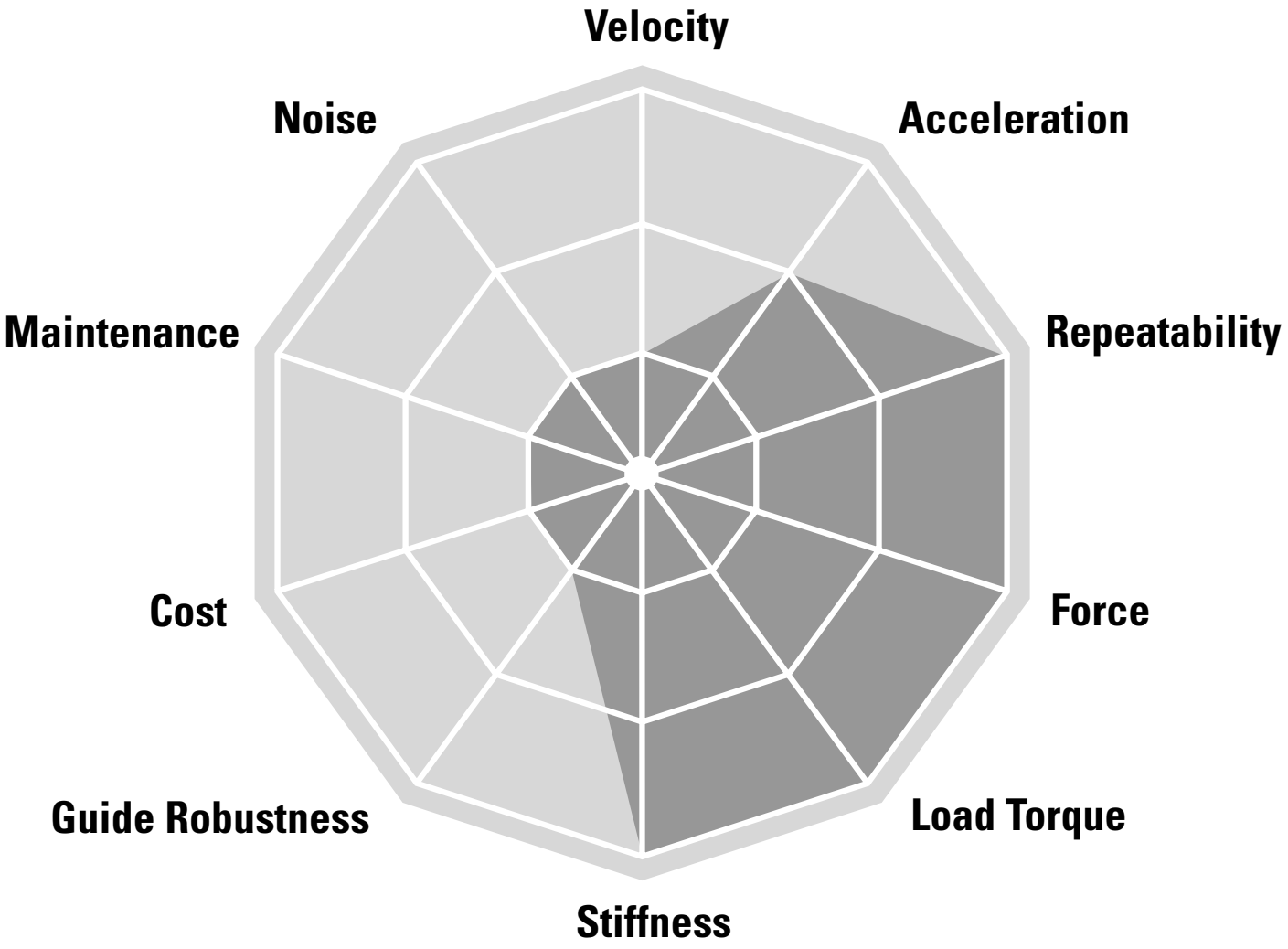


Units designed for lifting applications or for the replacement of hydraulic and pneumatic cylinders.


THOMSON
Linear Motion Optimized.

Linear Motion Systems with Ball Screw Drive and Ball Guide

PowerLine, ForceLine



Typical Applications

Typical applications are where high accuracy and load capability is required but where speed is less important. Typical examples are machining operations and in the handling of heavy goods that need accurate positioning.

Linear Motion Systems with Ball Screw Drive and Ball Guide

Overview

PowerLine WM

WM40

Features

- Can be installed in all directions
- Patented guide system
- Patented self-adjusting plastic cover band
- Patented screw support system

Parameter		WM40S	WM40D	WM60D	WM60S	WM60X	WM80D	WM80S	WM120D
Profile size (width × height)	[mm]	40 × 40	40 × 40	60 × 60	60 × 60	60 × 60	80 × 80	80 × 80	120 × 120
Stroke length (S max), maximum	[mm]	2000	2000	11000	5000	10340	11000	5000	11000
Linear speed, maximum	[m/s]	0,25	0,25	2,5	2,5	0,25	2,5	2,5	2,0
Dynamic carriage load (Fz), maximum	[N]	600	600	2000	1400	2000	3000	2100	6000
Remarks		single ball nut	double ball nuts	double ball nuts	single ball nut	left/right screw	double ball nuts	single ball nut	double ball nuts
Page		12	14	16	18	20	22	24	26

PowerLine WV

WV80

Features

- Can be installed in all directions
- Patented self-adjusting plastic cover band
- Patented screw support system
- The units require external guides

Parameter		WV60	WV80	WV120
Profile size (width × height)	[mm]	60 × 60	80 × 80	120 × 120
Stroke length (S max), maximum	[mm]	11000	11000	11000
Linear speed, maximum	[m/s]	2,5	2,5	2,0
Dynamic carriage load (Fz), maximum	[N]	-	-	-
Remarks		double ball nuts the units has no guides	double ball nuts the units has no guides	double ball nuts the units has no guides
Page		28	30	32

Linear Motion Systems with Ball Screw Drive and Ball Guide

Overview

ForceLine **MLSM**

MLSM80D

Features

- Can be installed in all directions
- Patented guide system
- Patented plastic cover band
- Patented screw support system

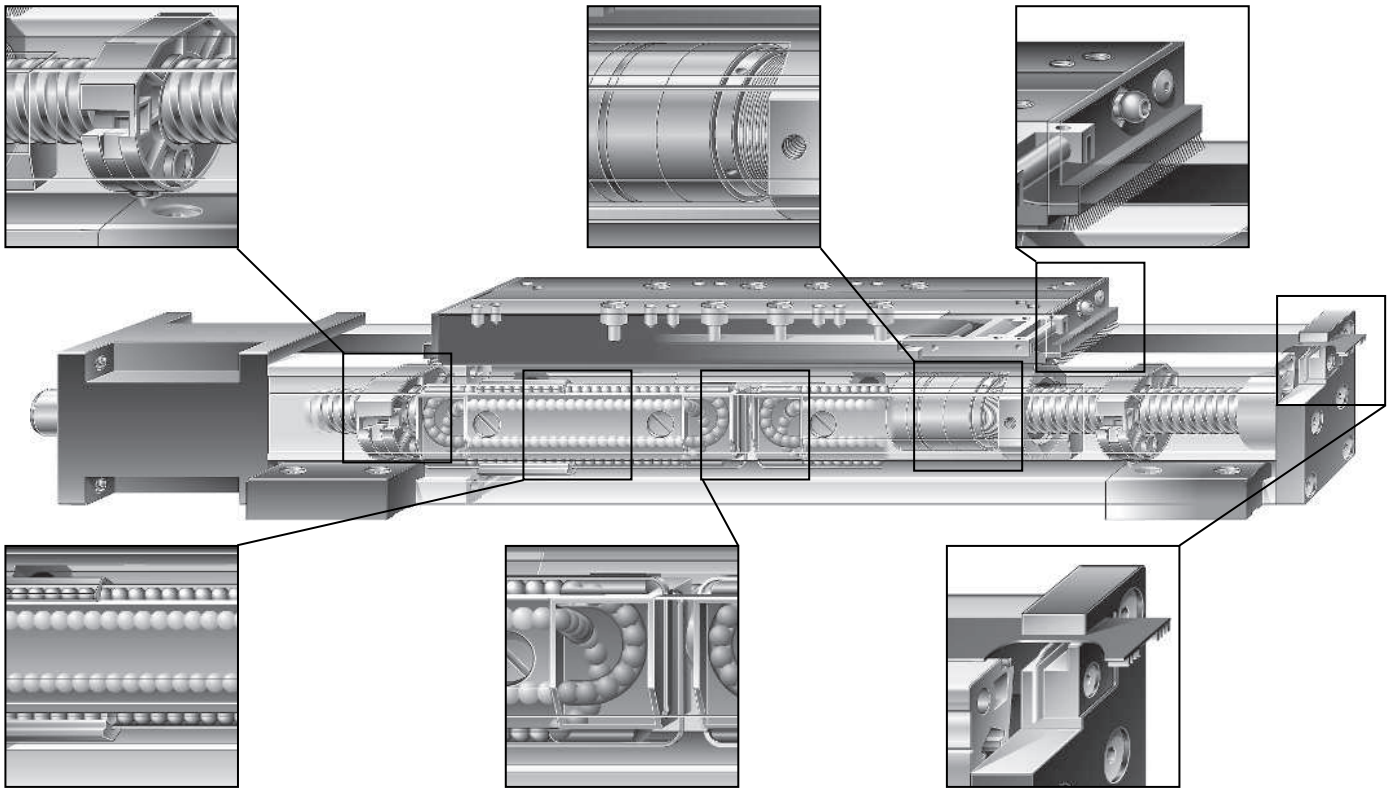
Parameter		MLSM60D	MLSM80D
Profile size (width × height)	[mm]	160 × 65	240 × 85
Stroke length (S max), maximum	[mm]	5500	5200
Linear speed, maximum	[m/s]	2,5	2,0
Dynamic carriage load (Fz), maximum	[N]	6000	8000
Remarks		double ball nuts	double ball nuts
Page		34	36

WM-Series Technical Presentation

Screw support
Patented screw support system permits high speed at long stroke lengths while reducing the stroke with a minimum.

Double ball nuts
Double pre-tensioned ball nuts improve the accuracy and allows re-tensioning increasing the lifetime of the unit.

Central lubrication
One central lubrication point on the carriage services the entire unit resulting in a minimum maintenace required.



Ball guides
Integrated patented ball guides with hardened steel tracks for optimum performance.

Ball cages
The balls in the ball guides are protected by a ball cage which ensures a long life.

Cover band
The patented self-adjusting cover band protect the unit from the penetration of dirt, dust and liquids.

WM40S

Ball Screw Drive, Ball Guide, Single Ball Nut

» Ordering key - see page 182
» Accessories - see page 125
» Additional data - see page 171

General Specifications

Parameter	WM40S
Profile size (w × h) [mm]	40 × 40
Type of screw	ball screw with single nut
Carriage sealing system	self-adjusting plastic cover band
Screw supports	included in all units that require screw supports
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WM40S
Stroke length (S max), maximum	[mm]	2000
Linear speed, maximum	[m/s]	0,25
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,02
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	1000
Dynamic load (Fy), maximum	[N]	450[1] / 5300[2]
Dynamic load (Fz), maximum	[N]	600[1] / 6790[2]
Dynamic load torque (Mx), maximum	[Nm]	10[1] / 30[2]
Dynamic load torque (My), maximum	[Nm]	30[1] / 230[2]
Dynamic load torque (Mz), maximum	[Nm]	30[1] / 230[2]
Drive shaft force (Frd), maximum	[N]	100
Drive shaft torque (Mta), maximum	[Nm]	3
Ball screw diameter (d_0)	[mm]	12
Ball screw lead (p)	[mm]	5
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 1,50 0,30 0,36

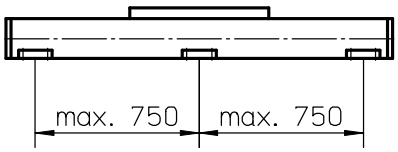
[1] Value for the complete unit
[2] Value for the ball guide only

Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]
	p = 5
150	0,3
1500	0,5
3000	0,8

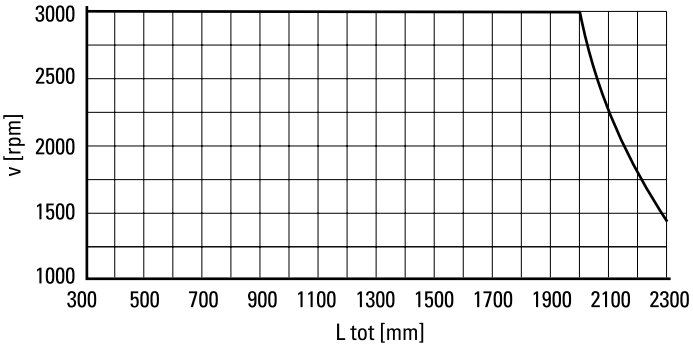
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

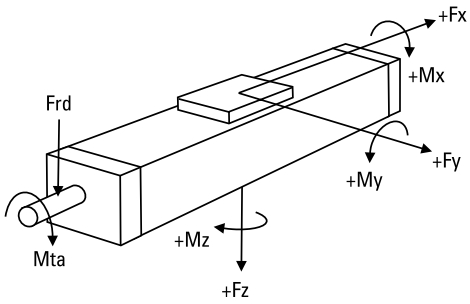


A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Critical Speed

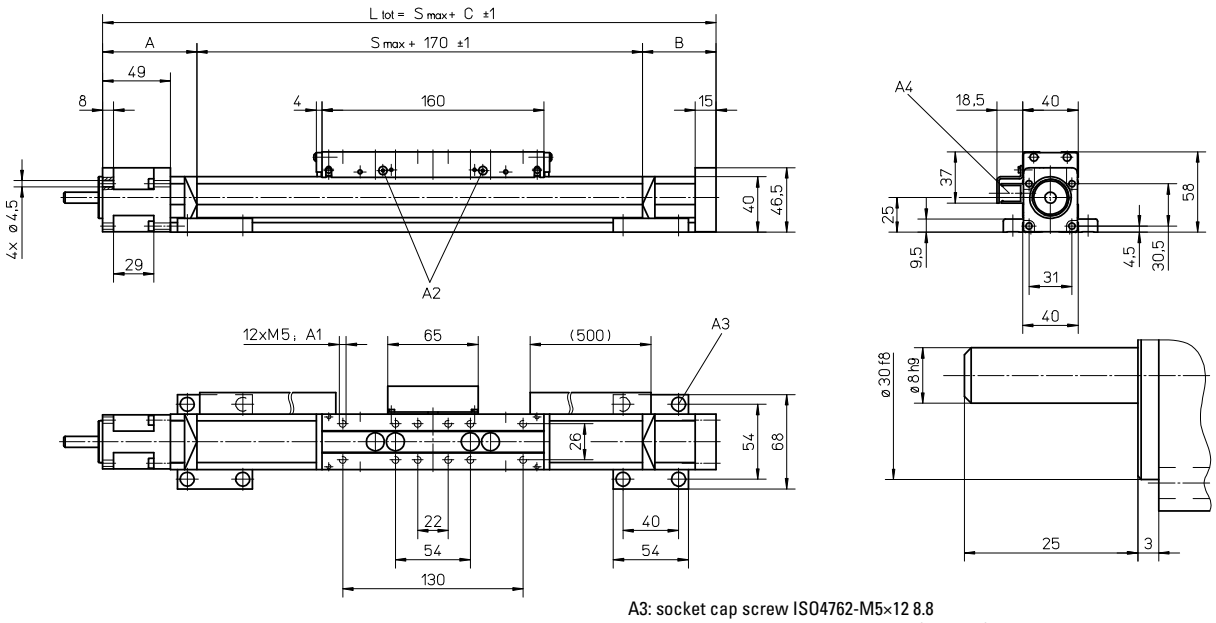


Definition of Forces



WM40S

Ball Screw Drive, Ball Guide, Single Ball Nut



A1: depth 7
A2: lubricating nipple on both sides DIN3405 D 1/A
A3: socket cap screw ISO4762-M5×12 8.8
A4: ENF inductive sensor rail option kit (optional)

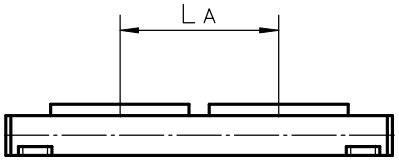
Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
0 – 500 (0 – 450)	65	35	270 (320)
501 – 1100 (451 – 1050)	65	45	280 (330)
1101 – 2000 (1051 – 1950)	70	60	300 (350)

Values between brackets = for units with long carriage

Double Carriages

Parameter		WM40S
Minimum distance between carriages (L A)	[mm]	175
Dynamic load (Fy), maximum	[N]	900
Dynamic load (Fz), maximum	[N]	1200
Dynamic load torque (My), maximum	[Nm]	L A[1] × 0,45
Dynamic load torque (Mz), maximum	[Nm]	L A[1] × 0,6
Force required to move second carriage	[N]	4
Total length (L tot)	[mm]	S max + C + L A

[1] Value in mm



WM40D

Ball Screw Drive, Ball Guide, Double Ball Nuts, Long Carriage

» Ordering key - see page 182
» Accessories - see page 125
» Additional data - see page 171

General Specifications

Parameter	WM40D
Profile size (w × h) [mm]	40 × 40
Type of screw	ball screw with double nuts
Carriage sealing system	self-adjusting plastic cover band
Screw supports	included in all units that require screw supports
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WM40D
Stroke length (S max), maximum	[mm]	1950
Linear speed, maximum	[m/s]	0,25
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,01
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	1000
Dynamic load (Fy), maximum	[N]	450[1] / 5300[2]
Dynamic load (Fz), maximum	[N]	600[1] / 6790[2]
Dynamic load torque (Mx), maximum	[Nm]	10[1] / 30[2]
Dynamic load torque (My), maximum	[Nm]	30[1] / 230[2]
Dynamic load torque (Mz), maximum	[Nm]	30[1] / 230[2]
Drive shaft force (Frd), maximum	[N]	100
Drive shaft torque (Mta), maximum	[Nm]	3
Ball screw diameter (d_0)	[mm]	12
Ball screw lead (p)	[mm]	5
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 1,90 0,30 0,60

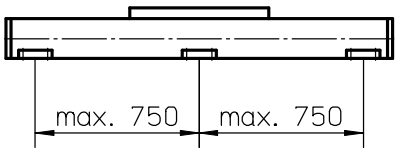
[1] Value for the complete unit
[2] Value for the ball guide only

Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]
	p = 5
150	0,4
1500	0,6
3000	0,9

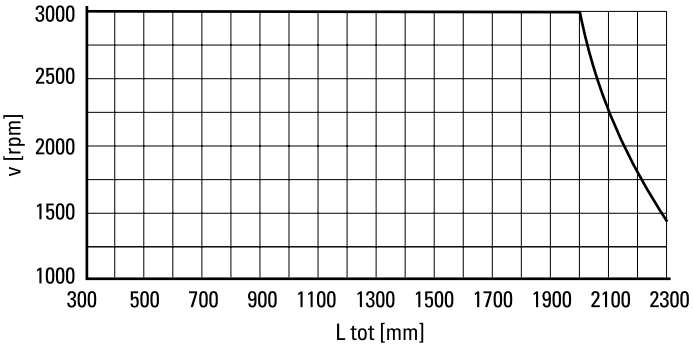
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

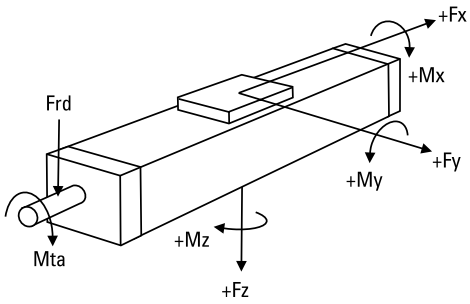


A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Critical Speed

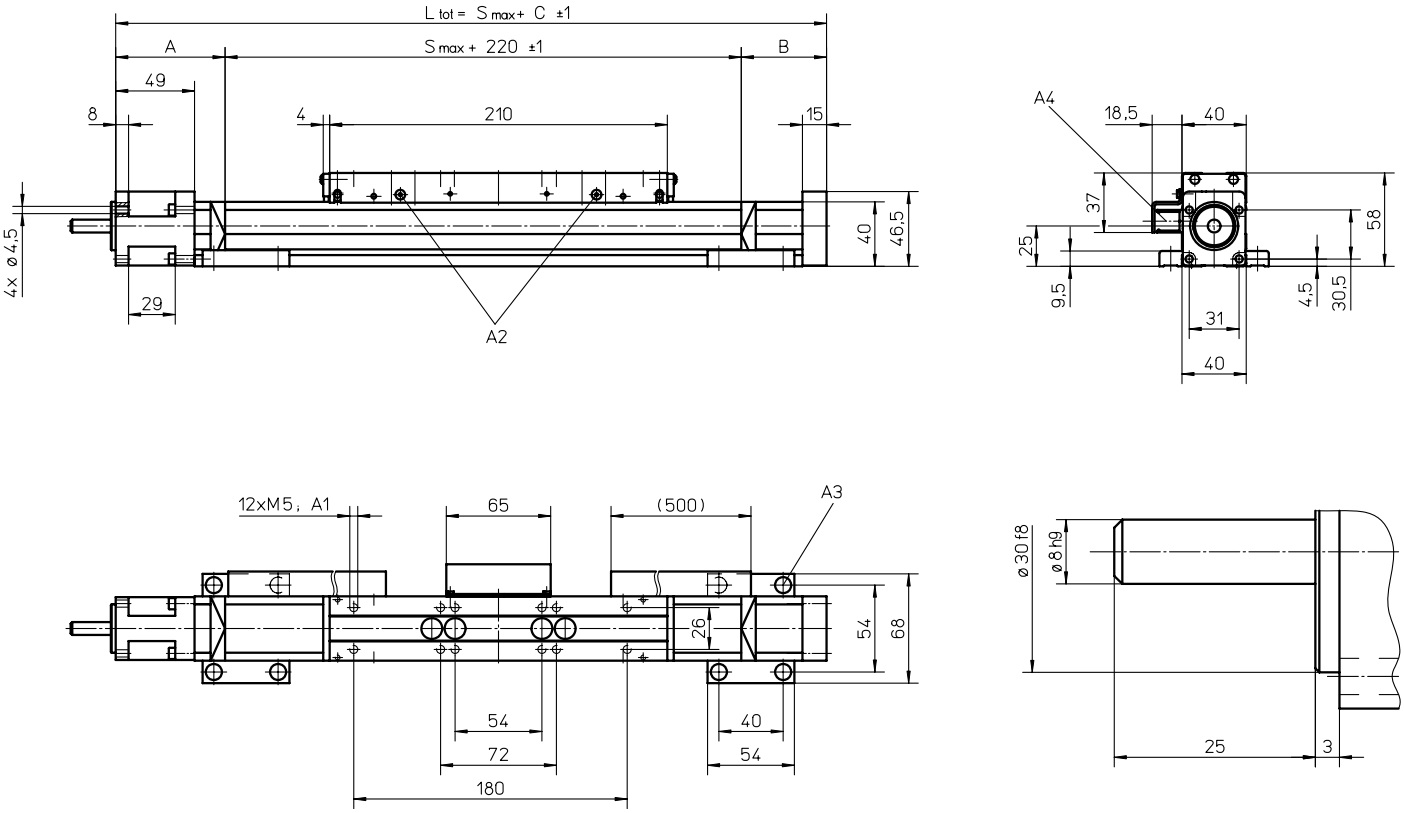


Definition of Forces



WM40D

Ball Screw Drive, Ball Guide, Double Ball Nuts, Long Carriage



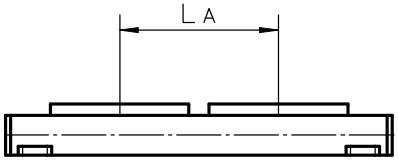
A1: depth 6
A2: lubricating nipple on both sides DIN3405 D 1/A
A3: socket cap screw ISO4762-M5×12 8.8
A4: ENF inductive sensor rail option kit (optional)

Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
0 – 500	65	35	320
501 – 1100	65	45	330
1101 – 2000	70	60	350

Double Long Carriages

Parameter		WM40D
Minimum distance between carriages (L_A)	[mm]	225
Dynamic load (Fy), maximum	[N]	900
Dynamic load (Fz), maximum	[N]	1200
Dynamic load torque (My), maximum	[Nm]	L_A[1] × 0,45
Dynamic load torque (Mz), maximum	[Nm]	L_A[1] × 0,6
Force required to move second carriage	[N]	4
Total length (L tot)	[mm]	S max + C + L_A

[1] Value in mm



WM60D

Ball Screw Drive, Ball Guide, Double Ball Nuts

» Ordering key - see page 182
» Accessories - see page 125
» Additional data - see page 171

General Specifications

Parameter	WM60D
Profile size (w × h) [mm]	60 × 60
Type of screw	ball screw with double nut
Carriage sealing system	self-adjusting plastic cover band
Screw supports	included in all units that require screw supports
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WM60D
Stroke length (S max), maximum screw lead 5, 20 mm screw lead 50 mm	[mm]	 11000 5000
Linear speed, maximum	[m/s]	2,5
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,01
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	4000
Dynamic load (Fy), maximum	[N]	2000[1] / 45980[2]
Dynamic load (Fz), maximum	[N]	2000[1] / 42320[2]
Dynamic load torque (Mx), maximum	[Nm]	100[1] / 740[2]
Dynamic load torque (My), maximum	[Nm]	200[1] / 2990[2]
Dynamic load torque (Mz), maximum	[Nm]	200[1] / 3250[2]
Drive shaft force (Frd), maximum	[N]	500
Drive shaft torque (Mta), maximum	[Nm]	35
Ball screw diameter (d_0)	[mm]	20
Ball screw lead (p)	[mm]	5, 20, 50
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 6,16 0,65 1,99

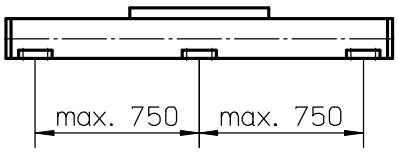
[1] Value for the complete unit
[2] Value for the ball guide only

Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]		
	p = 5	p = 20	p = 50
150	0,8	1,3	1,6
1500	1,4	2,0	2,4
3000	1,8	2,3	2,6

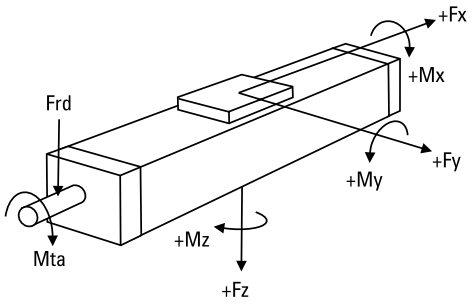
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile



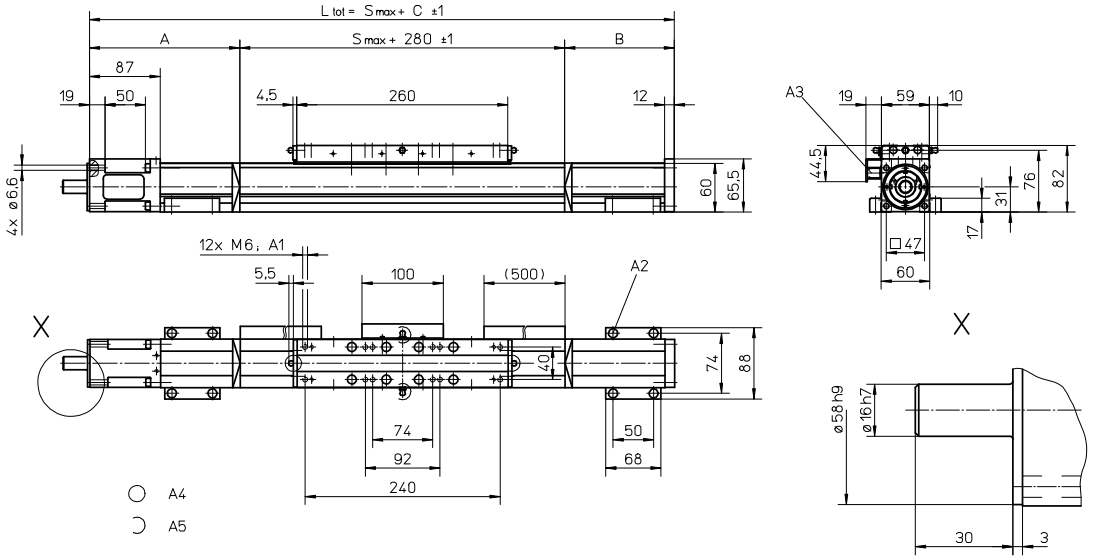
A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information. Units with a profile length over 6300 mm consists of two profiles where the joint between the two profiles must be addequately supported on both sides.

Definition of Forces



WM60D

Ball Screw Drive, Ball Guide, Double Ball Nuts



A1: depth 11
A2: socket cap screw ISO4762-M6×20 8.8
A3: ENF inductive sensor rail option kit (optional)
A4: tapered lubricating nipple to DIN71412 AM6 on fixed-bearing side as standard feature
A5: can be changed over to one of the three alternative lubricating points by the customer

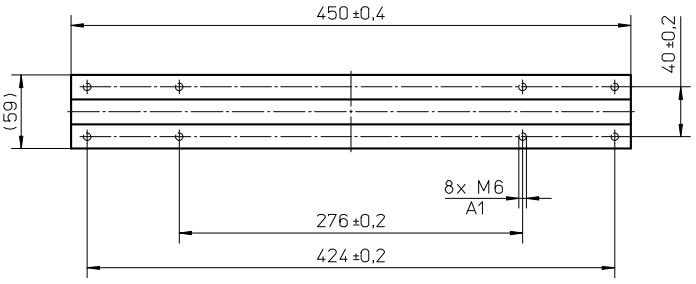
Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
0 - 695 (0 - 505)	115	65	460 (650)
696 - 1335 (506 - 1145)	165	115	560 (750)
1336 - 2075 (1146 - 1885)	185	135	600 (790)
2076 - 2780 (1886 - 2590)	210	160	650 (840)

Values between brackets = for units with long carriage

Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
2781 - 3545 (2591 - 3355)	230	180	690 (880)
3546 - 4285 (3366 - 4095)	250	200	730 (920)
4286 - 5015 (4096 - 4825)	275	225	780 (970)
5016 - 11000 (4826 - 10810)	contact customer service		

Long Carriage

Parameter		WM60D
Carriage length	[mm]	450
Dynamic load torque (My), maximum	[Nm]	500
Dynamic load torque (Mz), maximum	[Nm]	500
Weight	[kg]	3,1

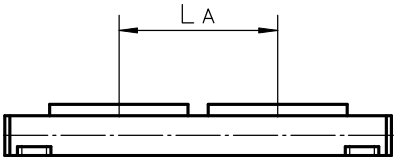


A1: depth 11

Double Carriages

Parameter		WM60D
Minimum distance between carriages (L_A)	[mm]	335
Dynamic load (Fy), maximum	[N]	4000
Dynamic load (Fz), maximum	[N]	4000
Dynamic load torque (My), maximum	[Nm]	L_A[1] × 2
Dynamic load torque (Mz), maximum	[Nm]	L_A[1] × 2
Force required to move second carriage	[N]	20
Total length (L tot)	[mm]	S max + C + L_A

[1] Value in mm



WM60S

Ball Screw Drive, Ball Guide, Single Ball Nut, Short Carriage

» Ordering key - see page 182
» Accessories - see page 125
» Additional data - see page 171

General Specifications

Parameter	WM60S
Profile size (w × h) [mm]	60 × 60
Type of screw	ball screw with single nut
Carriage sealing system	self-adjusting plastic cover band
Screw supports	included in all units that require screw supports
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WM60S
Stroke length (S max), maximum	[mm]	5000
Linear speed, maximum	[m/s]	2,5
Acceleration, maximum	[m/s²]	10
Repeatability	[± mm]	0,02
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	2800
Dynamic load (Fy), maximum	[N]	1400[1] / 25920[2]
Dynamic load (Fz), maximum	[N]	1400[1] / 23860[2]
Dynamic load torque (Mx), maximum	[Nm]	50[1] / 410[2]
Dynamic load torque (My), maximum	[Nm]	100[1] / 320[2]
Dynamic load torque (Mz), maximum	[Nm]	100[1] / 320[2]
Drive shaft force (Frd), maximum	[N]	500
Drive shaft torque (Mta), maximum	[Nm]	35
Ball screw diameter (d0)	[mm]	20
Ball screw lead (p)	[mm]	5, 20, 50
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 3,80 0,65 1,00

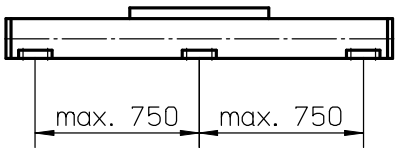
[1] Value for the complete unit
[2] Value for the ball guide only

Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]		
	p = 5	p = 20	p = 50
150	0,7	1,0	1,4
1500	1,1	1,6	2,0
3000	1,5	1,8	2,2

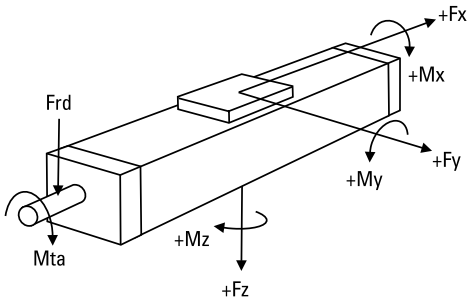
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile



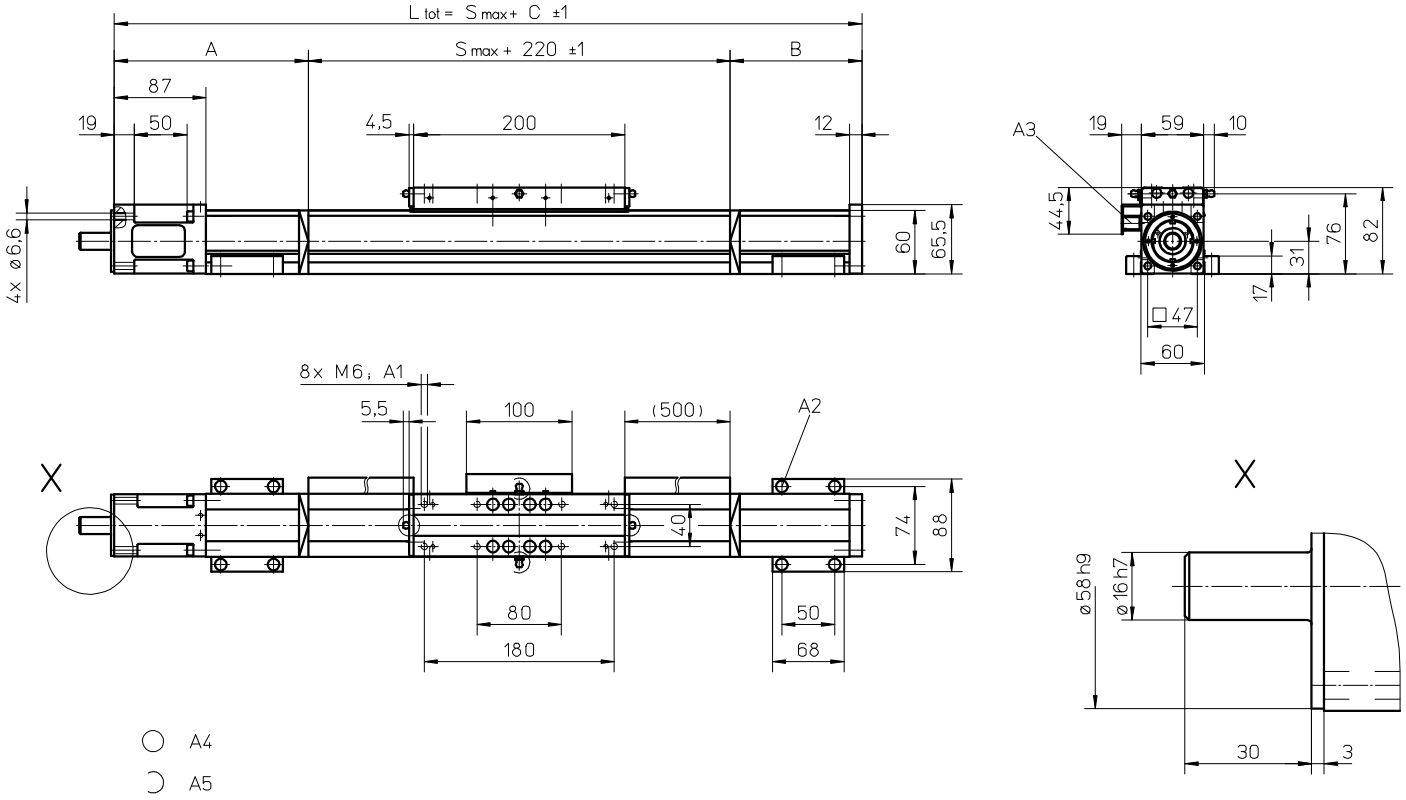
A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Definition of Forces



WM60S

Ball Screw Drive, Ball Guide, Single Ball Nut, Short Carriage



A1: depth 11
A2: socket cap screw ISO4762-M6×20 8.8
A3: ENF inductive sensor rail option kit (optional)

A4: tapered lubricating nipple to DIN71412 AM6 on fixed-bearing side as standard feature
A5: can be changed over to one of the three alternative lubricating points by the customer

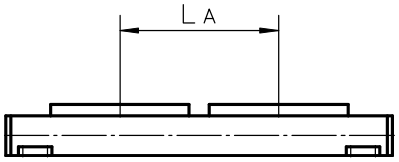
Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
0 - 580	95	20	335
581 - 1140	110	60	390
1141 - 1805	130	80	430
1806 - 2460	155	105	480

Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
2461 - 3125	175	125	520
3126 - 3780	200	150	570
3781 - 4445	220	170	610
4446 - 5000	240	190	650

Double Short Carriages

Parameter		WM60S
Minimum distance between carriages (L_A)	[mm]	255
Dynamic load (Fy), maximum	[N]	2800
Dynamic load (Fz), maximum	[N]	2800
Dynamic load torque (My), maximum	[Nm]	L_A[1] × 1,4
Dynamic load torque (Mz), maximum	[Nm]	L_A[1] × 1,4
Force required to move second carriage	[N]	18
Total length (L tot)	[mm]	S max + C + L_A

[1] Value in mm



WM60X

Ball Screw Drive, Ball Guide, Left/right Moving Carriages

» Ordering key - see page 182
» Accessories - see page 125
» Additional data - see page 171

General Specifications

Parameter	WM60X
Profile size (w × h) [mm]	60 × 60
Type of screw	ball screw with double nut
Carriage sealing system	self-adjusting plastic cover band
Screw supports	included in all units that require screw supports
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WM60X
Stroke length (S max), maximum	[mm]	10340
Linear speed, maximum	[m/s]	0,25
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,01
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	4000
Dynamic load (Fy), maximum	[N]	2000[1] / 45980[2]
Dynamic load (Fz), maximum	[N]	2000[1] / 42320[2]
Dynamic load torque (Mx), maximum	[Nm]	100[1] / 740[2]
Dynamic load torque (My), maximum	[Nm]	200[1] / 2990[2]
Dynamic load torque (Mz), maximum	[Nm]	200[1] / 3250[2]
Drive shaft force (Frd), maximum	[N]	500
Drive shaft torque (Mta), maximum	[Nm]	35
Ball screw diameter (d0)	[mm]	20
Ball screw lead (p)	[mm]	5
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 10,33 0,65 1,99

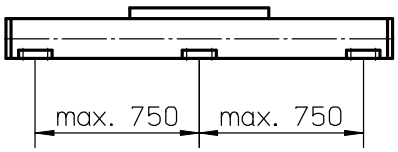
[1] Value for the complete unit
[2] Value for the ball guide only

Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]
	p = 5
150	1,6
1500	2,8
3000	3,6

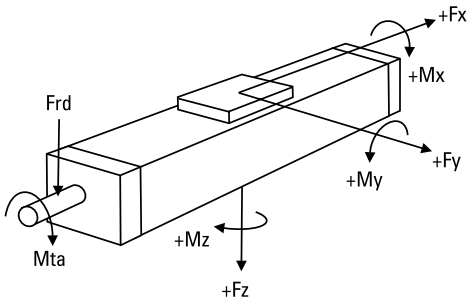
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile



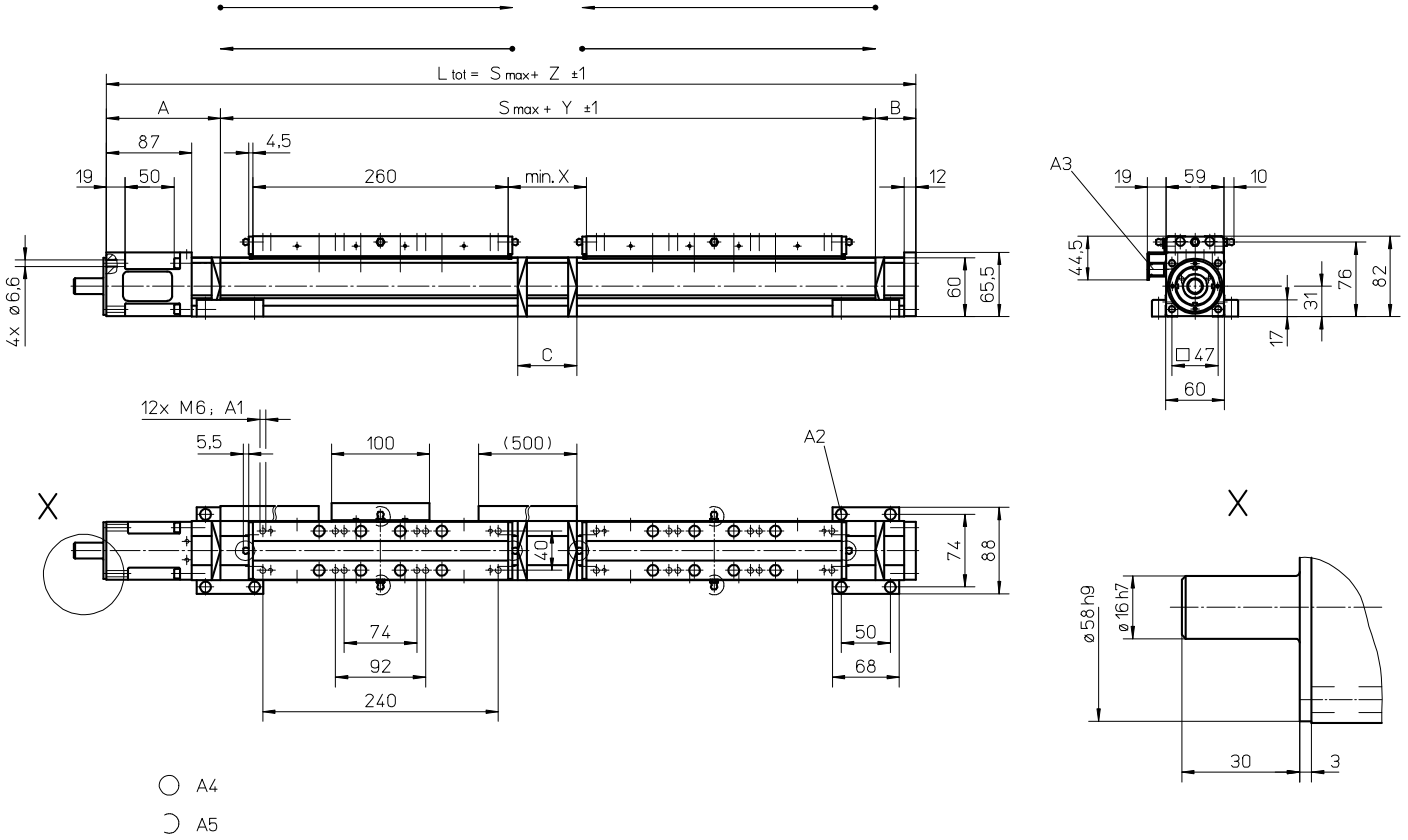
A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information. Units with a profile length over 5400 mm consists of two profiles where the joint between the two profiles must be addequately supported on both sides.

Definition of Forces



WM60X

Ball Screw Drive, Ball Guide, Left/right Moving Carriages



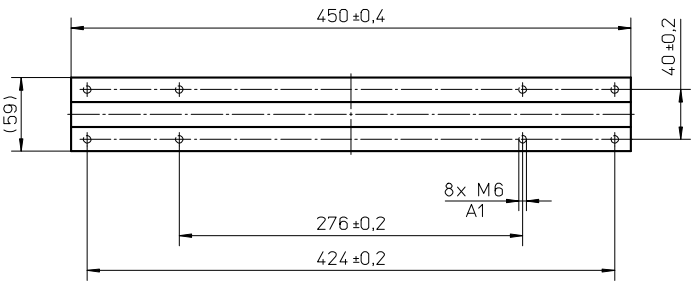
A1: depth 11
A2: socket cap screw ISO4762-M6×20 8.8
A3: ENF inductive sensor rail option kit (optional)
A4: tapered lubricating nipple to DIN71412 AM6 on fixed-bearing side as standard feature
A5: can be changed over to one of the three alternative lubricating points by the customer

Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]	X [mm]	Y [mm]	Z [mm]
0 - 1390 (0 - 1200)	115	65	60	80	620	800
1391 - 2670 (1201 - 2480)	165	115	210	230	770	1050
2671 - 4150 (2481 - 3960)	185	135	250	270	810	1130
4151 - 5560 (3961 - 5370)	210	160	300	320	860	1230
5561 - 10340 (5371 - 10150)	contact customer sevice					

Values between brackets = for units with long carriage

Long Carriage

Parameter		WM60X
Carriage length	[mm]	450
Dynamic load torque (My), maximum	[Nm]	500
Dynamic load torque (Mz), maximum	[Nm]	500
Weight	[kg]	3,1



A1: depth 11

WM80D

Ball Screw Drive, Ball Guide, Double Ball Nuts

» Ordering key - see page 182
» Accessories - see page 125
» Additional data - see page 171

General Specifications

Parameter	WM80D
Profile size (w × h) [mm]	80 × 80
Type of screw	ball screw with double nuts
Carriage sealing system	self-adjusting plastic cover band
Screw supports	included in all units that require screw supports
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WM80D
Stroke length (S max), maximum screw lead 5, 10, 20 mm screw lead 50 mm	[mm]	 11000 5000
Linear speed, maximum	[m/s]	2,5
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,01
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	5000
Dynamic load (Fy), maximum	[N]	3000[1] / 57420[2]
Dynamic load (Fz), maximum	[N]	3000[1] / 54950[2]
Dynamic load torque (Mx), maximum	[Nm]	350[1] / 1360[2]
Dynamic load torque (My), maximum	[Nm]	300[1] / 4230[2]
Dynamic load torque (Mz), maximum	[Nm]	300[1] / 4220[2]
Drive shaft force (Frd), maximum	[N]	700
Drive shaft torque (Mta), maximum	[Nm]	55
Ball screw diameter (d0)	[mm]	25
Ball screw lead (p)	[mm]	5, 10, 20, 50
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 11,57 1,08 4,26

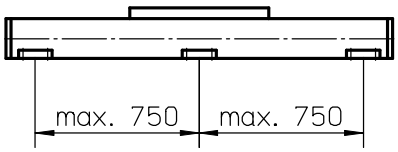
[1] Value for the complete unit
[2] Value for the ball guide only

Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]			
	p = 5	p = 10	p = 20	p = 50
150	1,1	1,5	1,8	2,3
1500	1,7	2.1	2,3	3,0
3000	2,1	2,5	2,6	3,6

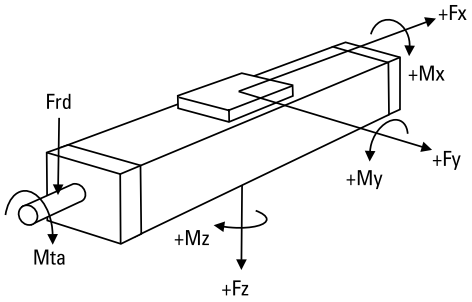
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile



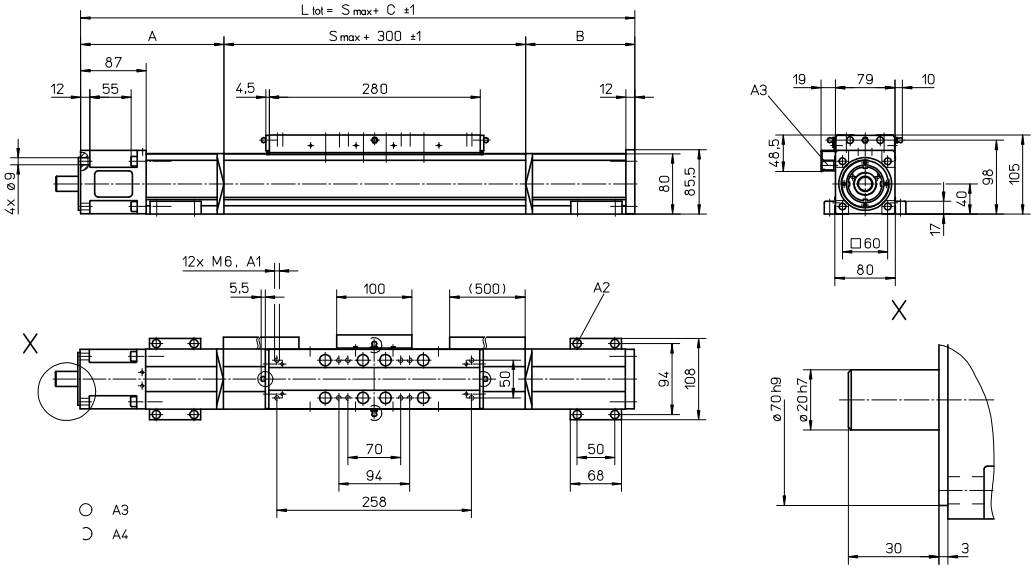
A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information. Units with a profile length over 6300 mm consists of two profiles where the joint between the two profiles must be addequately supported on both sides.

Definition of Forces



WM80D

Ball Screw Drive, Ball Guide, Double Ball Nuts



A1: depth 12 mm
A2: socket cap screw ISO4762-M6×20 8.8
A3: ENF inductive sensor rail option kit (optional)
A4: tapered lubricating nipple to DIN71412 AM6 on fixed-bearing side as standard feature
A5: can be changed over to one of three alternative lubrication points by customer

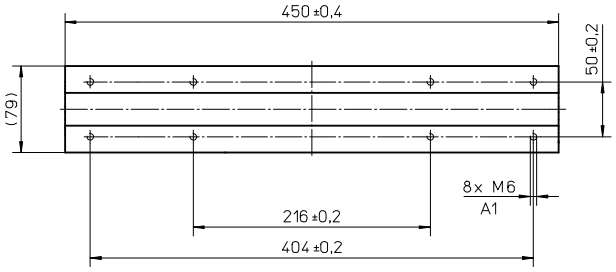
Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
0 - 780 (0 - 610)	120	80	500 (670)
781 - 1535 (611 - 1365)	170	125	595 (765)
1536 - 2375 (1366 - 2205)	190	145	635 (805)
2376 - 3205 (2206 - 3035)	215	170	685 (855)

Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
3206 - 4045 (3036 - 3875)	235	190	725 (895)
4046 - 4885 (3876 - 4715)	255	210	765 (935)
4886 - 5000 (4716 - 4830)	280	235	815 (985)
5001 - 11000 (4717 - 10830)	contact customer service		

Values between brackets = for units with long carriage

Long Carriage

Parameter		WM80D
Carriage length	[mm]	450
Dynamic load torque (My), maximum	[Nm]	750
Dynamic load torque (Mz), maximum	[Nm]	750
Weight	[kg]	6,4

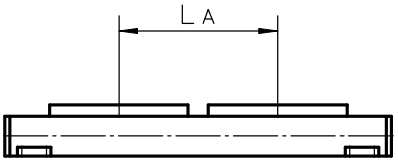


A1: depth 12 mm

Double Carriages

Parameter		WM80D
Minimum distance between carriages (L_A)	[mm]	360
Dynamic load (Fy), maximum	[N]	6000
Dynamic load (Fz), maximum	[N]	6000
Dynamic load torque (My), maximum	[Nm]	L_A[1] × 3
Dynamic load torque (Mz), maximum	[Nm]	L_A[1] × 3
Force required to move second carriage	[N]	25
Total length (L tot)	[mm]	S max + C + L_A

[1] Value in mm



WM80S

Ball Screw Drive, Ball Guide, Singel Ball Nut, Short Carriage

» Ordering key - see page 182
» Accessories - see page 125
» Additional data - see page 171

General Specifications

Parameter	WM80S
Profile size (w × h) [mm]	80 × 80
Type of screw	ball screw with single nut
Carriage sealing system	self-adjusting plastic cover band
Screw supports	included in all units that require screw supports
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WM80S
Stroke length (S max), maximum	[mm]	5000
Linear speed, maximum	[m/s]	2,5
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,02
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	3500
Dynamic load (Fy), maximum	[N]	2100[1] / 37440[2]
Dynamic load (Fz), maximum	[N]	2100[1] / 35830[2]
Dynamic load torque (Mx), maximum	[Nm]	150[1] / 890[2]
Dynamic load torque (My), maximum	[Nm]	180[1] / 580[2]
Dynamic load torque (Mz), maximum	[Nm]	180[1] / 600[2]
Drive shaft force (Frd), maximum	[N]	700
Drive shaft torque (Mta), maximum	[Nm]	55
Ball screw diameter (d0)	[mm]	25
Ball screw lead (p)	[mm]	5, 10, 20, 50
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 7,0 1,1 1,6

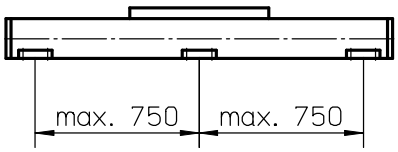
[1] Value for the complete unit
[2] Value for the ball guide only

Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]			
	p = 5	p = 10	p = 20	p = 50
150	0,9	1,1	1,3	2,0
1500	1,3	1,5	1,8	2,4
3000	1,7	1,8	2,0	2,9

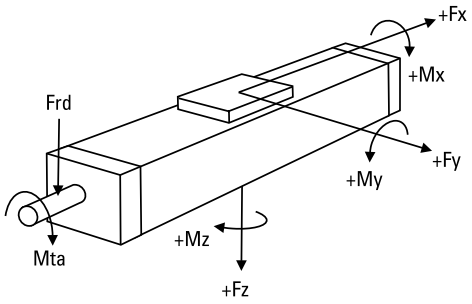
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile



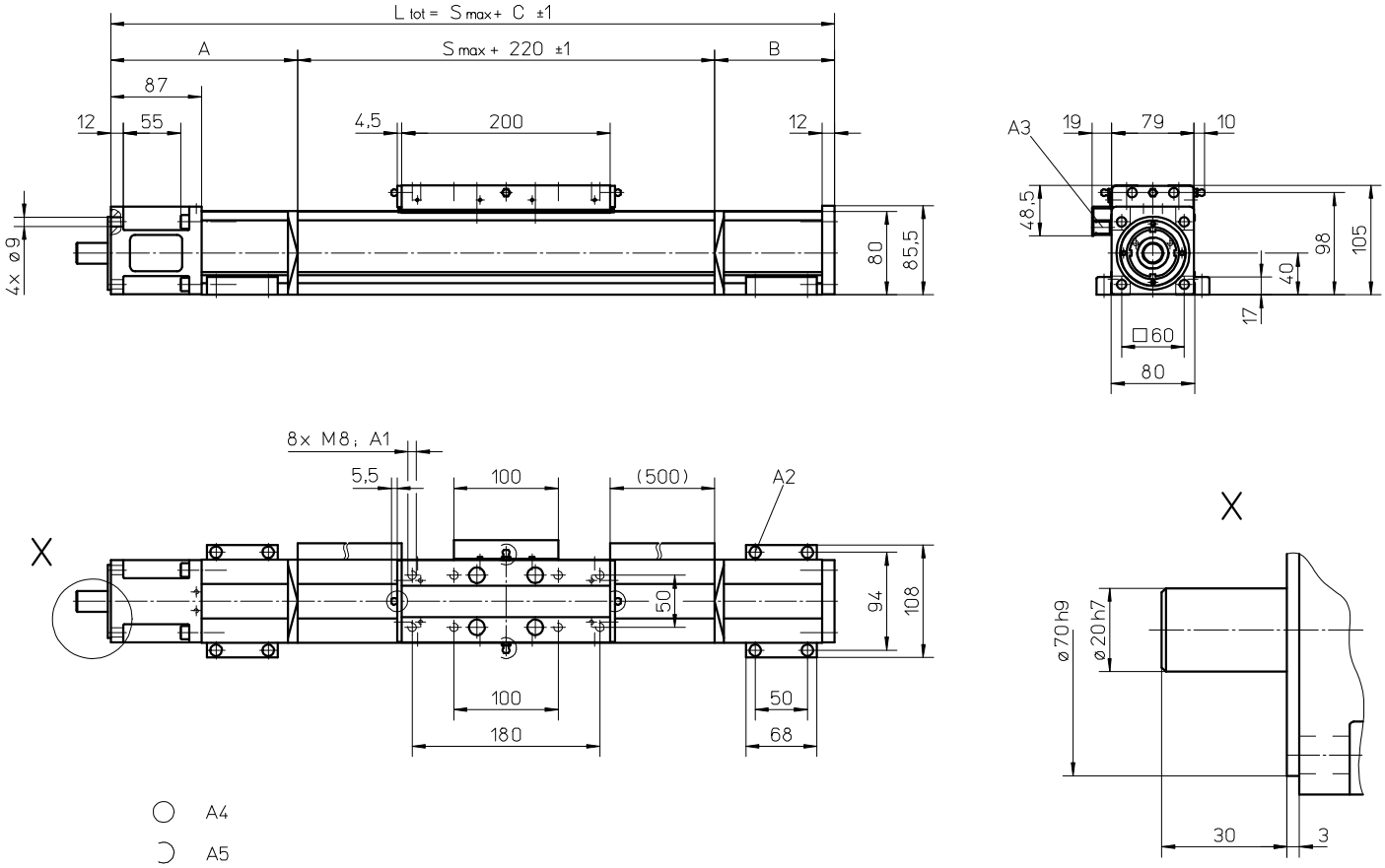
A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Definition of Forces



WM80S

Ball Screw Drive, Ball Guide, Singel Ball Nut, Short Carriage



A1: depth 12 mm
A2: socket cap screw ISO4762-M6×20 8.8
A3: ENF inductive sensor rail option kit (optional)

A4: tapered lubricating nipple to DIN71412 AM6 on fixed-bearing side as standard feature
A5: can be changed over to one of three alternative lubrication points by customer

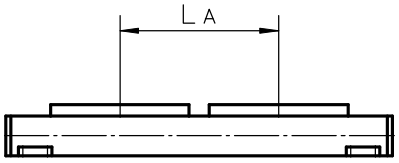
Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
0 - 680	95	35	350
681 - 1310	125	80	425
1311 - 2065	150	105	475
2066 - 2830	170	125	515

Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
2831 - 3590	195	150	565
3591 - 4355	215	170	605
4356 - 5000	235	190	645

Double Carriages

Parameter		WM80S
Minimum distance between carriages (L_A)	[mm]	280
Dynamic load (Fy), maximum	[N]	4200
Dynamic load (Fz), maximum	[N]	4200
Dynamic load torque (My), maximum	[Nm]	L_A[1] × 2,1
Dynamic load torque (Mz), maximum	[Nm]	L_A[1] × 2,1
Force required to move second carriage	[N]	22,5
Total length (L tot)	[mm]	S max + C + L_A

[1] Value in mm



WM120D

Ball Screw Drive, Ball Guide, Double Ball Nuts

» Ordering key - see page 182
» Accessories - see page 125
» Additional data - see page 171

General Specifications

Parameter	WM120D
Profile size (w × h) [mm]	120 × 120
Type of screw	ball screw with double nuts
Carriage sealing system	self-adjusting plastic cover band
Screw supports	included in all units that require screw supports
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WM120D
Stroke length (S max), maximum screw lead 5, 10, 20 mm screw lead 40 mm	[mm]	 11000 5000
Linear speed, maximum	[m/s]	2,0
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,01
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum screw lead 5, 10, 20 mm screw lead 40 mm	[N]	 12000 8000
Dynamic load (Fy), maximum	[N]	6000[1] / 74890[2]
Dynamic load (Fz), maximum	[N]	6000[1] / 71670[2]
Dynamic load torque (Mx), maximum	[Nm]	500[1] / 2890[2]
Dynamic load torque (My), maximum	[Nm]	600[1] / 6660[2]
Dynamic load torque (Mz), maximum	[Nm]	600[1] / 6960[2]
Drive shaft force (Frd), maximum	[N]	1000
Drive shaft torque (Mta), maximum	[Nm]	80
Ball screw diameter (d_0)	[mm]	32
Ball screw lead (p)	[mm]	5, 10, 20, 40
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 25,91 1,93 9,25

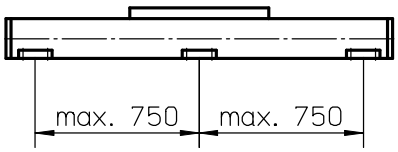
[1] Value for the complete unit
[2] Value for the ball guide only

Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]			
	p = 5	p = 10	p = 20	p = 40
150	1,4	2,0	2,3	2,4
1500	2,5	3,0	3,3	3,8
3000	3,0	3,7	4,0	4,3

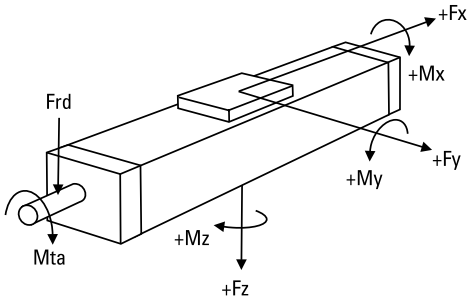
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile



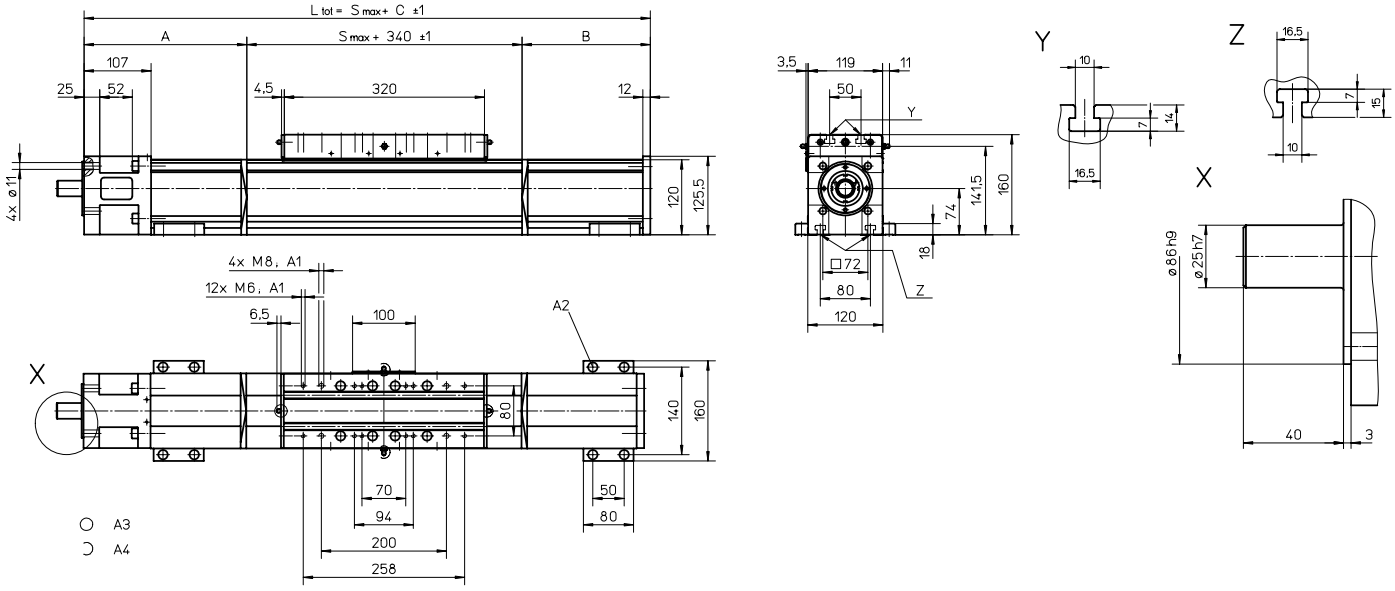
A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information. Units with a profile length over 5400 mm consists of two profiles where the joint between the two profiles must be addequately supported on both sides.

Definition of Forces



WM120D

Ball Screw Drive, Ball Guide, Double Ball Nuts



A1: depth 22
A2: socket cap screw ISO4762-M8×20 8.8

A3: tapered lubricating nipple to DIN71412 M8×1 on fixed-bearing side as standard feature
A4: can be changed over to one of the three alternative lubricating points by the customer

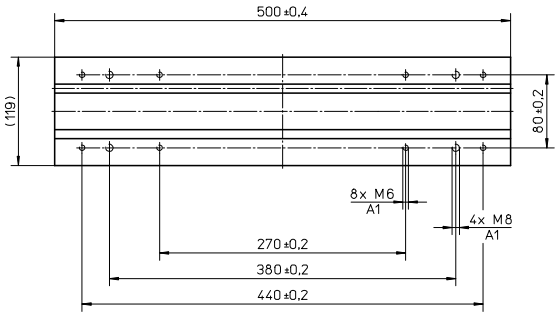
Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
0 - 890 (0 - 710)	155	100	595 (775)
891 - 1695 (711 - 1515)	225	170	735 (815)
1696 - 2625 (1516 - 2445)	260	205	805 (985)
2626 - 3555 (2446 - 3375)	295	240	875 (1055)

Values between brackets = for units with long carriage

Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
3556 - 4485 (3376 - 4305)	330	275	945 (1125)
4486 - 5000 (4306 - 4820)	365	310	1015 (1195)
5001 - 11000 (4307 - 10820)	contact customer service		

Long Carriage

Parameter		WM120D
Carriage length	[mm]	500
Dynamic load torque (My), maximum	[Nm]	1500
Dynamic load torque (Mz), maximum	[Nm]	1500
Weight	[kg]	14,2

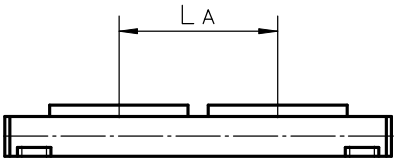


A1: depth 22

Double Carriages

Parameter		WM120D
Minimum distance between carriages (L_A)	[mm]	450
Dynamic load (Fy), maximum	[N]	12000
Dynamic load (Fz), maximum	[N]	12000
Dynamic load torque (My), maximum	[Nm]	L_A[1] × 6
Dynamic load torque (Mz), maximum	[Nm]	L_A[1] × 6
Force required to move second carriage	[N]	30
Total length (L tot)	[mm]	S max + C + L_A

[1] Value in mm



WV60

Ball Screw Drive, No Guides

» Ordering key - see page 183
» Accessories - see page 125
» Additional data - see page 171

General Specifications

Parameter	WV60
Profile size (w × h) [mm]	60 × 60
Type of screw	ball screw with double nut
Carriage sealing system	self-adjusting plastic cover band
Screw supports	included in all units that require screw supports
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

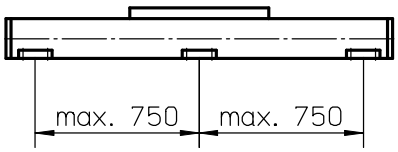
Parameter		WV60
Stroke length (S max), maximum screw lead 5, 20 mm screw lead 50 mm	[mm]	 11000 5000
Linear speed, maximum	[m/s]	2,5
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,01
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	4000
Dynamic load (Fy), maximum	[N]	0
Dynamic load (Fz), maximum	[N]	0
Dynamic load torque (Mx), maximum	[Nm]	0
Dynamic load torque (My), maximum	[Nm]	0
Dynamic load torque (Mz), maximum	[Nm]	0
Drive shaft force (Frd), maximum	[N]	500
Drive shaft torque (Mta), maximum	[Nm]	35
Ball screw diameter (d_0)	[mm]	20
Ball screw lead (p)	[mm]	5, 20, 50
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 4,72 0,55 1,42

Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]		
	p = 5	p = 20	p = 50
150	0,7	0,9	1,1
1500	1,3	1,5	1,5
3000	1,7	1,9	2,1

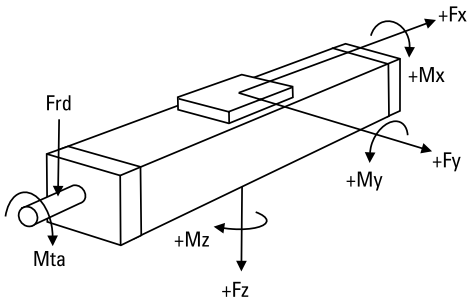
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile



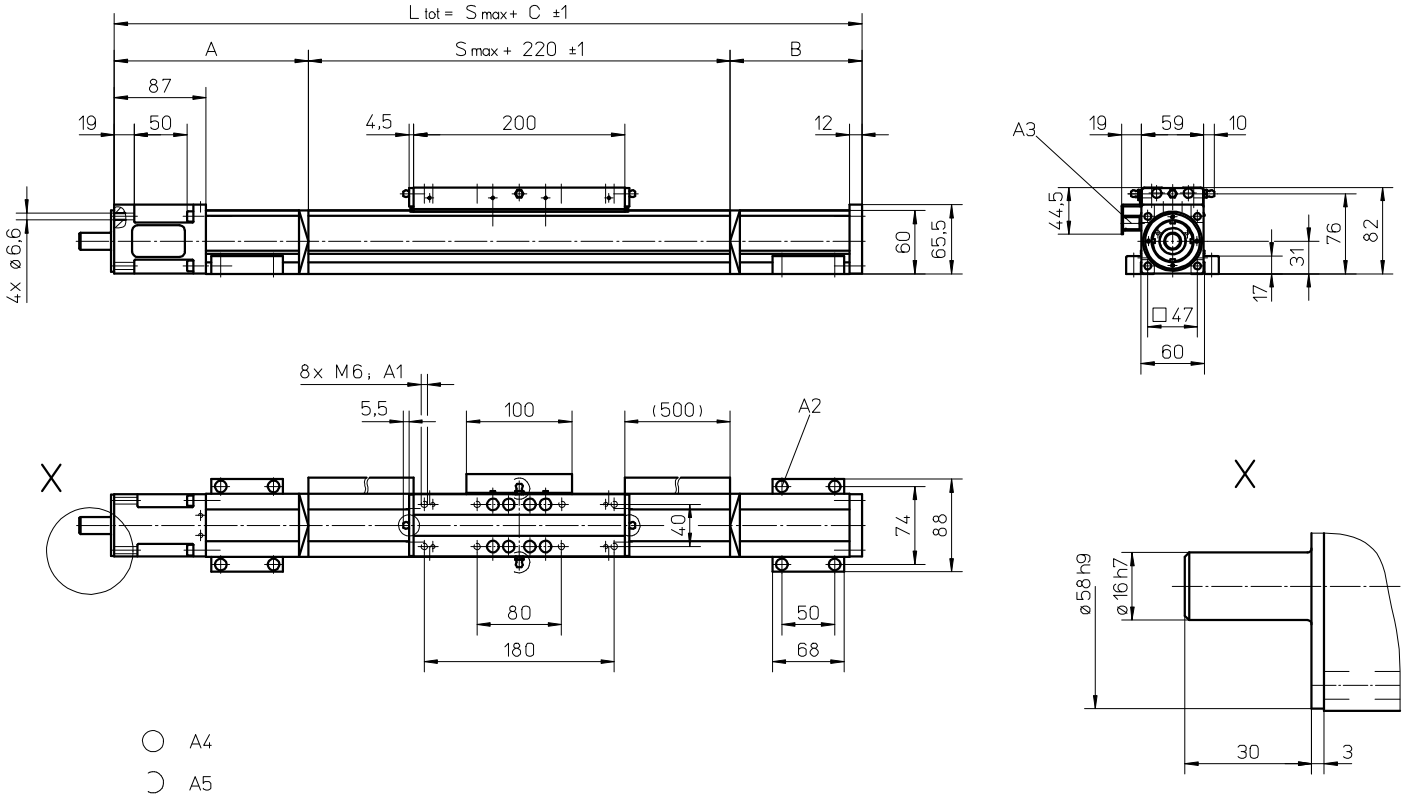
A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information. Units with a profile length over 6300 mm consists of two profiles where the joint between the two profiles must be addequately supported on both sides.

Definition of Forces



WV60

Ball Screw Drive, No Guides



A1: depth 11
A2: socket cap screw ISO4762-M6×20 8.8
A3: ENF inductive sensor rail option kit (optional)
A4: tapered lubricating nipple to DIN71412 AM6 on fixed-bearing side as standard feature
A5: can be changed over to one of the three alternative lubricating points by the customer

Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
0 - 690	130	80	430
691 - 1415	155	105	480
1416 - 2155	175	125	520
2156 - 2885	200	150	570

Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
2886 - 3625	220	170	610
3626 - 4355	245	195	660
4256 - 5095	265	215	700
5096 - 11000	contact customer service		

WV80

Ball Screw Drive, No Guides

» Ordering key - see page 183
» Accessories - see page 125
» Additional data - see page 171

General Specifications

Parameter	WV80
Profile size (w × h) [mm]	80 × 80
Type of screw	ball screw with double nuts
Carriage sealing system	self-adjusting plastic cover band
Screw supports	included in all units that require screw supports
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

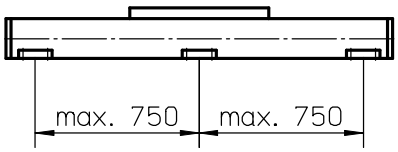
Parameter		WV80
Stroke length (S max), maximum screw lead 5, 10, 20 mm screw lead 50 mm	[mm]	 11000 5000
Linear speed, maximum	[m/s]	2,5
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,01
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	5000
Dynamic load (Fy), maximum	[N]	0
Dynamic load (Fz), maximum	[N]	0
Dynamic load torque (Mx), maximum	[Nm]	0
Dynamic load torque (My), maximum	[Nm]	0
Dynamic load torque (Mz), maximum	[Nm]	0
Drive shaft force (Frd), maximum	[N]	700
Drive shaft torque (Mta), maximum	[Nm]	55
Ball screw diameter (d0)	[mm]	25
Ball screw lead (p)	[mm]	5, 10, 20, 50
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 7,95 0,99 2,25

Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]			
	p = 5	p = 10	p = 20	p = 50
150	0,9	1,1	1,3	1,4
1500	1,6	1,9	2,1	2,3
3000	2,0	2,4	2,6	3,0

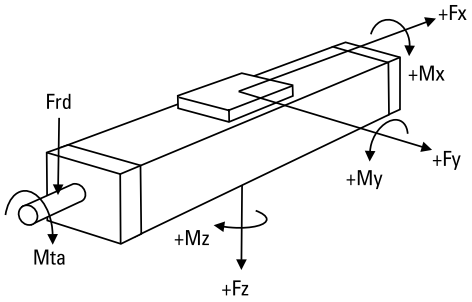
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile



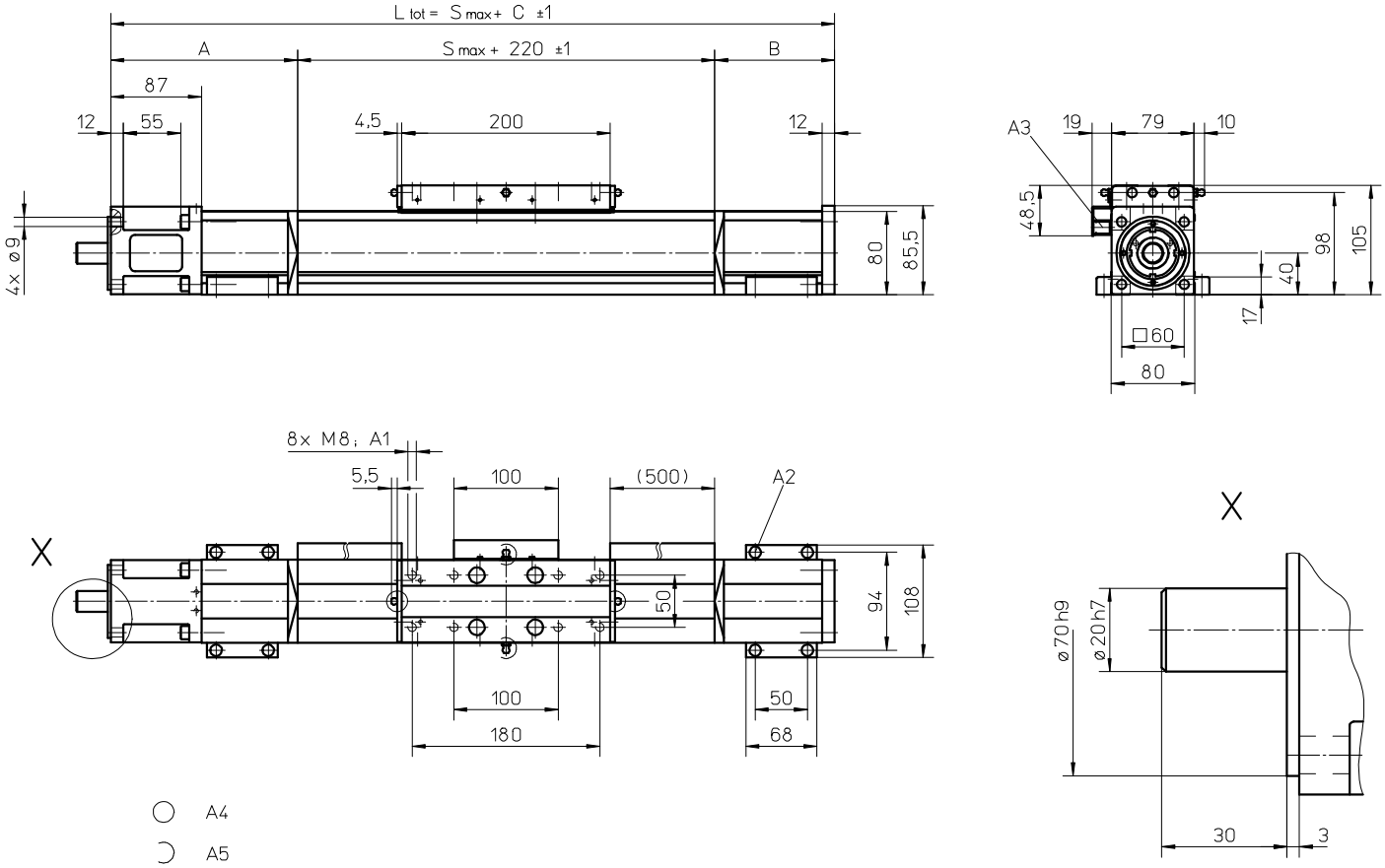
A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information. Units with a profile length over 6300 mm consists of two profiles where the joint between the two profiles must be addequately supported on both sides.

Definition of Forces



WV80

Ball Screw Drive, No Guides



A1: depth 12 mm
A2: socket cap screw ISO4762-M6×20 8.8
A3: ENF inductive sensor rail option kit (optional)

A4: tapered lubricating nipple to DIN71412 AM6 on fixed-bearing side as standard feature
A5: can be changed over to one of three alternative lubrication points by customer

Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
0 - 775	125	50	395
776 - 1670	145	95	460
1671 - 2505	170	115	505
2506 - 3340	190	140	550

Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
3341 - 4175	210	160	590
4176 - 5015	235	180	635
5016 - 11000	contact customer service		

WV120

Ball Screw Drive, No Guides

» Ordering key - see page 183
» Accessories - see page 125
» Additional data - see page 171

General Specifications

Parameter	WV120
Profile size (w × h) [mm]	120 × 120
Type of screw	ball screw with double nuts
Carriage sealing system	self-adjusting plastic cover band
Screw supports	included in all units that require screw supports
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

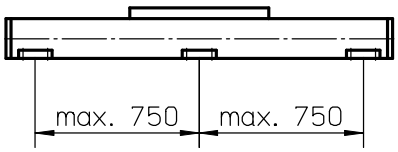
Parameter		WV120
Stroke length (S max), maximum screw lead 5, 10, 20 mm screw lead 40 mm	[mm]	 11000 5000
Linear speed, maximum	[m/s]	2,0
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,01
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum screw lead 5, 10, 20 mm screw lead 40 mm	[N]	 12000 8000
Dynamic load (Fy), maximum	[N]	0
Dynamic load (Fz), maximum	[N]	0
Dynamic load torque (Mx), maximum	[Nm]	0
Dynamic load torque (My), maximum	[Nm]	0
Dynamic load torque (Mz), maximum	[Nm]	0
Drive shaft force (Frd), maximum	[N]	1000
Drive shaft torque (Mta), maximum	[Nm]	80
Ball screw diameter (d0)	[mm]	32
Ball screw lead (p)	[mm]	5, 10, 20, 40
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 18,10 1,94 4,75

Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]			
	p = 5	p = 10	p = 20	p = 40
150	1,0	1,1	1,4	1,5
1500	2,1	2,2	2,5	2,8
3000	2,4	2,6	3,0	3,5

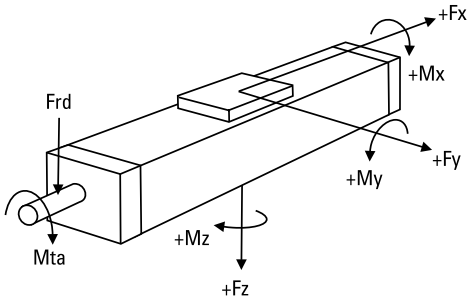
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile



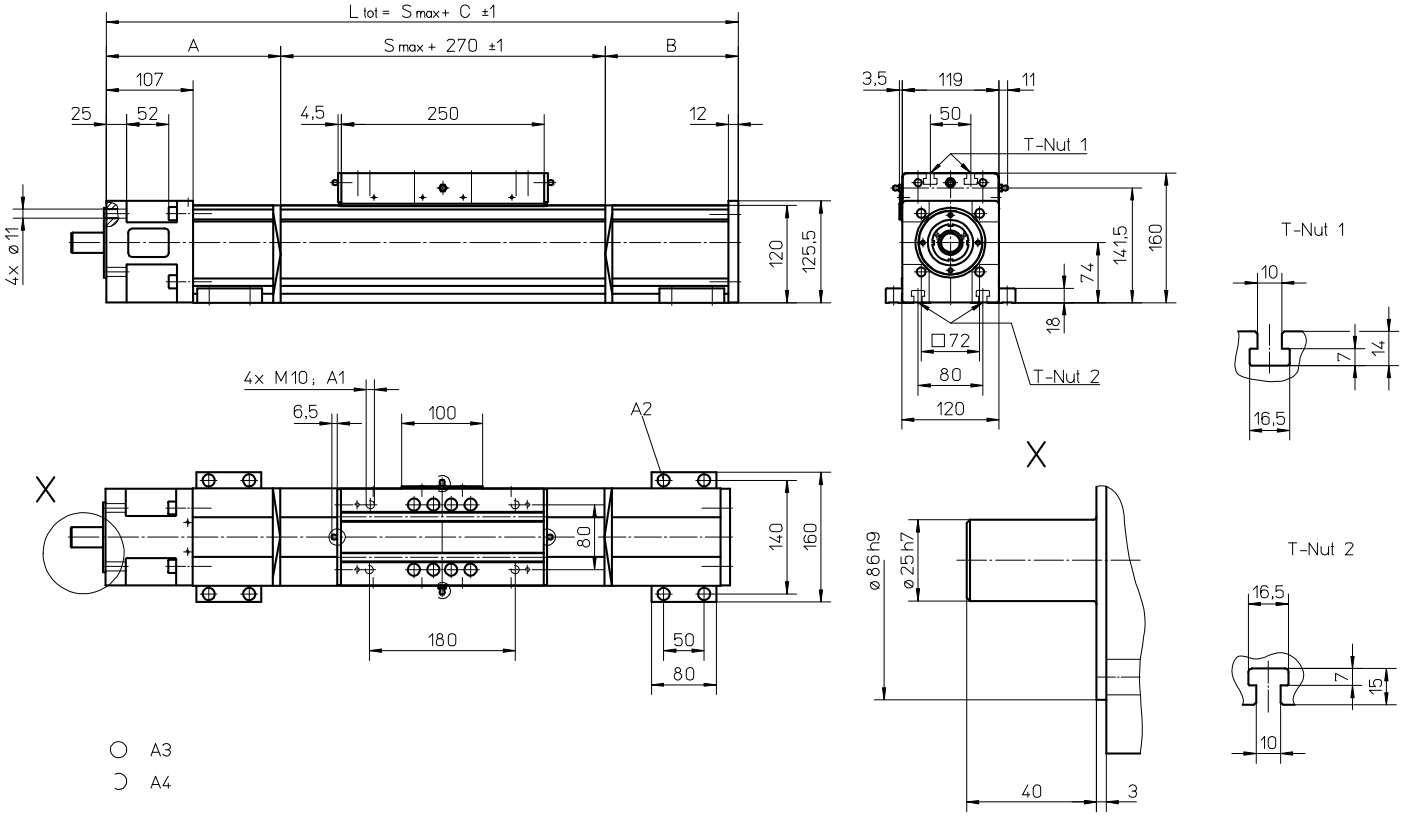
A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information. Units with a profile length over 5400 mm consists of two profiles where the joint between the two profiles must be addequately supported on both sides.

Definition of Forces



WV120

Ball Screw Drive, No Guides



A1: depth 22
A2: socket cap screw ISO4762-M8×20 8.8

A3: tapered lubricating nipple to DIN71412 M8×1 on fixed-bearing side as standard feature
A4: can be changed over to one of the three alternative lubricating points by the customer

Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
0 - 940	145	50	465
941 - 1860	180	120	570
1861 - 2790	215	155	640
2791 - 3720	250	190	710

Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
3721 - 4650	285	225	780
4651 - 5000	320	255	845
5001 - 11000	contact customer service		

MLSM60D

Ball Screw Drive, Ball Guide

» Ordering key - see page 184
» Accessories - see page 125
» Additional data - see page 171

General Specifications

Parameter	MLSM60D
Profile size (w × h) [mm]	160 × 65
Type of screw	ball screw with double nuts
Carriage sealing system	plastic cover band
Screw supports	included in all units that require screw supports
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		MLSM60D
Stroke length (S max), maximum	[mm]	5500
Linear speed, maximum	[m/s]	2,5
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,01
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	5000
Dynamic load (Fy), maximum	[N]	6000[1] / 55090[2]
Dynamic load (Fz), maximum	[N]	6000[1] / 55090[2]
Dynamic load torque (Mx), maximum	[Nm]	400[1] / 2890[2]
Dynamic load torque (My), maximum	[Nm]	460[1] / 4490[2]
Dynamic load torque (Mz), maximum	[Nm]	460[1] / 4490[2]
Drive shaft force (Frd), maximum	[N]	350
Drive shaft torque (Mta), maximum	[Nm]	60
Ball screw diameter (d0)	[mm]	25
Ball screw lead (p)	[mm]	5, 10, 20, 50
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 14,40 1,65 5,70

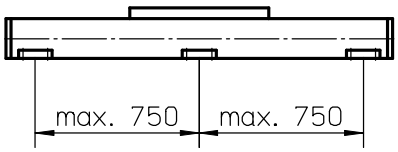
[1] Value for the complete unit
[2] Value for the ball guide only

Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]			
	p = 5	p = 10	p = 20	p = 50
150	1,0	1,6	1,9	2,7
1500	1,6	2,2	2,3	3,4
3000	2,0	2,6	2,6	4,0

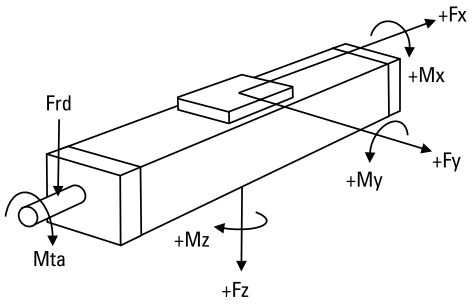
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile



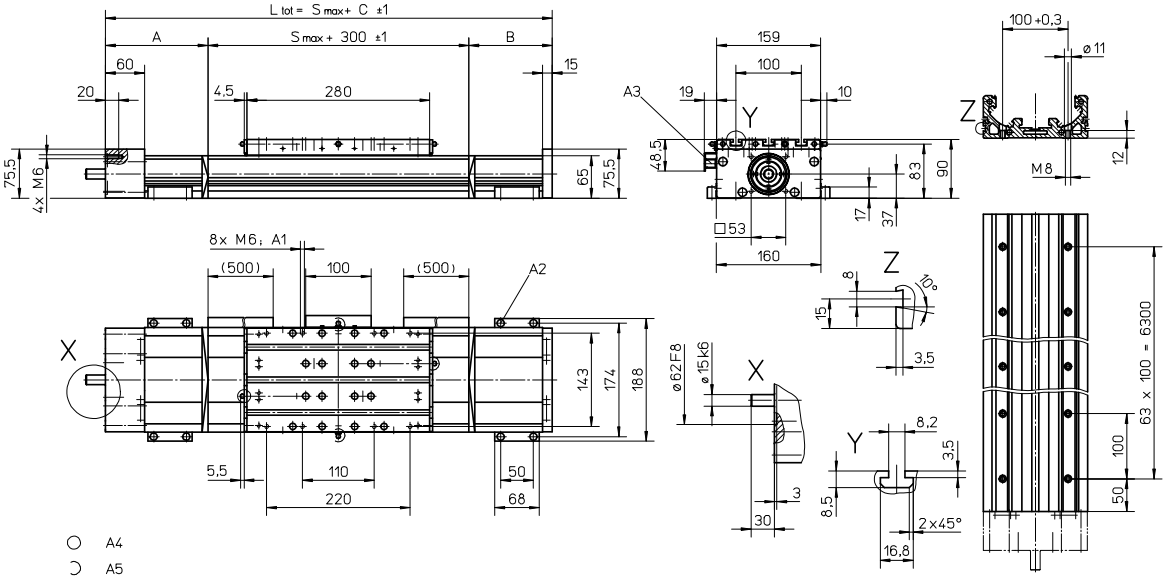
A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Definition of Forces



MLSM60D

Ball Screw Drive, Ball Guide



A1: depth 10
A2: socket cap screw ISO4762-M6×20 8.8
A3: ENF inductive sensor rail option kit (optional)

A4: tapered lubricating nipple to DIN71412 AM6 on fixed-bearing side as standard feature
A5: can be changed over to one of the three alternative lubricating points by the customer

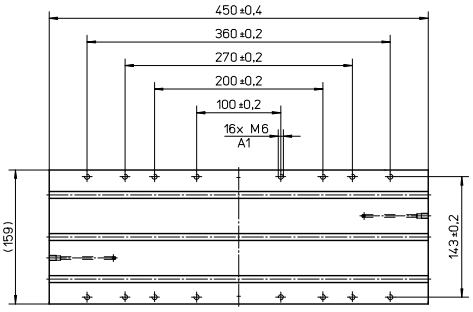
Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
0 - 750 (0 - 580)	90	45	435 (605)
751 - 1220 (581 - 1050)	105	90	495 (665)
1221 - 1980 (1051 - 1810)	125	110	535 (705)
1981 - 2730 (1811 - 2560)	150	135	585 (765)

Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
2731 - 3490 (2561 - 3320)	170	155	625 (795)
3491 - 4240 (3321 - 4070)	195	180	675 (845)
4241 - 5000 (4071 - 4830)	215	200	715 (885)
5001 - 5500 (4831 - 5330)	235	220	755 (925)

Values between brackets = for units with long carriage

Long Carriage

Parameter		MLSM60D
Carriage length	[mm]	450
Dynamic load torque (My), maximum	[Nm]	940
Dynamic load torque (Mz), maximum	[Nm]	940
Weight	[kg]	6,5

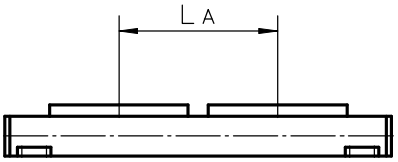


A1: depth 10

Double Carriages

Parameter		MLSM60D
Minimum distance between carriages (L_A)	[mm]	320
Dynamic load (Fy), maximum	[N]	12000
Dynamic load (Fz), maximum	[N]	12000
Dynamic load torque (My), maximum	[Nm]	L_A[1] × 6
Dynamic load torque (Mz), maximum	[Nm]	L_A[1] × 6
Force required to move second carriage	[N]	27
Total length (L tot)	[mm]	S max + C + L_A

[1] Value in mm



MLSM80D

Ball Screw Drive, Ball Guide

» Ordering key - see page 184
» Accessories - see page 125
» Additional data - see page 171

General Specifications

Parameter	MLSM80D
Profile size (w × h) [mm]	240 × 85
Type of screw	ball screw with double nuts
Carriage sealing system	plastic cover band
Screw supports	included in all units that require screw supports
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		MLSM80D
Stroke length (S max), maximum	[mm]	5200
Linear speed, maximum	[m/s]	2,0
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,01
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum screw lead 5, 10, 20 mm screw lead 40 mm	[N]	 12000 8000
Dynamic load (Fy), maximum	[N]	8000[1] / 71860[2]
Dynamic load (Fz), maximum	[N]	8000[1] / 71860[2]
Dynamic load torque (Mx), maximum	[Nm]	780[1] / 5890[2]
Dynamic load torque (My), maximum	[Nm]	900[1] / 6640[2]
Dynamic load torque (Mz), maximum	[Nm]	900[1] / 6640[2]
Drive shaft force (Frd), maximum	[N]	700
Drive shaft torque (Mta), maximum	[Nm]	85
Ball screw diameter (d0)	[mm]	32
Ball screw lead (p)	[mm]	5, 10, 20, 40
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 29,5 2,7 11,5

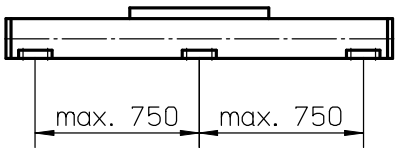
[1] Value for the complete unit
[2] Value for the ball guide only

Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]			
	p = 5	p = 10	p = 20	p = 40
150	1,6	2,2	2,5	2,8
1500	2,7	3,2	3,4	4,0
3000	3,2	4,0	4,2	4,5

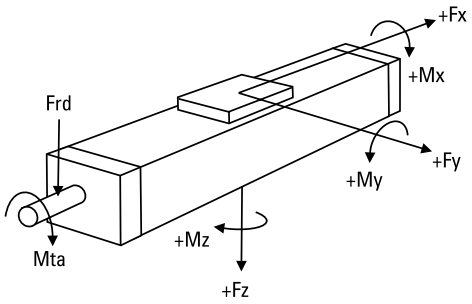
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile



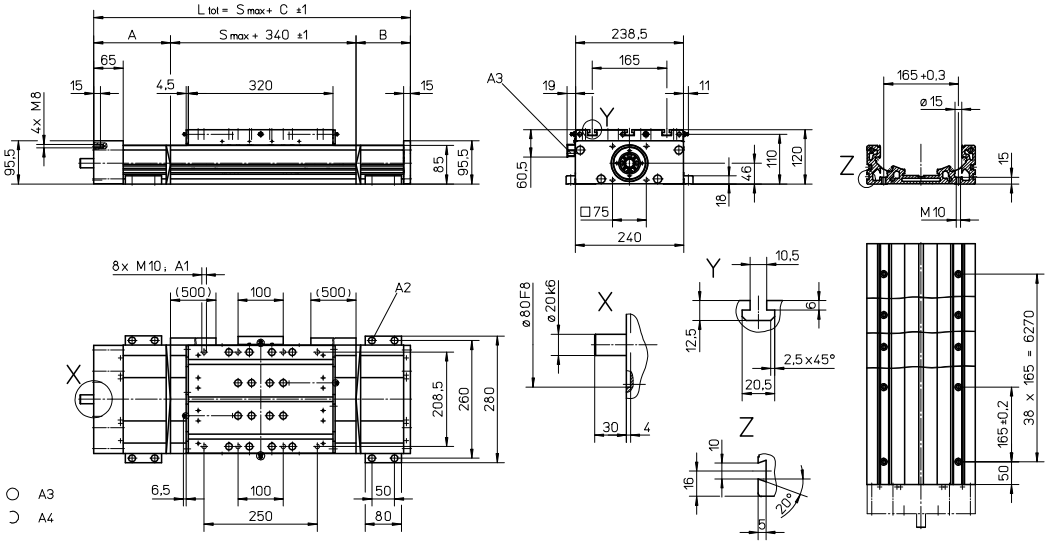
A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Definition of Forces



MLSM80D

Ball Screw Drive, Ball Guide



A1: depth 15
A2: socket cap screw ISO4762-M8×20 8.8
A3: ENF inductive sensor rail option kit (optional)

A4: tapered lubricating nipple to DIN71412 M8×1 on fixed-bearing side as standard feature
A5: can be changed over to one of the three alternative lubricating points by the customer

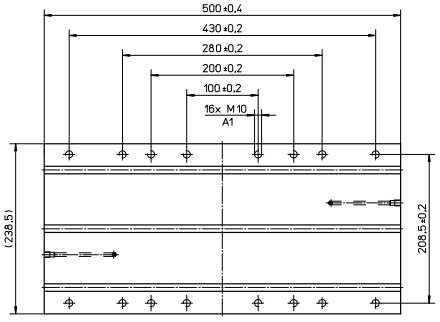
Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
0 - 750 (0 - 570)	100	90	530 (710)
751 - 1140 (571 - 960)	130	120	590 (770)
1141 - 1880 (961 - 1700)	160	150	650 (830)
1881 - 2620 (1701 - 2440)	190	180	710 (890)

Stroke length (S max) [mm]	A [mm]	B [mm]	C [mm]
2621 - 3360 (2441 - 3180)	220	210	770 (950)
3361 - 4100 (3181 - 3920)	250	240	830 (1010)
4101 - 4840 (3921 - 4660)	280	270	890 (1070)
4841 - 5000 (4661 - 4820)	310	300	950 (1130)

Values between brackets = for units with long carriage

Long Carriage

Parameter		MLSM80D
Carriage length	[mm]	500
Dynamic load torque (My), maximum	[Nm]	1750
Dynamic load torque (Mz), maximum	[Nm]	1750
Weight	[kg]	16

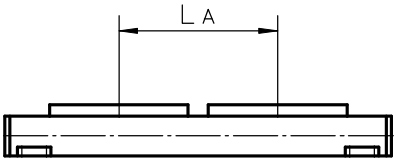


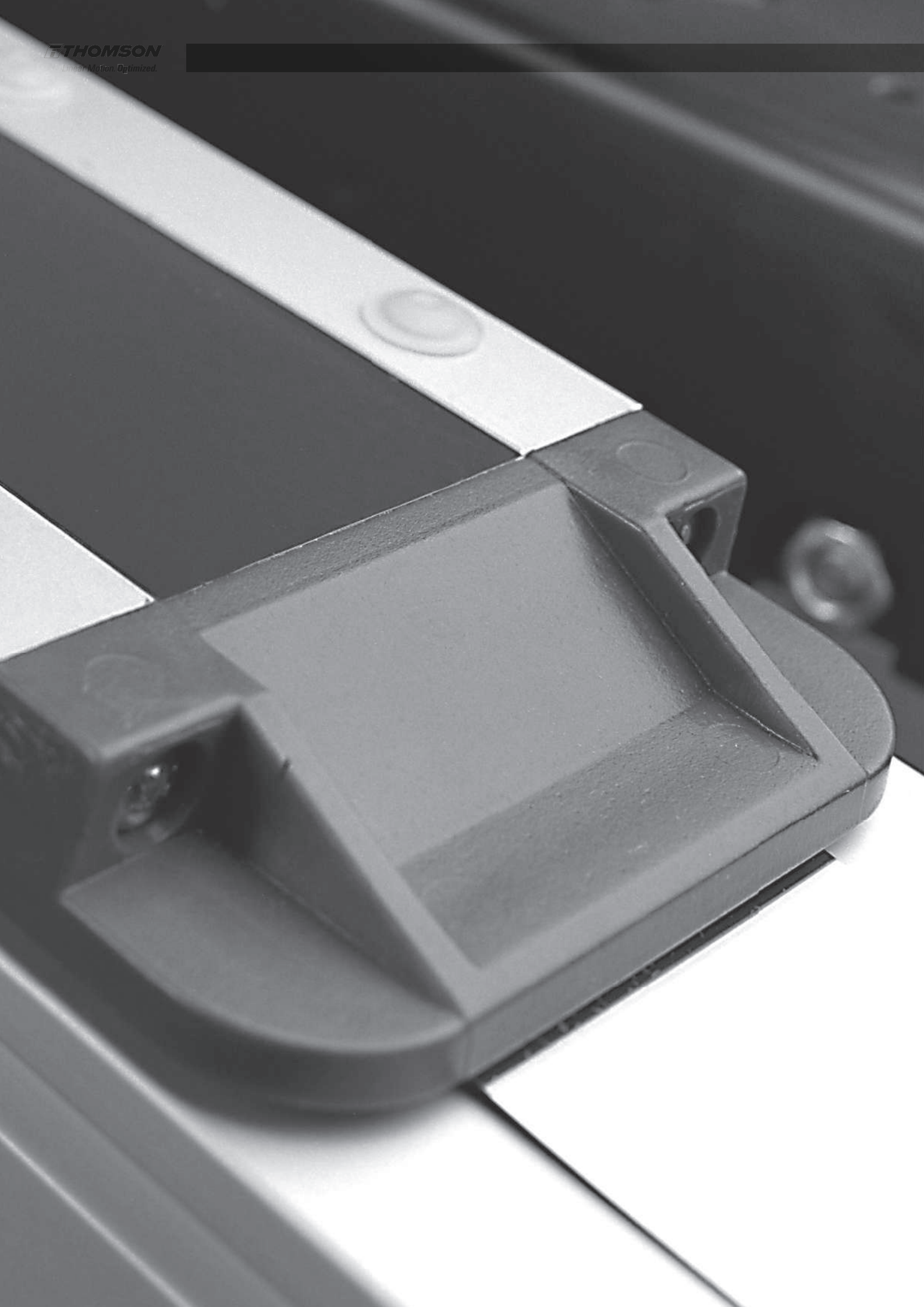
A1: depth 15

Double Carriages

Parameter		MLSM80D
Minimum distance between carriages (L_A)	[mm]	400
Dynamic load (Fy), maximum	[N]	16000
Dynamic load (Fz), maximum	[N]	16000
Dynamic load torque (My), maximum	[Nm]	$L_{A^1} \times 8$
Dynamic load torque (Mz), maximum	[Nm]	$L_{A^1} \times 8$
Force required to move second carriage	[N]	35
Total length (L tot)	[mm]	S max + C + L_A

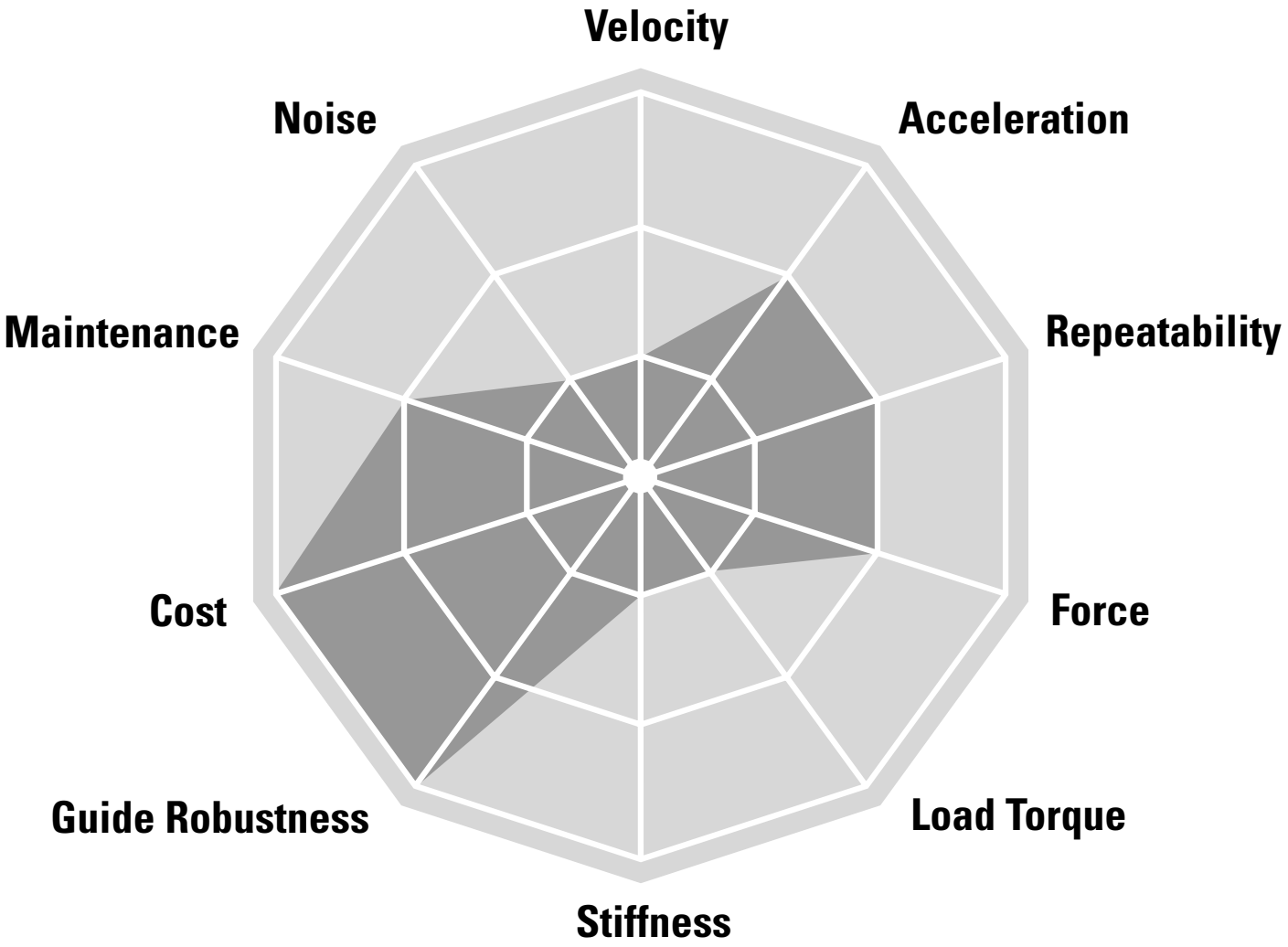
[1] Value in mm





Linear Motion Systems with Ball Screw Drive and Slide Guide

BaseLine, Movopart



Typical Applications

Typical applications are where low to medium loads needs to be moved at low to medium speed. These units are also suited for harsh environments. Typical examples are all types of machines in the food, chemical, paper and wood working industry. Materials handling is another area where these units are ideal.

Linear Motion Systems with Ball Screw Drive and Slide Guide

Overview

BaseLine WB

WB40

Features

- Can be installed in all directions
- Plastic cover band
- Robust external slide guides
- Ball screw or lead screw drive

Parameter		WB40	WB60
Profile size (width × height)	[mm]	40 × 37	60 × 59
Stroke length (S max), maximum	[mm]	1000	5200
Linear speed, maximum	[m/s]	0,25	1,0
Dynamic carriage load (Fz), maximum	[N]	250	650
Remarks		ball screw or lead screw drive	ball screw or lead screw drive
Page		42	44

Movopart M

M75

Features

- Can be installed in all directions
- Self-adjusting stainless steel cover band
- Patented internal self-adjusting prism slide guides
- Wash down protected versions available

Parameter		M55	M75	M100
Profile size (width × height)	[mm]	58 × 55	86 × 75	108 × 100
Stroke length (S max), maximum	[mm]	3000	4000	6000
Linear speed, maximum	[m/s]	1,0	1,6	1,6
Dynamic carriage load (Fz), maximum	[N]	400	1485	3005
Remarks		single ball nut or composite nut	single ball nut or composite nut	single ball nut or composite nut
Page		46	48	50

Linear Motion Systems with Ball Screw Drive and Slide Guide

Overview

Movopart MD

M100D

Features

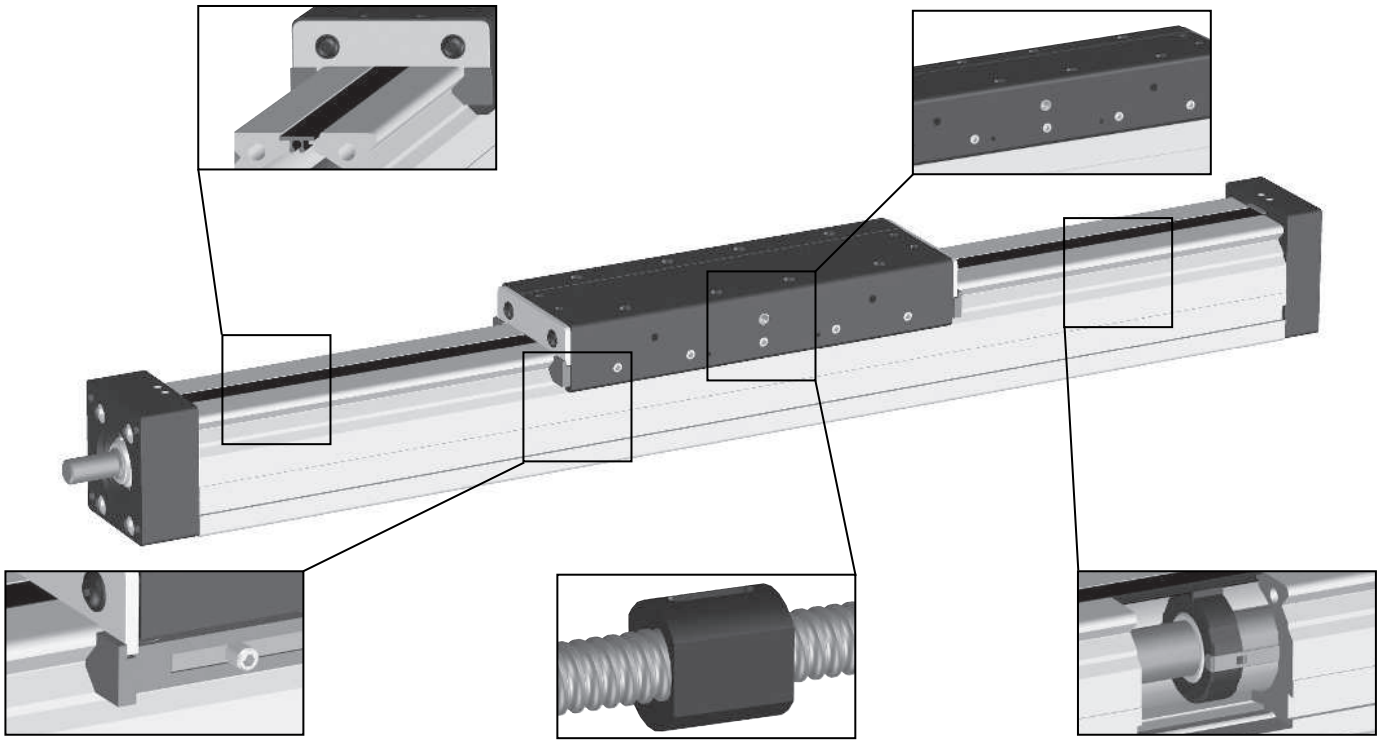
- Can be installed in all directions
- Self-adjusting stainless steel cover band
- Patented intenal self-adjusting prism slide guides
- Wash down protected versions available

Parameter		M75D	M100D
Profile size (width × height)	[mm]	86 × 75	108 × 100
Stroke length (S max), maximum	[mm]	3550	6000
Linear speed, maximum	[m/s]	1,6	1,6
Dynamic carriage load (Fz), maximum	[N]	1485	3005
Remarks		pre-loaded ball nut	pre-loaded ball nut
Page		52	54

WB-Series Technical Presentation

Cover band
The durable plastic cover band protect the interior of the unit from the penetration of dirt, dust and liquids.

Central lubrication
One central lubrication point on the carriage services the entire unit resulting in a minimum maintenace required.



Slide guides
The robust and accurate slide guides can be easily replaced by the user whenever needed.

Drive
Select between the fast high precision ball screw or the robust lead screw with composite nut.

Screw support
The screw support system reduce noise and vibrations and permits high speed at long stroke lengths.

WB40

Ball Screw or Lead Screw Drive, Slide Guide

» Ordering key - see page 185
» Accessories - see page 125
» Additional data - see page 172

General Specifications

Parameter	WB40
Profile size (w × h) [mm]	40 × 37
Type of screw	ball or lead screw with single nut
Carriage sealing system	plastic cover band
Screw supports	none
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WB40
Stroke length (S max), maximum	[mm]	1000
Linear speed, maximum	[m/s]	0,25
Acceleration, maximum	[m/s²]	5
Repeatability	[± mm]	0,05
Input speed, maximum Ball screw units Lead screw units with composite nut	[rpm]	 3000 1500
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum ball screw units / lead screw units	[N]	 200 / 500
Dynamic load (Fy), maximum	[N]	200[1]
Dynamic load (Fz), maximum	[N]	250[1]
Dynamic load torque (Mx), maximum	[Nm]	6[1]
Dynamic load torque (My), maximum	[Nm]	15[1]
Dynamic load torque (Mz), maximum	[Nm]	10[1]
Drive shaft force (Frd), maximum	[N]	80
Drive shaft torque (Mta), maximum	[Nm]	1
Screw diameter (d0)	[mm]	12
Screw lead (p) ball screw units / lead screw units	[mm]	 5 / 4, 8
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 1,07 0,30 0,45

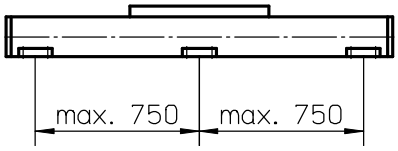
[1] Value for the complete unit

Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]		
	p = 4	p = 5	p = 8
150	-	0,02	-
1500	-	0,35	-
3000	-	0,50	-

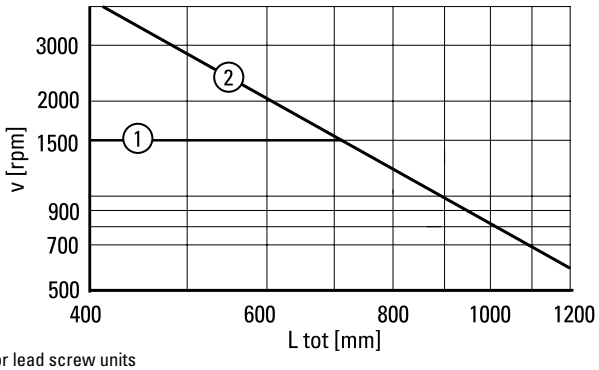
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile



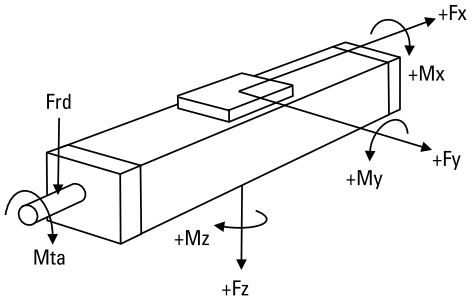
A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Critical Speed



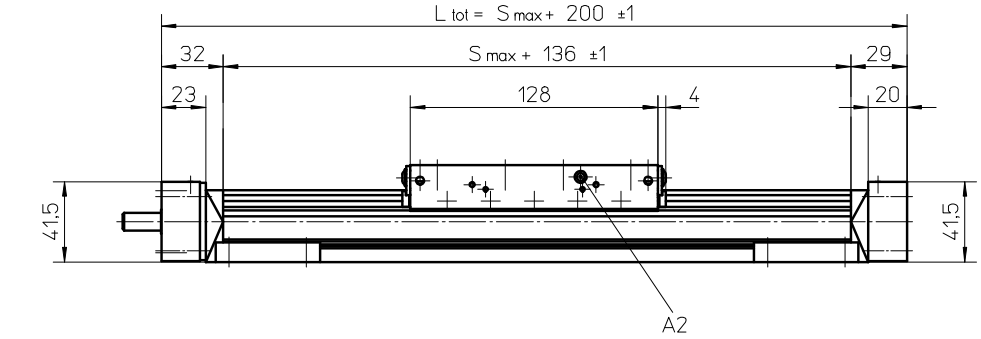
1: For lead screw units
2: For ball screw units

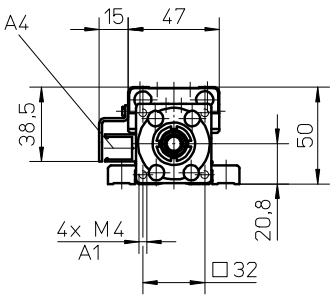
Definition of Forces

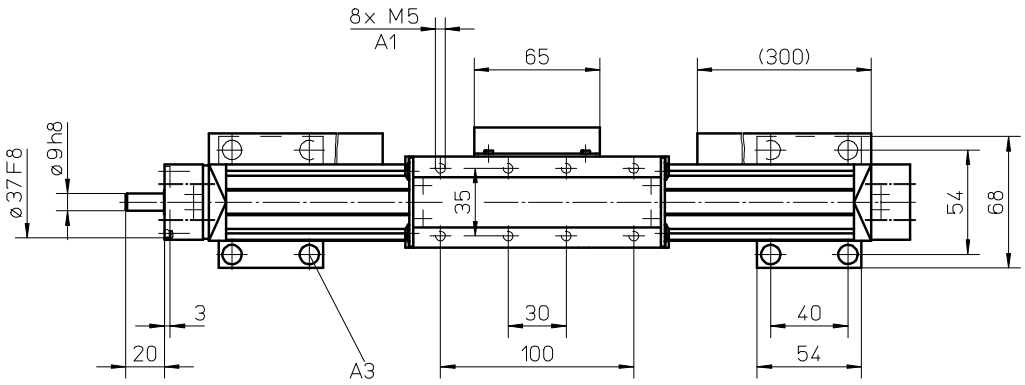


WB40

Ball Screw or Lead Screw Drive, Slide Guide







A1: depth 10
A2: lubricating nipple DIN3405 D 1/A
A3: socket cap screw ISO4762-M5×20 8.8
A4: ENF inductive sensor rail option kit (optional)

WB60

Ball Screw or Lead Screw Drive, Slide Guide

» Ordering key - see page 185
» Accessories - see page 125
» Additional data - see page 172

General Specifications

Parameter	WB60
Profile size (w × h) [mm]	60 × 59
Type of screw	ball or lead screw with single nut
Carriage sealing system	plastic cover band
Screw supports	number of screw supports to be specified by customer at order
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WB60
Stroke length (S max), maximum	[mm]	5200
Linear speed, maximum	[m/s]	1,0
Acceleration, maximum	[m/s²]	5
Repeatability	[± mm]	0,05
Input speed, maximum Ball screw units Lead screw units with composite nut	[rpm]	 3000 1500
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum ball screw units / lead screw units	[N]	 2500 / 2500
Dynamic load (Fy), maximum	[N]	500[1]
Dynamic load (Fz), maximum	[N]	650[1]
Dynamic load torque (Mx), maximum	[Nm]	30[1]
Dynamic load torque (My), maximum	[Nm]	70[1]
Dynamic load torque (Mz), maximum	[Nm]	50[1]
Drive shaft force (Frd), maximum	[N]	150
Drive shaft torque (Mta), maximum	[Nm]	17
Screw diameter (d0)	[mm]	20
Screw lead (p) ball screw units / lead screw units	[mm]	 5, 20 / 8
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 3,63 0,72 1,17

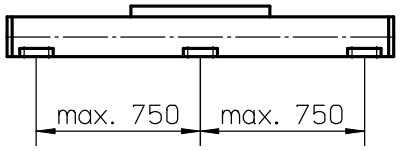
[1] Value for the complete unit

Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]		
	p = 5	p = 8	p = 20
150	0,5	-	0,7
1500	1,0	-	1,35
3000	1,5	-	1,8

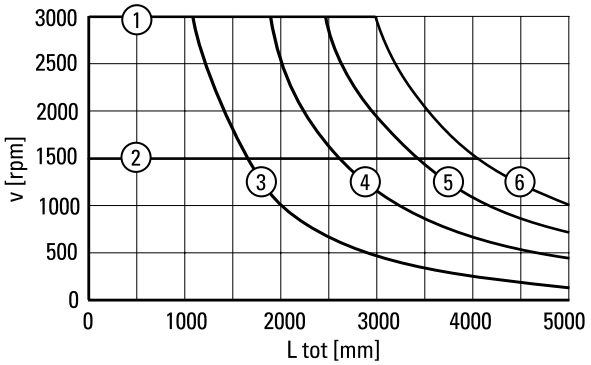
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile



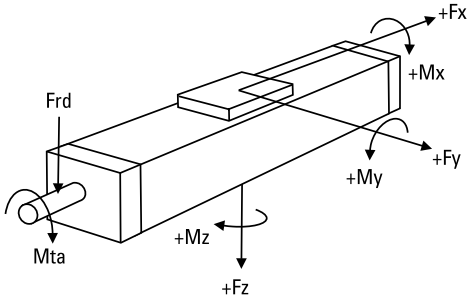
A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Critical Speed



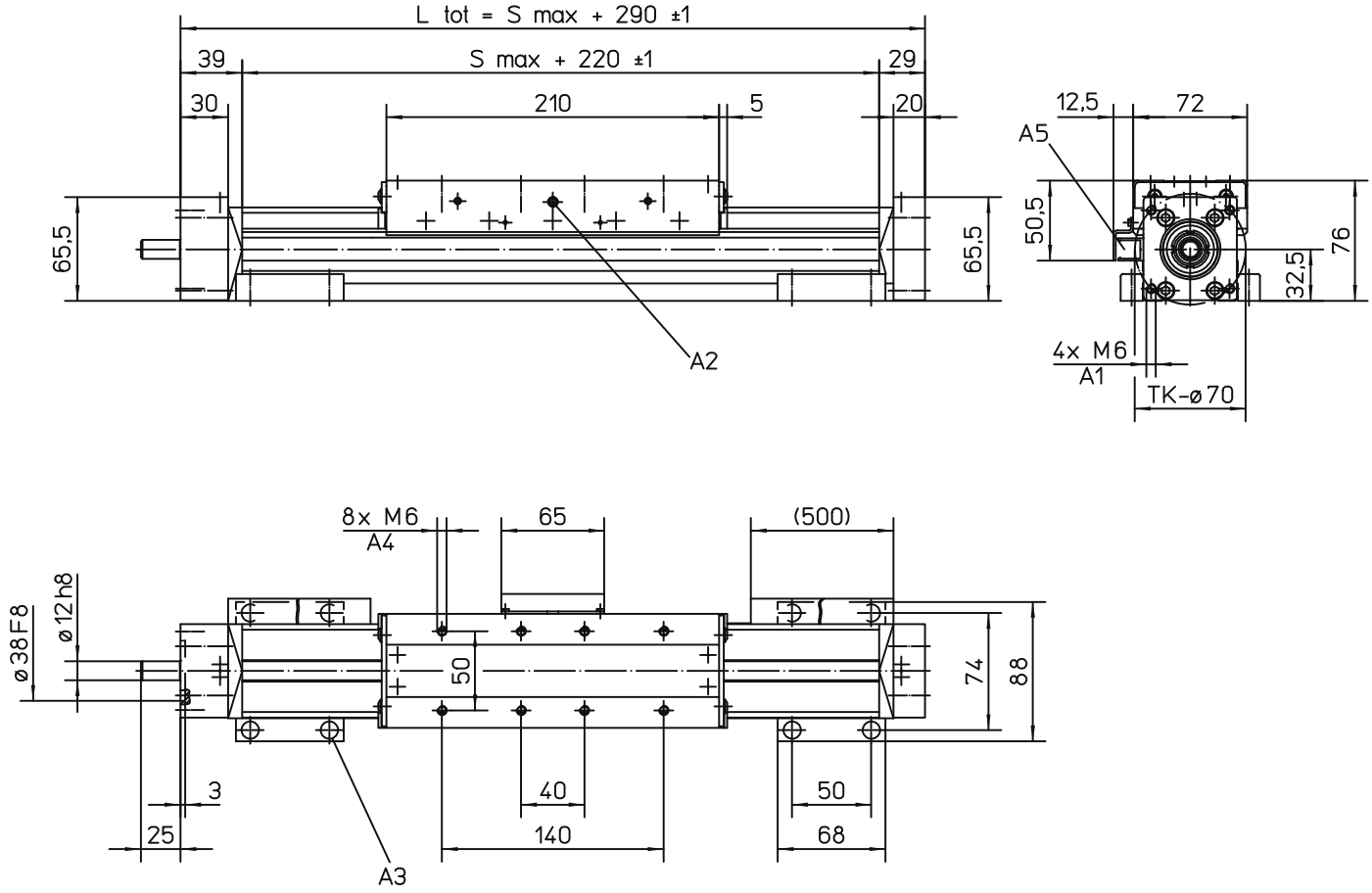
1: Max. input speed for ball screw units
2: Max. input speed for lead screw units
3: No screw supports required
4: One pair of screw supports required
5: Two pairs of screw supports required
6: Three pairs of screw supports required

Definition of Forces



WB60

Ball Screw or Lead Screw Drive, Slide Guide



A1: depth 12
A2: lubricating nipple DIN3405 D 1/A
A3: socket cap screw ISO4762-M6×20 8.8
A4: depth 10
A5: ENF inductive sensor rail option kit (optional)

M55

Ball Screw Drive, Slide Guide

» Ordering key - see page 186
» Accessories - see page 125
» Additional data - see page 172

General Specifications

Parameter	M55
Profile size (w × h) [mm]	58 × 55
Type of screw	ball screw with single nut
Carriage sealing system	self-adjusting steel cover band
Screw supports	number of screw supports to be specified by customer at order
Lubrication	lubrication of ball screw
Included accessories	none

Performance Specifications

Parameter		M55
Stroke length (S max), maximum	[mm]	3000
Linear speed, maximum	[m/s]	1,0
Acceleration, maximum	[m/s²]	8
Repeatability	[± mm]	0,05
Input speed, maximum ball nut units / composite nut units	[rpm]	 3000 / 1500
Operation temperature limits	[°C]	-20 – 70
Dynamic load (Fx), maximum ball nut units / composite nut units	[N]	 1000 / 500
Dynamic load (Fy), maximum	[N]	400[1]
Dynamic load (Fz), maximum	[N]	400[1]
Dynamic load torque (Mx), maximum	[Nm]	9[1]
Dynamic load torque (My), maximum	[Nm]	23[1]
Dynamic load torque (Mz), maximum	[Nm]	23[1]
Drive shaft force (Frd), maximum	[N]	200
Drive shaft torque (Mta), maximum	[Nm]	12
Screw diameter (d0)	[mm]	16
Screw lead (p) ball nut units / composite nut units	[mm]	 5, 5,08, 10, 20 / 32
Weight of unit with zero stroke of every 100 mm of stroke of carriage of option single screw support of option double screw supports	[kg]	 3,06 0,44 1,20 0,83 1,88

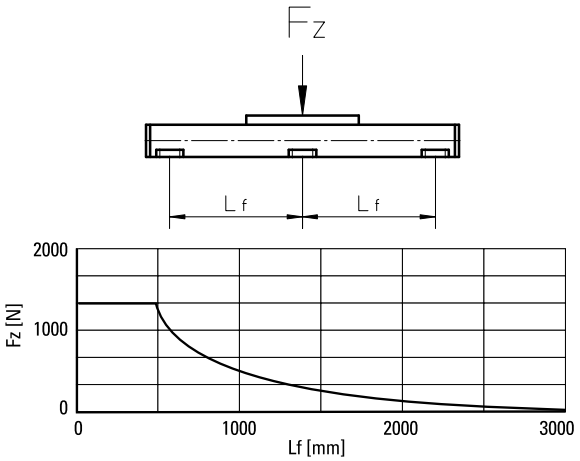
[1] Value for the complete unit

Carriage Idle Torque (M idle) [Nm]

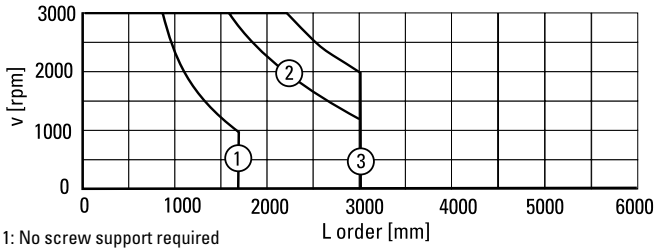
Input speed [rpm]	Screw lead [mm]				
	p = 5	p = 5,08	p = 10	p = 20	p = 32[1]
500 - no screw supports	0,10	0,10	0,15	0,30	0,80
500 - with screw supports	0,13	0,13	0,27	0,45	1,00

[1] Value for cmposite nut.
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

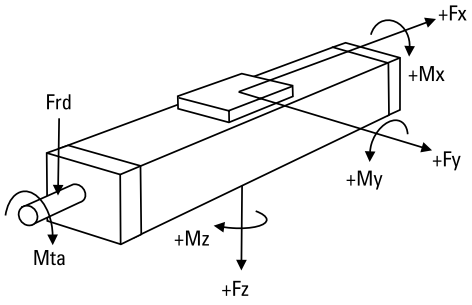


Critical Speed



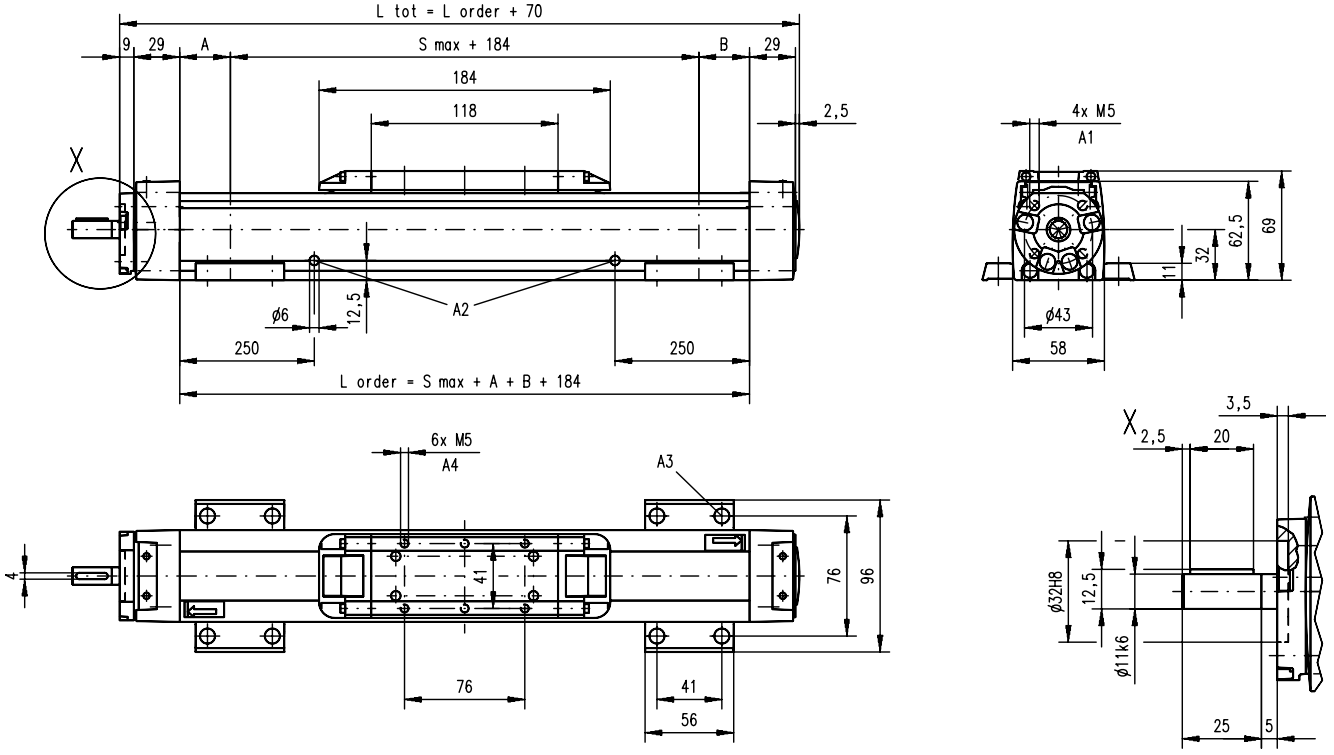
1: No screw support required
2: Single screw support required
3: Double screw supports required

Definition of Forces



M55

Ball Screw Drive, Slide Guide

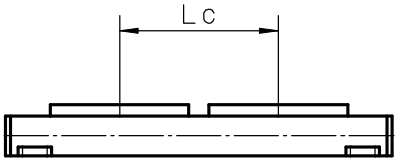


A1: depth 7,5, Heli coil
A2: lubrication holes
A3: ø9,5/ø5,5 for socket head cap screw M5
A4: depth 7,5, Heli coil

Screw support configuration	A [mm]	B [mm]	Ordering length (L order) [mm]	Total length (L tot) [mm]
No screw support	6	6	L order = S max + A + B + 184	L tot = L order + 70
Single screw support	32	32	L order = S max + A + B + 184	L tot = L order + 70
Double screw supports	83	83	L order = S max + A + B + 184	L tot = L order + 70

Double Carriages

Parameter		M55
Minimum distance between carriages (Lc)	[mm]	200
Dynamic load (Fy), maximum	[N]	600
Dynamic load (Fz), maximum	[N]	600
Dynamic load torque (My), maximum	[Nm]	Lc[1] × 0,3
Dynamic load torque (Mz), maximum	[Nm]	Lc[1] × 0,3
Force required to move second carriage	[N]	35
Weight of unit with zero stroke of carriages	[kg]	 5,14 2,40



Screw support configuration	A [mm]	B [mm]	Ordering length (L order) [mm]	Total length (L tot) [mm]
No screw support	6	6	L order = S max + A + B + Lc + 184	L tot = L order + 70
Single screw support	32	32	L order = S max + A + B + Lc + 184	L tot = L order + 70
Double screw supports	83	83	L order = S max + A + B + Lc + 184	L tot = L order + 70

[1] Value in mm

M75

Ball Screw Drive, Slide Guide

» Ordering key - see page 186
» Accessories - see page 125
» Additional data - see page 172

General Specifications

Parameter	M75
Profile size (w × h) [mm]	86 × 75
Type of screw	ball screw with single nut
Carriage sealing system	self-adjusting steel cover band
Screw supports	number of screw supports to be specified by customer at order
Lubrication	lubrication of ball screw
Included accessories	none

Performance Specifications

Parameter		M75
Stroke length (S max), maximum	[mm]	4000
Linear speed, maximum	[m/s]	1,6
Acceleration, maximum	[m/s²]	8
Repeatability	[± mm]	0,05
Input speed, maximum ball nut units / composite nut units	[rpm]	 5000 / 1500
Operation temperature limits	[°C]	-20 – 70
Dynamic load (Fx), maximum ball nut units / composite nut units	[N]	 2500 / 1250
Dynamic load (Fy), maximum	[N]	1485[1]
Dynamic load (Fz), maximum	[N]	1485[1]
Dynamic load torque (Mx), maximum	[Nm]	49[1]
Dynamic load torque (My), maximum	[Nm]	85[1]
Dynamic load torque (Mz), maximum	[Nm]	85[1]
Drive shaft force (Frd), maximum	[N]	600
Drive shaft torque (Mta), maximum	[Nm]	30
Screw diameter (d0)	[mm]	20
Screw lead (p) ball nut units / composite nut units	[mm]	 5, 12,7, 20 / 5
Weight of unit with zero stroke of every 100 mm of stroke of carriage of option single screw support of option double screw supports	[kg]	 6,07 0,82 1,70 1,70 3,58

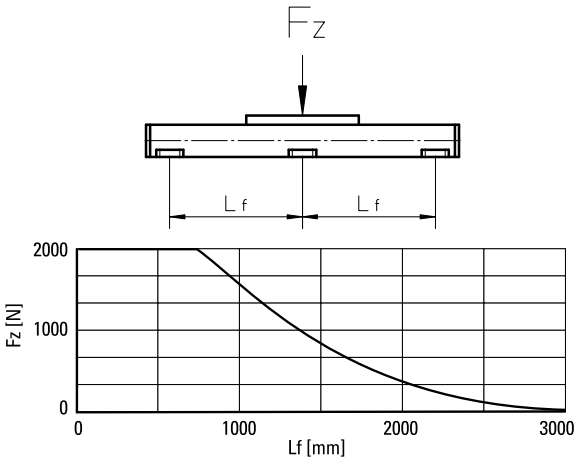
[1] Value for the complete unit

Carriage Idle Torque (M idle) [Nm]

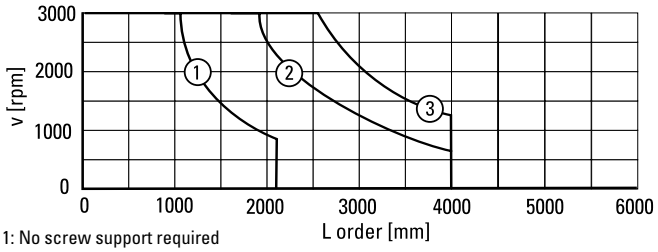
Input speed [rpm]	Screw lead [mm]			
	p = 5	p = 5[1]	p = 12,7	p = 20
500 - no screw supports	0,10	0,20	0,24	0,37
500 - with screw supports	0,15	0,50	0,39	0,57

[1] Value for composite nut.
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

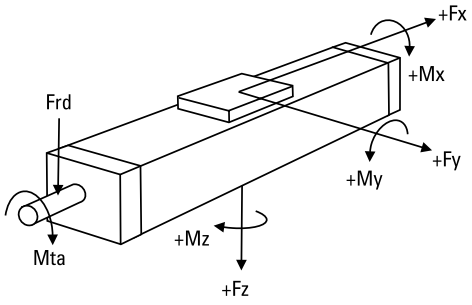


Critical Speed



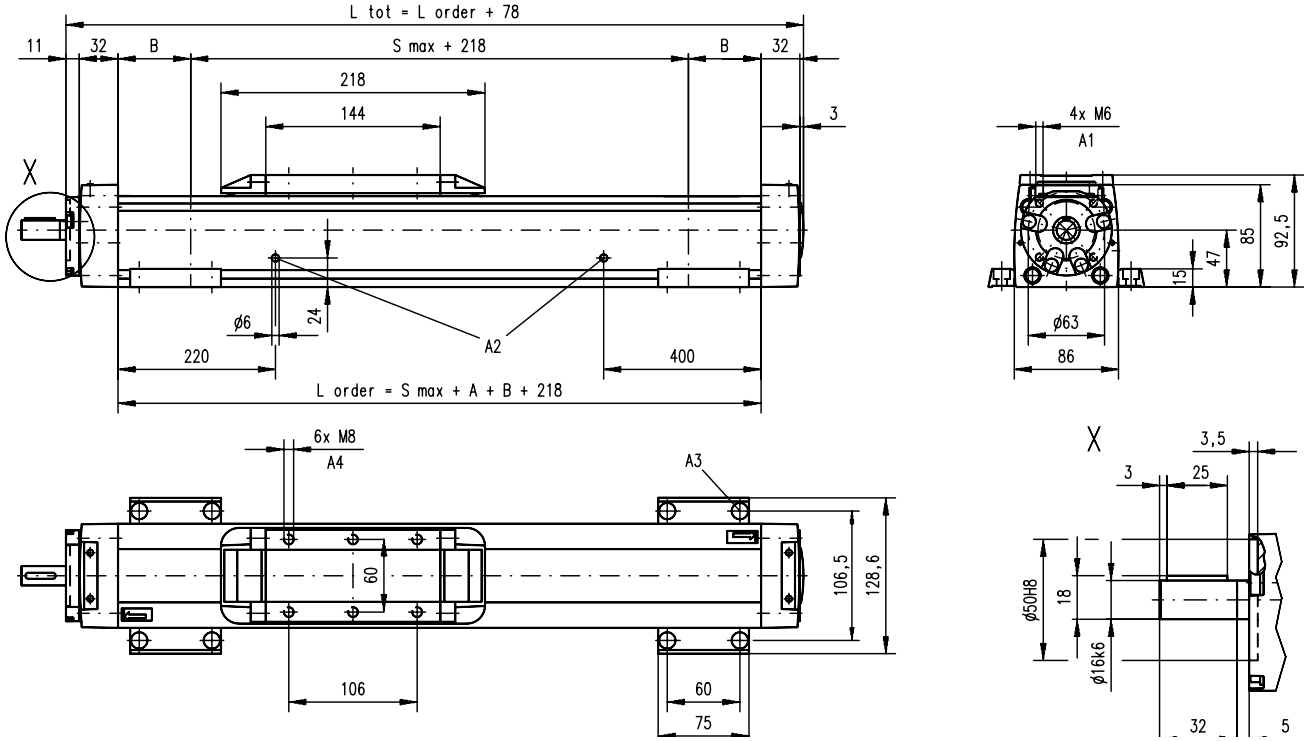
1: No screw support required
2: Single screw support required
3: Double screw supports required

Definition of Forces



M75

Ball Screw Drive, Slide Guide

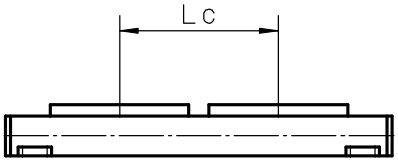


A1: depth 9, Heli coil
A2: lubrication holes
A3: ø13,5/ø8,5 for socket head cap screw M8
A4: depth 8, Heli coil

Screw support configuration	A [mm]	B [mm]	Ordering length (L order) [mm]	Total length (L tot) [mm]
No screw support	5	5	L order = S max + A + B + 218	L tot = L order + 78
Single screw support	60	60	L order = S max + A + B + 218	L tot = L order + 78
Double screw supports	126	126	L order = S max + A + B + 218	L tot = L order + 78

Double Carriages

Parameter		M75
Minimum distance between carriages (Lc)	[mm]	250
Dynamic load (Fy), maximum	[N]	2227
Dynamic load (Fz), maximum	[N]	2227
Dynamic load torque (My), maximum	[Nm]	Lc[1] × 1,114
Dynamic load torque (Mz), maximum	[Nm]	Lc[1] × 1,114
Force required to move second carriage	[N]	40
Weight of unit with zero stroke of carriages	[kg]	 9,82 3,40



Screw support configuration	A [mm]	B [mm]	Ordering length (L order) [mm]	Total length (L tot) [mm]
No screw support	5	5	L order = S max + A + B + Lc + 218	L tot = L order + 78
Single screw support	60	60	L order = S max + A + B + Lc + 218	L tot = L order + 78
Double screw supports	126	126	L order = S max + A + B + Lc + 218	L tot = L order + 78

[1] Value in mm

M100

Ball Screw Drive, Slide Guide

» Ordering key - see page 186
» Accessories - see page 125
» Additional data - see page 172

General Specifications

Parameter	M100
Profile size (w × h) [mm]	108 × 100
Type of screw	ball screw with single nut
Carriage sealing system	self-adjusting steel cover band
Screw supports	number of screw supports to be specified by customer at order
Lubrication	lubrication of ball screw
Included accessories	none

Performance Specifications

Parameter		M100
Stroke length (S max), maximum	[mm]	6000
Linear speed, maximum	[m/s]	1,6
Acceleration, maximum	[m/s²]	8
Repeatability	[± mm]	0,05
Input speed, maximum ball nut units / composite nut units	[rpm]	 4000 / 1500
Operation temperature limits	[°C]	-20 – 70
Dynamic load (Fx), maximum ball nut units / composite nut units	[N]	 5000 / 2000
Dynamic load (Fy), maximum	[N]	3005
Dynamic load (Fz), maximum	[N]	3005
Dynamic load torque (Mx), maximum	[Nm]	117
Dynamic load torque (My), maximum	[Nm]	279
Dynamic load torque (Mz), maximum	[Nm]	279
Drive shaft force (Frd), maximum	[N]	1000
Drive shaft torque (Mta), maximum	[Nm]	45
Screw diameter (d0)	[mm]	25
Screw lead (p) ball nut units / composite nut units	[mm]	 5, 10, 25 / 10, 25
Weight of unit with zero stroke of every 100 mm of stroke of carriage of option single screw support of option double screw supports	[kg]	 12,87 1,42 3,50 1,86 4,42

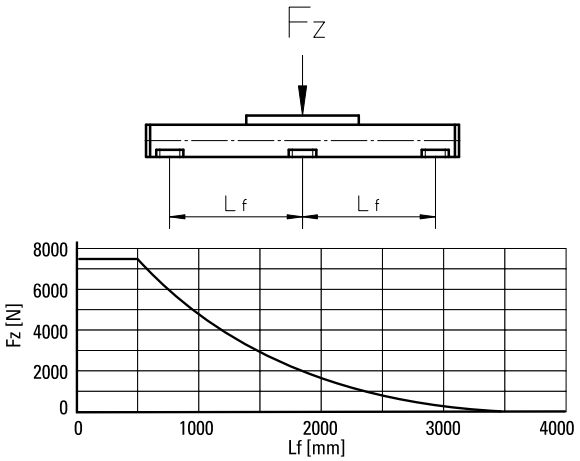
[1] Value for the complete unit

Carriage Idle Torque (M idle) [Nm]

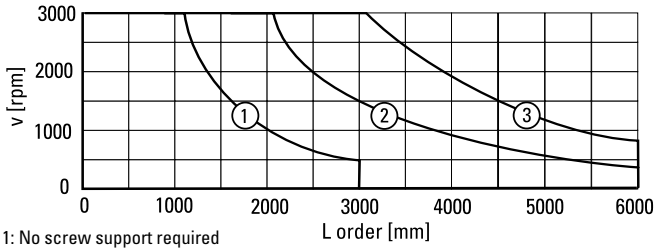
Input speed [rpm]	Screw lead [mm]				
	p = 5	p = 10	p = 10[1]	p = 25	p = 25[1]
500 - no screw supports	0,15	0,25	0,50	0,55	1,00
500 - with screw supports	0,25	0,40	0,80	0,85	1,30

[1] Value for composite nut.
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

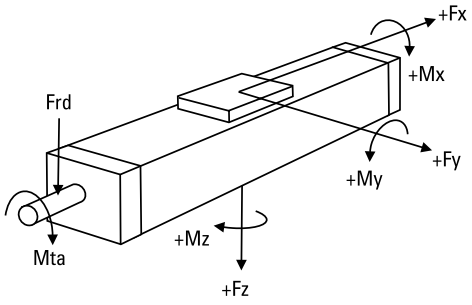


Critical Speed



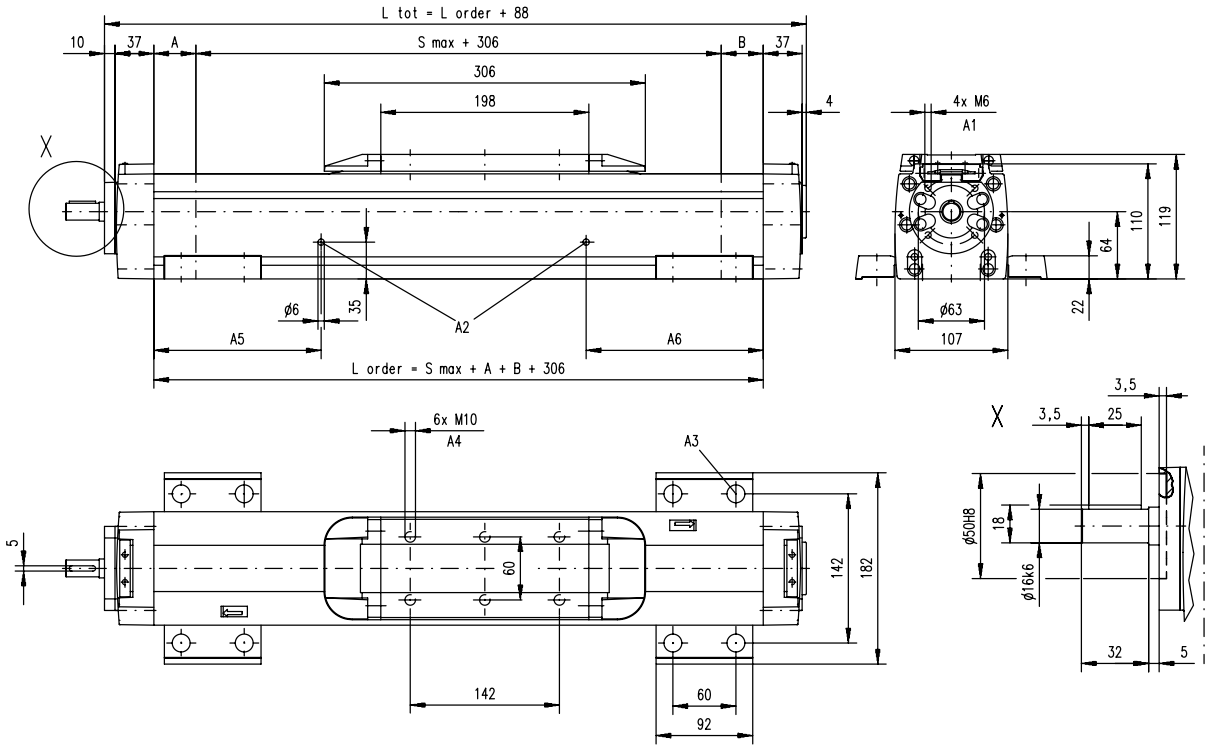
1: No screw support required
2: Single screw support required
3: Double screw supports required

Definition of Forces



M100

Ball Screw Drive, Slide Guide

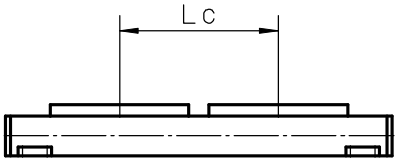


A1: depth 9, Heli coil
A2: lubrication holes
A3: ø17/ø10,5 for socket head cap screw M10
A4: depth 10, Heli coil
A5: 100 (L order <= 1 m), 320 (L order > 1 m)
A6: 100 (L order <= 1 m), 430 (L order > 1 m)

Screw support configuration	A [mm]	B [mm]	Ordering length (L order) [mm]	Total length (L tot) [mm]
No screw support	1	1	L order = S max + A + B + 306	L tot = L order + 88
Single screw support	31	31	L order = S max + A + B + 306	L tot = L order + 88
Double screw supports	86	86	L order = S max + A + B + 306	L tot = L order + 88

Double Carriages

Parameter		M100
Minimum distance between carriages (Lc)	[mm]	350
Dynamic load (Fy), maximum	[N]	4508
Dynamic load (Fz), maximum	[N]	4508
Dynamic load torque (My), maximum	[Nm]	Lc[1] × 2,254
Dynamic load torque (Mz), maximum	[Nm]	Lc[1] × 2,254
Force required to move second carriage	[N]	45
Weight of unit with zero stroke of carriages	[kg]	 21,34 7,00



Screw support configuration	A [mm]	B [mm]	Ordering length (L order) [mm]	Total length (L tot) [mm]
No screw support	1	1	L order = S max + A + B + Lc + 306	L tot = L order + 88
Single screw support	31	31	L order = S max + A + B + Lc + 306	L tot = L order + 88
Double screw supports	86	86	L order = S max + A + B + Lc + 306	L tot = L order + 88

[1] Value in mm

M75D

Ball Screw Drive, Slide Guide, Pre-loaded Ball Nut

» Ordering key - see page 187
» Accessories - see page 125
» Additional data - see page 172

General Specifications

Parameter	M75D
Profile size (w × h) [mm]	86 × 75
Type of screw	ball screw with pre-loaded nut
Carriage sealing system	self-adjusting steel cover band
Screw supports	number of screw supports to be specified by customer at order
Lubrication	lubrication of ball screw
Included accessories	none

Performance Specifications

Parameter		M75D
Stroke length (S max), maximum	[mm]	3550
Linear speed, maximum	[m/s]	1,6
Acceleration, maximum	[m/s²]	8
Repeatability	[± mm]	0,05
Input speed, maximum	[rpm]	5000
Operation temperature limits	[°C]	-20 – 70
Dynamic load (Fx), maximum	[N]	2500[1]
Dynamic load (Fy), maximum	[N]	1485[1]
Dynamic load (Fz), maximum	[N]	1485[1]
Dynamic load torque (Mx), maximum	[Nm]	49[1]
Dynamic load torque (My), maximum	[Nm]	85[1]
Dynamic load torque (Mz), maximum	[Nm]	85[1]
Drive shaft force (Frd), maximum	[N]	600
Drive shaft torque (Mta), maximum	[Nm]	30
Screw diameter (d0)	[mm]	20
Screw lead (p)	[mm]	5, 20
Weight	[kg]	
of unit with zero stroke		6,57
of every 100 mm of stroke		0,82
of carriage		1,70
of option single screw support		1,70
of option double screw supports		3,58

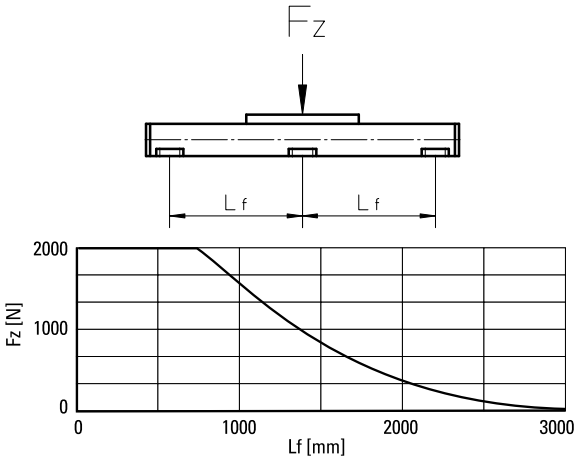
[1] Value for the complete unit

Carriage Idle Torque (M idle) [Nm]

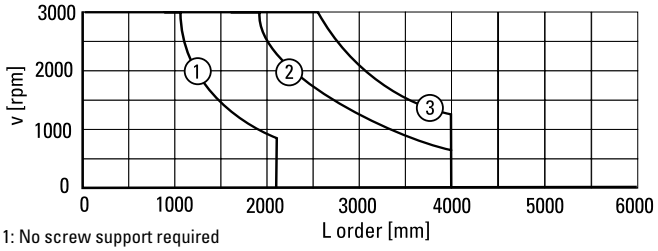
Input speed [rpm]	Screw lead [mm]	
	p = 5	p = 20
500 - no screw supports	0,15	0,5
500 - with screw supports	0,2	0,8

M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

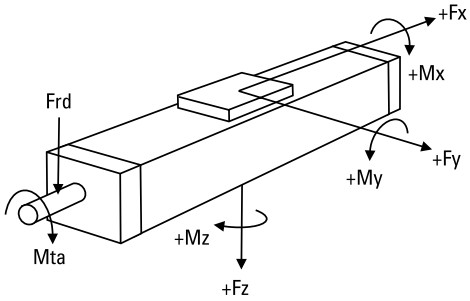


Critical Speed



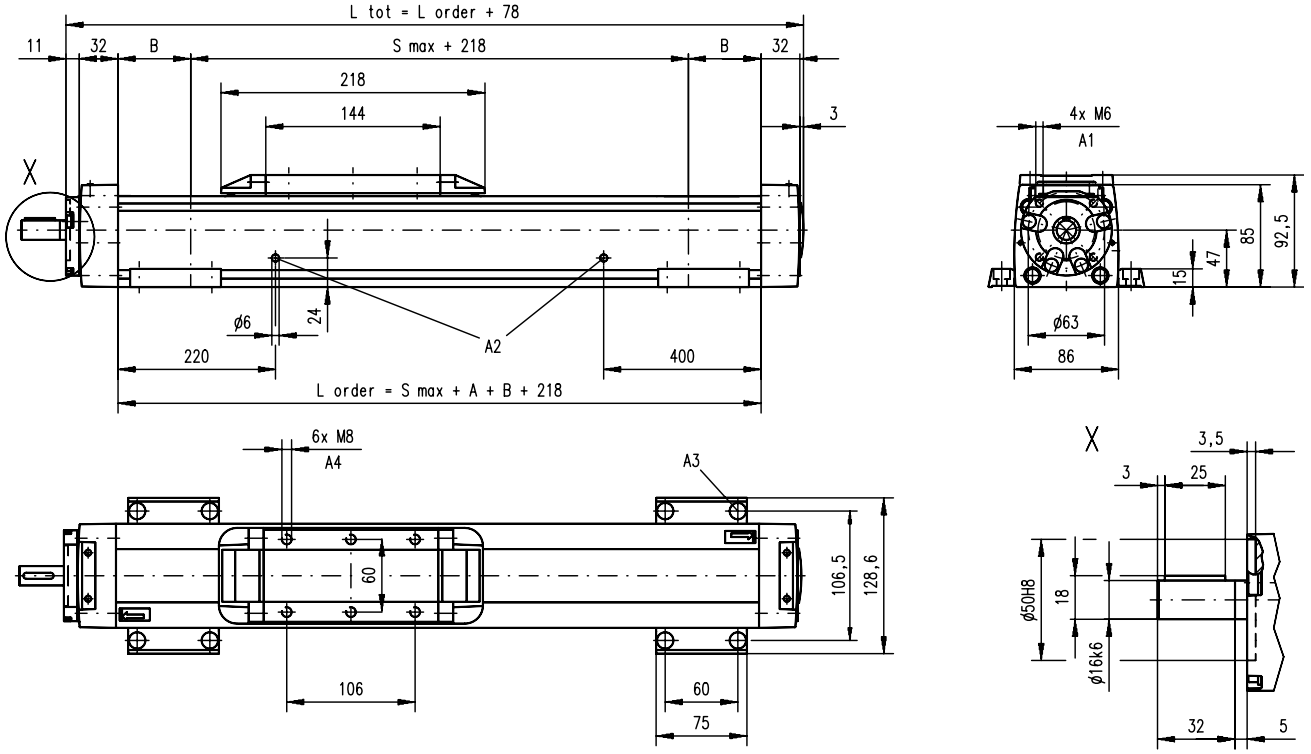
1: No screw support required
2: Single screw support required
3: Double screw supports required

Definition of Forces



M75D

Ball Screw Drive, Slide Guide, Pre-loaded Ball Nut

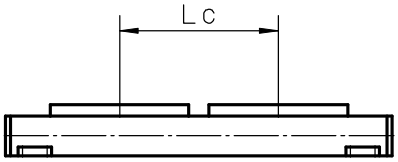


A1: depth 9, Heli coil
A2: lubrication holes
A3: ø13,5/ø8,5 for socket head cap screw M8
A4: depth 8, Heli coil

Screw support configuration	A [mm]	B [mm]	Ordering length (L order) [mm]	Total length (L tot) [mm]
No screw support	5	76	L order = S max + A + B + 218	L tot = L order + 78
Single screw support	60	151	L order = S max + A + B + 218	L tot = L order + 78
Double screw supports	126	216	L order = S max + A + B + 218	L tot = L order + 78

Double Carriages

Parameter		M75D
Minimum distance between carriages (Lc)	[mm]	250
Dynamic load (Fy), maximum	[N]	2227
Dynamic load (Fz), maximum	[N]	2227
Dynamic load torque (My), maximum	[Nm]	Lc[1] × 1,114
Dynamic load torque (Mz), maximum	[Nm]	Lc[1] × 1,114
Force required to move second carriage	[N]	40
Weight of unit with zero stroke of carriages	[kg]	 10,32 3,40



Screw support configuration	A [mm]	B [mm]	Ordering length (L order) [mm]	Total length (L tot) [mm]
No screw support	5	76	L order = S max + A + B + Lc + 218	L tot = L order + 78
Single screw support	60	151	L order = S max + A + B + Lc + 218	L tot = L order + 78
Double screw supports	126	216	L order = S max + A + B + Lc + 218	L tot = L order + 78

[1] Value in mm

M100D

Ball Screw Drive, Slide Guide, Pre-loaded Ball Nut

» Ordering key - see page 187
» Accessories - see page 125
» Additional data - see page 172

General Specifications

Parameter	M100D
Profile size (w × h) [mm]	108 × 100
Type of screw	ball screw with pre-loaded nut
Carriage sealing system	self-adjusting steel cover band
Screw supports	number of screw supports to be specified by customer at order
Lubrication	lubrication of ball screw
Included accessories	none

Performance Specifications

Parameter		M100D
Stroke length (S max), maximum	[mm]	6000
Linear speed, maximum	[m/s]	1,6
Acceleration, maximum	[m/s²]	8
Repeatability	[± mm]	0,05
Input speed, maximum	[rpm]	4000
Operation temperature limits	[°C]	-20 – 70
Dynamic load (Fx), maximum	[N]	5000
Dynamic load (Fy), maximum	[N]	3005[1]
Dynamic load (Fz), maximum	[N]	3005[1]
Dynamic load torque (Mx), maximum	[Nm]	117[1]
Dynamic load torque (My), maximum	[Nm]	279[1]
Dynamic load torque (Mz), maximum	[Nm]	279[1]
Drive shaft force (Frd), maximum	[N]	100
Drive shaft torque (Mta), maximum	[Nm]	45
Screw diameter (d0)	[mm]	25
Screw lead (p)	[mm]	5, 10, 25
Weight	[kg]	
of unit with zero stroke		13,87
of every 100 mm of stroke		1,42
of carriage		3,50
of option single screw support		1,86
of option double screw supports		4,42

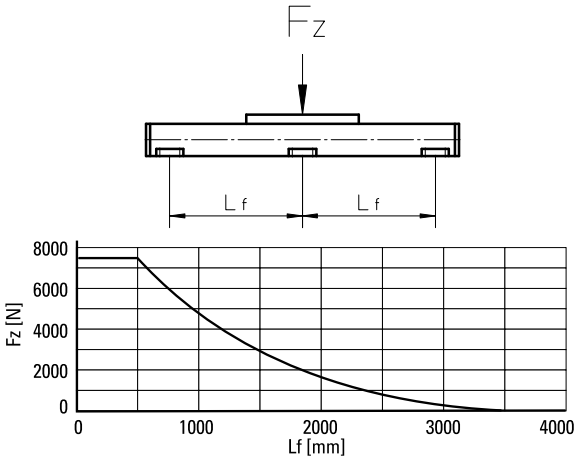
[1] Value for the complete unit

Carriage Idle Torque (M idle) [Nm]

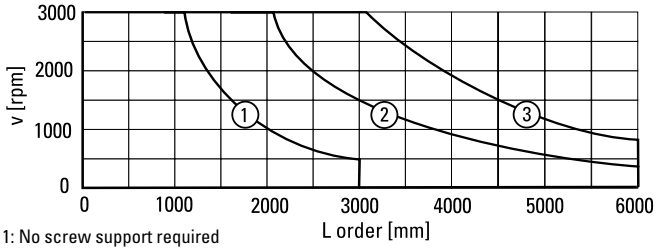
Input speed [rpm]	Screw lead [mm]		
	p = 5	p = 10	p = 25
500 - no screw supports	0,2	0,4	0,8
500 - with screw supports	0,4	0,6	1,3

M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

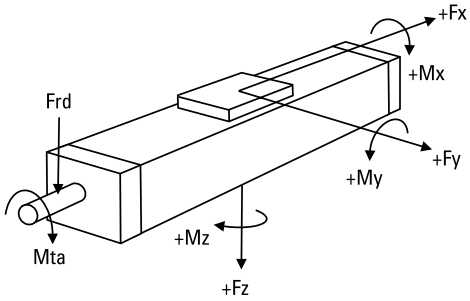


Critical Speed



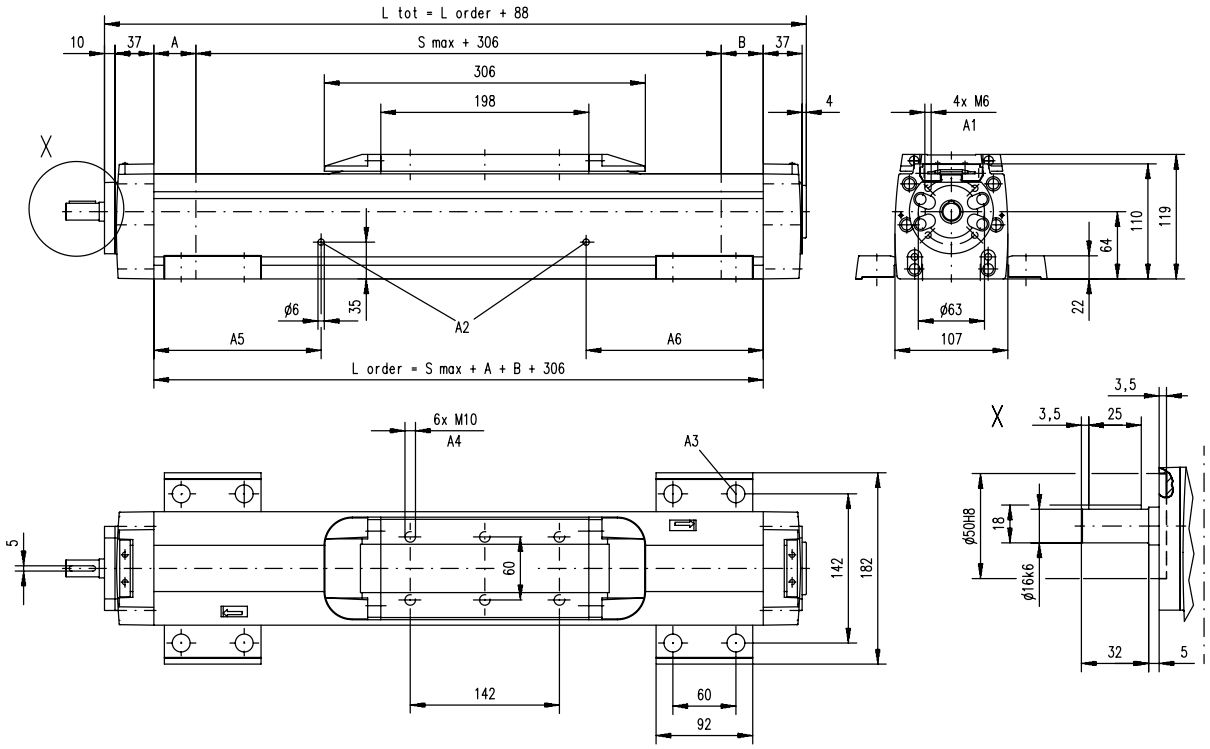
1: No screw support required
2: Single screw support required
3: Double screw supports required

Definition of Forces



M100D

Ball Screw Drive, Slide Guide, Pre-loaded Ball Nut

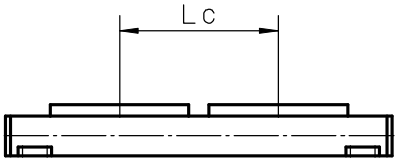


A1: depth 9, Heli coil
A2: lubrication holes
A3: ø17/ø10,5 for socket head cap screw M10
A4: depth 10, Heli coil
A5: 100 (L order <= 1 m), 320 (L order > 1 m)
A6: 100 (L order <= 1 m), 430 (L order > 1 m)

Screw support configuration	A [mm]	B [mm]	Ordering length (L order) [mm]	Total length (L tot) [mm]
No screw support	1	59	L order = S max + A + B + 306	L tot = L order + 88
Single screw support	31	117	L order = S max + A + B + 306	L tot = L order + 88
Double screw supports	86	172	L order = S max + A + B + 306	L tot = L order + 88

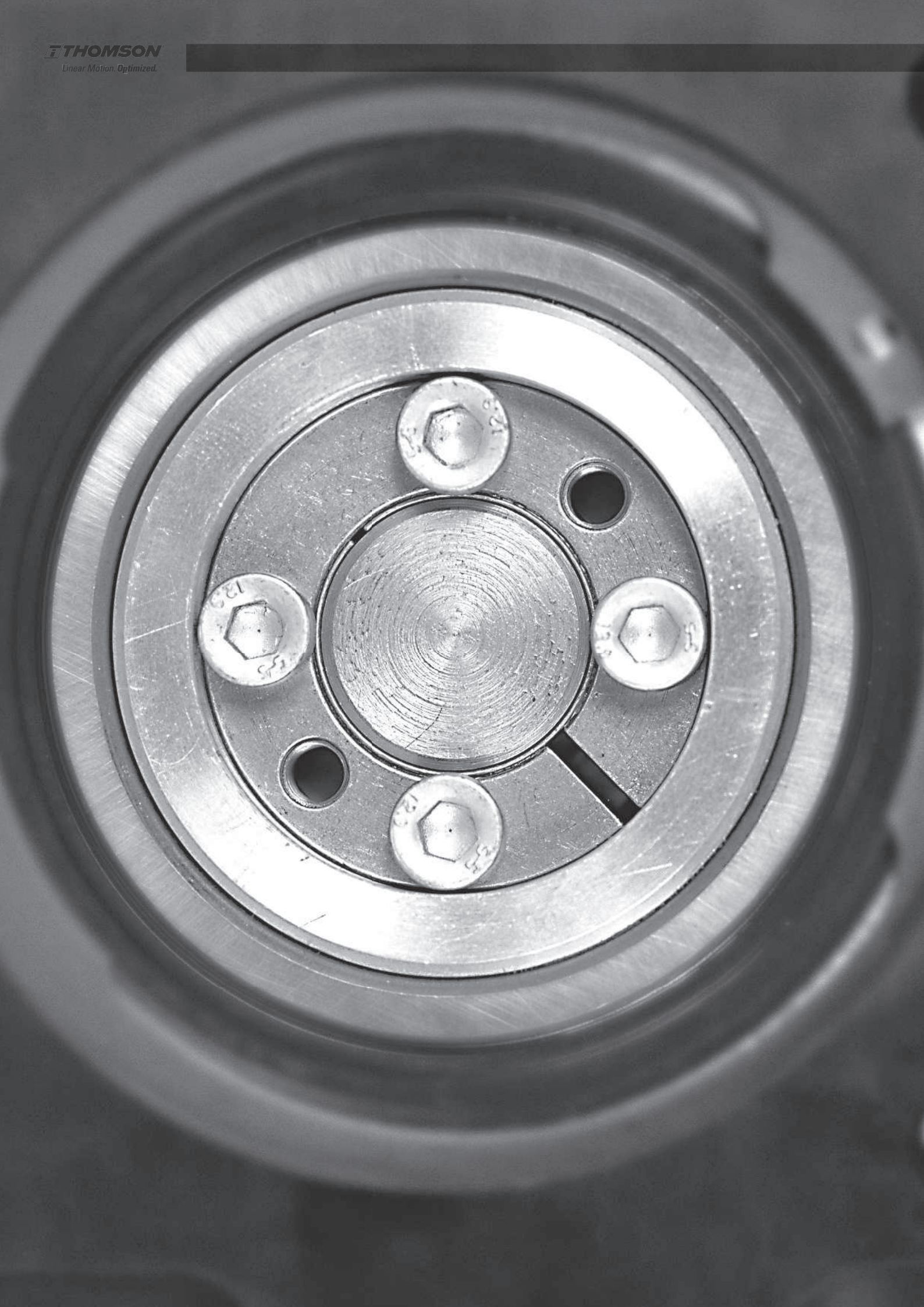
Double Carriages

Parameter		M100D
Minimum distance between carriages (Lc)	[mm]	350
Dynamic load (Fy), maximum	[N]	4508
Dynamic load (Fz), maximum	[N]	4508
Dynamic load torque (My), maximum	[Nm]	Lc[1] × 2,254
Dynamic load torque (Mz), maximum	[Nm]	Lc[1] × 2,254
Force required to move second carriage	[N]	45
Weight of unit with zero stroke of carriages	[kg]	 22,34 7,00



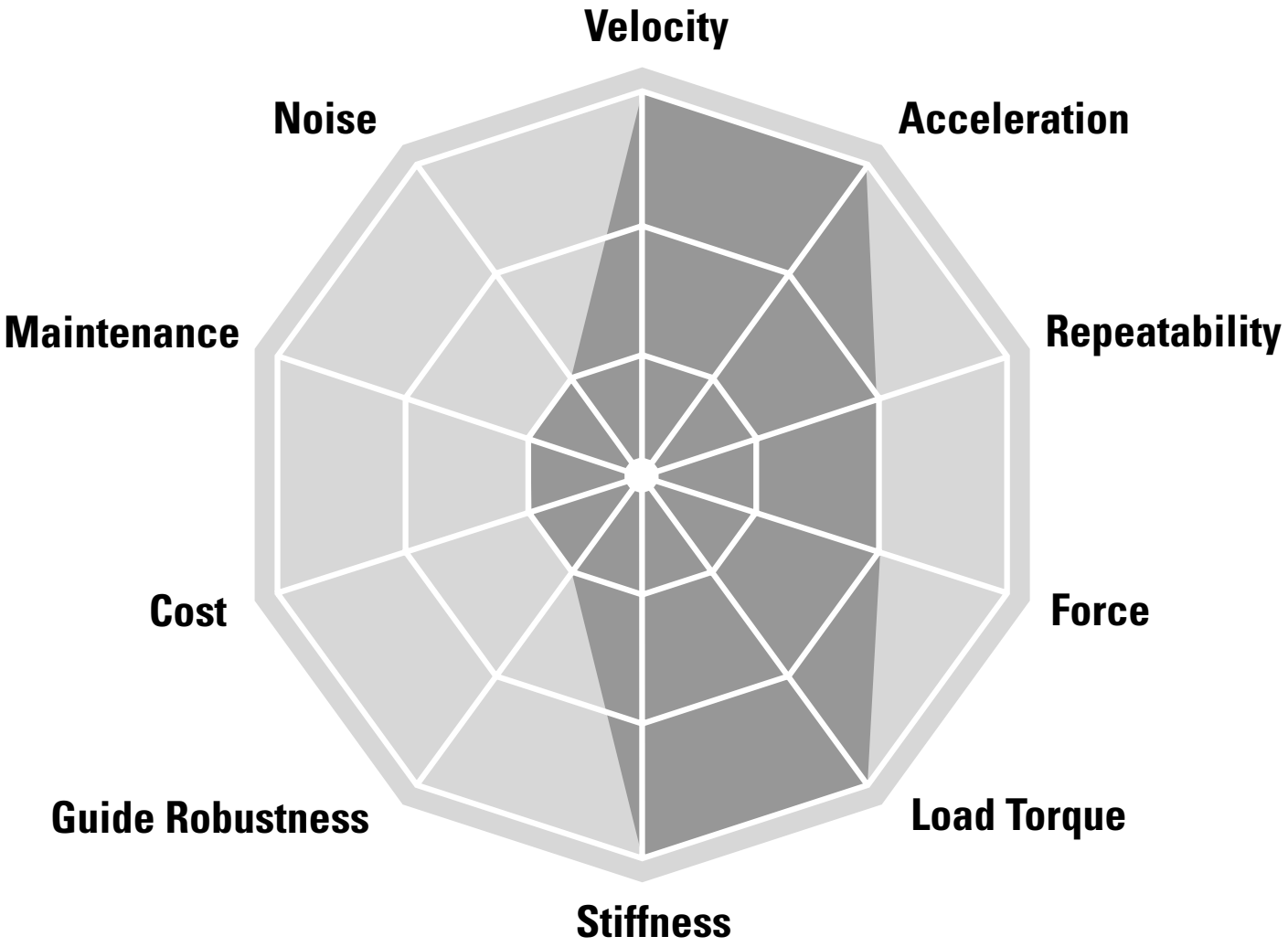
Screw support configuration	A [mm]	B [mm]	Ordering length (L order) [mm]	Total length (L tot) [mm]
No screw support	1	59	L order = S max + A + B + Lc + 306	L tot = L order + 88
Single screw support	31	117	L order = S max + A + B + Lc + 306	L tot = L order + 88
Double screw supports	86	172	L order = S max + A + B + Lc + 306	L tot = L order + 88

[1] Value in mm



Linear Motion Systems with Belt Drive and Ball Guide

SpeedLine, Movopart, ForceLine



Typical Applications

Typical applications are where medium accuracy, speed and load capability is required. Typical examples are cutting, welding, glueing and assembly operations and in materials handling applications such as palletizing and pick and place operations.

Linear Motion Systems with Belt Drive and Ball Guide

Overview

SpeedLine WH

WH40

Features

- Can be installed in all directions
- Stroke up to 2 m
- Acceleration up to 40 m/s^2
- Compact

Parameter		WH40
Profile size (width × height)	[mm]	40 × 40
Stroke length (S max), maximum	[mm]	2000
Linear speed, maximum	[m/s]	3,0
Dynamic carriage load (Fz), maximum	[N]	600
Remarks		no cover band
Page		60

PowerLine WMZ

WM80Z

Features

- Can be installed in all directions
- Stroke up to 5,5 m
- Speed up to 5 m/s
- Patented plastic cover band

Parameter		WM60Z	WM80Z
Profile size (width × height)	[mm]	60 × 60	80 × 80
Stroke length (S max), maximum	[mm]	4000	5500
Linear speed, maximum	[m/s]	2,5	5,0
Dynamic carriage load (Fz), maximum	[N]	1400	2100
Remarks		-	-
Page		62	64

Movopart M

M75

Features

- Can be installed in all directions
- Self-adjusting stainless steel cover band
- Stroke up to 12 m
- Wash down protected versions available

Parameter		M55	M75	M100
Profile size (width × height)	[mm]	58 × 55	86 × 75	108 × 100
Stroke length (S max), maximum	[mm]	7000	12000	12000
Linear speed, maximum	[m/s]	5,0	5,0	5,0
Dynamic carriage load (Fz), maximum	[N]	750	1750	4000
Remarks		-	-	-
Page		68	70	72

Linear Motion Systems with Belt Drive and Ball Guide

Overview

ForceLine **MLSM**

MLSM80Z

Features

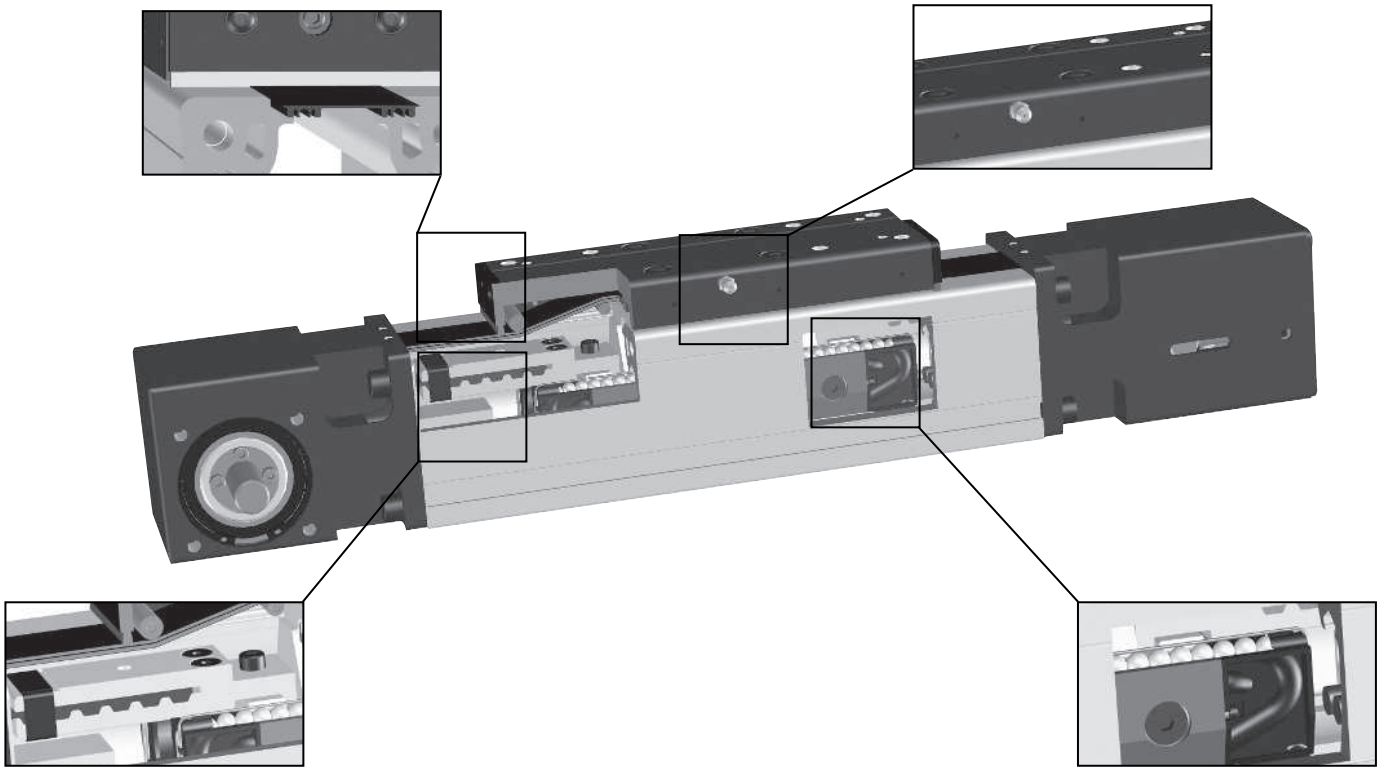
- Can be installed in all directions
- Patented plastic cover band
- High load capabilities
- Low profile height

Parameter		MLSM80Z
Profile size (width × height)	[mm]	240 × 85
Stroke length (S max), maximum	[mm]	5900
Linear speed, maximum	[m/s]	5,0
Dynamic carriage load (Fz), maximum	[N]	6400
Remarks		-
Page		74

WMZ-Series Technical Presentation

Cover band
The patented self-adjusting cover band protect the interior of the unit from the penetration of dirt, dust and liquids.

Central lubrication
One central lubrication point on the carriage services the entire unit resulting in a minimum maintenace required.



Belt drive
The belt is protected from the outside ensuring long, accurate and safe operation.

Ball guides
Integrated patented ball guides with hardened steel tracks for optimum performance.

WH40

Belt Drive, Ball Guide

» Ordering key - see page 188
» Accessories - see page 125
» Additional data - see page 172

General Specifications

Parameter	WH40
Profile size (w × h) [mm]	40 × 40
Type of belt	10 AT 5
Carriage sealing system	none
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WH40
Stroke length (S max), maximum	[mm]	2000
Linear speed, maximum	[m/s]	3,0
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,05
Input speed, maximum	[rpm]	1800
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	315[1]
Dynamic load (Fy), maximum	[N]	450[1] / 5300[2]
Dynamic load (Fz), maximum	[N]	600[1] / 6790[2]
Dynamic load torque (Mx), maximum	[Nm]	10[1] / 32[2]
Dynamic load torque (My), maximum	[Nm]	30[1] / 190[2]
Dynamic load torque (Mz), maximum	[Nm]	30[1] / 190[2]
Drive shaft force (Frd), maximum	[N]	100
Drive shaft torque (Mta), maximum	[Nm]	6
Pulley diameter	[mm]	31,83
Stroke per shaft revolution	[mm]	100
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 1,19 0,15 0,28

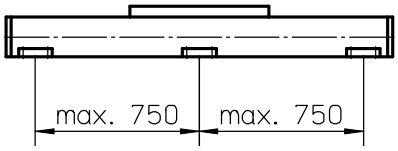
[1] Value for the complete unit, also see diagram Force Fx
[2] Value for the ball guide only

Carriage Idle Torque, (M idle) [Nm]

Input speed [rpm]	Idle torque [Nm]
150	0,1
900	0,3
1800	0,6

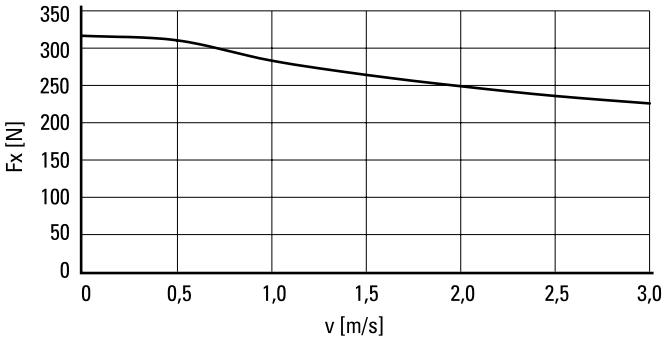
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

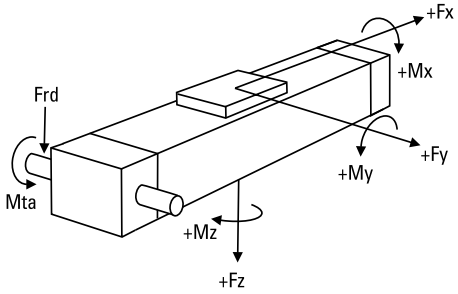


A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Force Fx as a Function of the Speed

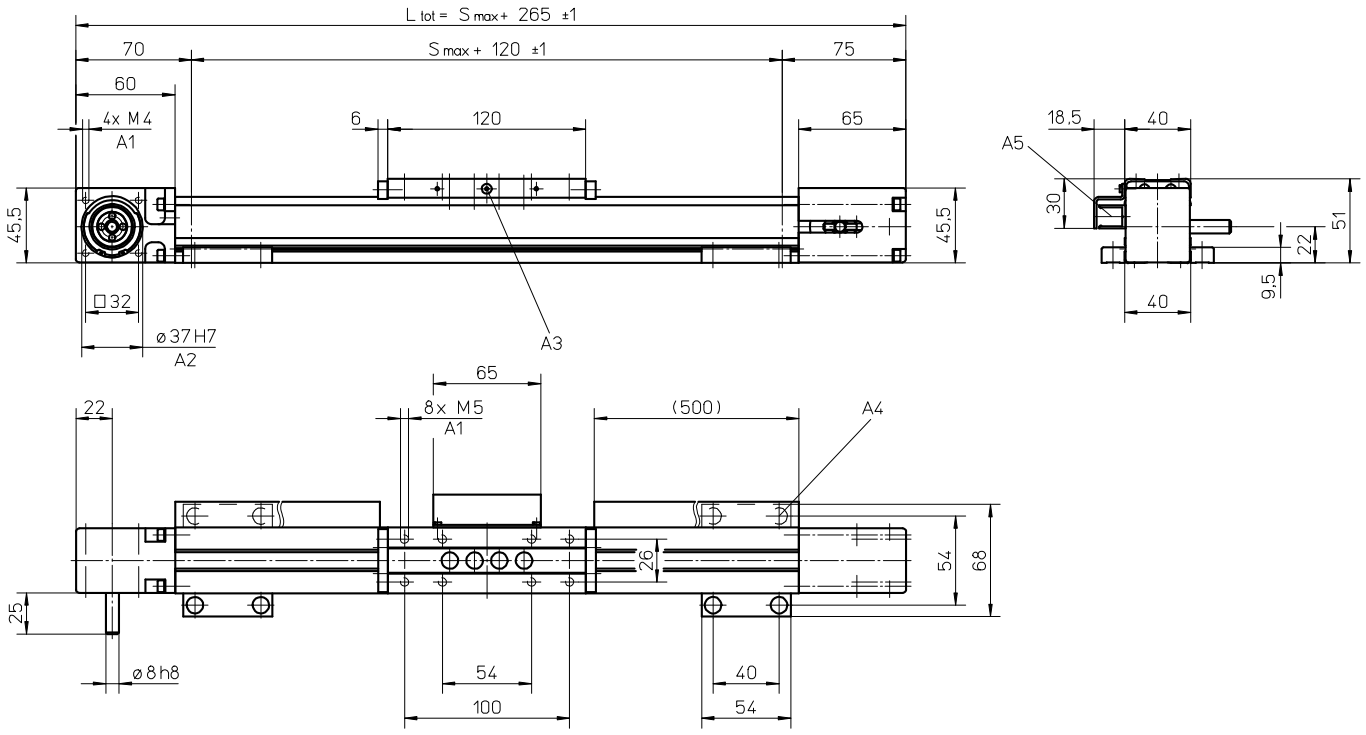


Definition of Forces



WH40

Belt Drive, Ball Guide

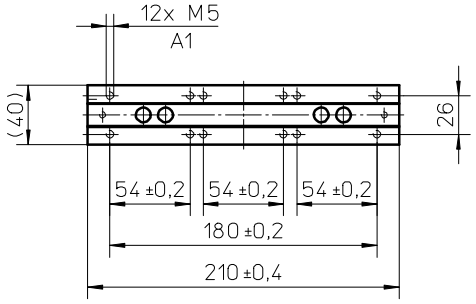


A1: depth 10
A2: depth 3
A3: lubricating nipple on both sides

A4: socket cap screw ISO4762-M5×12 8.8
A5: ENF inductive sensor rail option kit (optional)

Long Carriage

Parameter		WH40
Carriage length	[mm]	210
Dynamic load torque (My), maximum	[Nm]	50
Dynamic load torque (Mz), maximum	[Nm]	50
Weight	[kg]	0,43

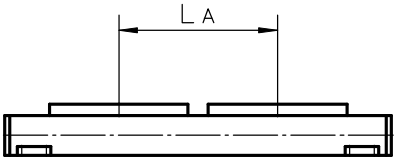


A1: depth 10

Double Carriages

Parameter		WH40
Minimum distance between carriages (L_A)	[mm]	135
Dynamic load (Fy), maximum	[N]	900
Dynamic load (Fz), maximum	[N]	1200
Dynamic load torque (My), maximum	[Nm]	L_A[1] × 0,45
Dynamic load torque (Mz), maximum	[Nm]	L_A[1] × 0,60
Force required to move second carriage	[N]	2
Total length (L tot)	[mm]	S max + 265 + L_A

[1] Value in mm



WM60Z

Belt Drive, Ball Guide, Short Carriage

» Ordering key - see page 189
» Accessories - see page 125
» Additional data - see page 172

General Specifications

Parameter	WM60Z
Profile size (w × h) [mm]	60 × 60
Type of belt	20 ATL 5
Carriage sealing system	self-adjusting plastic cover band
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WM60Z
Stroke length (S max), maximum	[mm]	4000
Linear speed, maximum	[m/s]	2,5
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,05
Input speed, maximum	[rpm]	1250
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	850
Dynamic load (Fy), maximum	[N]	1400[1] / 25930[2]
Dynamic load (Fz), maximum	[N]	1400[1] / 23870[2]
Dynamic load torque (Mx), maximum	[Nm]	25[1] / 420[2]
Dynamic load torque (My), maximum	[Nm]	50[1] / 330[2]
Dynamic load torque (Mz), maximum	[Nm]	50[1] / 360[2]
Drive shaft force (Frd), maximum	[N]	150
Drive shaft torque (Mta), maximum	[Nm]	17
Pulley diameter	[mm]	38,20
Stroke per shaft revolution	[mm]	120
Weight	[kg]	
of unit with zero stroke		4,30
of every 100 mm of stroke		0,45
of each carriage		1,25

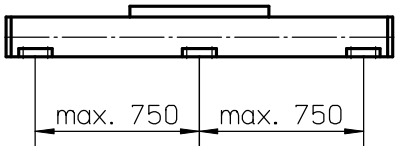
[1] Value for the complete unit, also see diagram Force Fx
[2] Value for the ball guide only

Carriage Idle Torque, (M idle) [Nm]

Input speed [rpm]	Idle torque [Nm]
150	1,6
600	2,5
1250	3,0

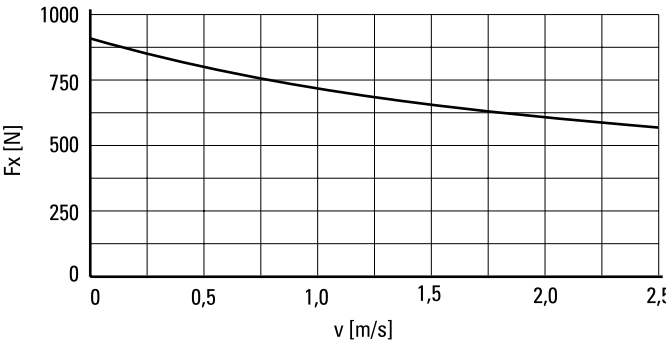
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

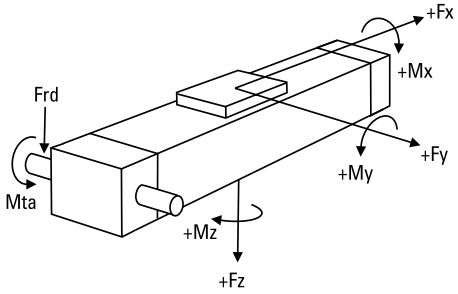


A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Force Fx as a Function of the Speed

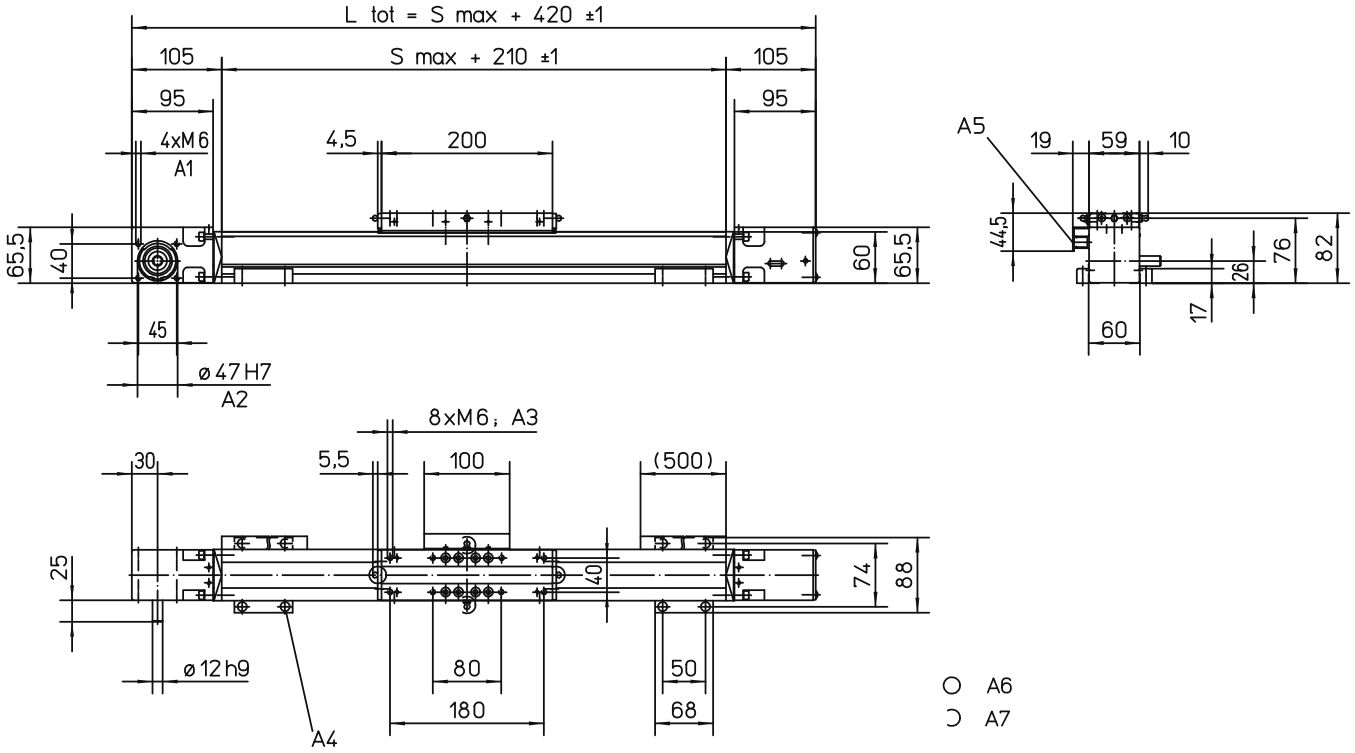


Definition of Forces



WM60Z

Belt Drive, Ball Guide, Short Carriage



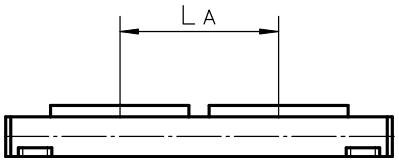
A1: depth 15
A2: depth 4
A3: depth 11
A4: socket cap screw ISO4762-M6×20 8.8

A5: ENF inductive sensor rail option kit (optional)
A6: tapered lubricating nipple to DIN71412 AM6 on fixed-bearing side as standard feature
A7: can be changed over to one of three alternative lubrications points by the customer

Double Short Carriages

Parameter		WM60Z
Minimum distance between carriages (L_A)	[mm]	255
Dynamic load (Fy), maximum	[N]	2800
Dynamic load (Fz), maximum	[N]	2800
Dynamic load torque (My), maximum	[Nm]	L_A[1] × 1,4
Dynamic load torque (Mz), maximum	[Nm]	L_A[1] × 1,4
Force required to move second carriage	[N]	18
Total length (L tot)	[mm]	S max + 420 + L_A

[1] Value in mm



WM80Z

Belt Drive, Ball Guide, Standard Carriage

» Ordering key - see page 189
» Accessories - see page 125
» Additional data - see page 172

General Specifications

Parameter	WM80Z
Profile size (w × h) [mm]	80 × 80
Type of belt	25 AT 10
Carriage sealing system	self-adjusting plastic cover band
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WM80Z
Stroke length (S max), maximum	[mm]	5400
Linear speed, maximum	[m/s]	5,0
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,05
Input speed, maximum	[rpm]	885
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	1470
Dynamic load (Fy), maximum	[N]	3000[1] / 57420[2]
Dynamic load (Fz), maximum	[N]	3000[1] / 54960[2]
Dynamic load torque (Mx), maximum	[Nm]	150[1] / 1370[2]
Dynamic load torque (My), maximum	[Nm]	300[1] / 4200[2]
Dynamic load torque (Mz), maximum	[Nm]	300[1] / 4390[2]
Drive shaft force (Frd), maximum	[N]	600
Drive shaft torque (Mta), maximum	[Nm]	40
Pulley diameter	[mm]	54,11
Stroke per shaft revolution	[mm]	170
Weight	[kg]	
of unit with zero stroke		11,2
of every 100 mm of stroke		0,8
of each carriage		3,4

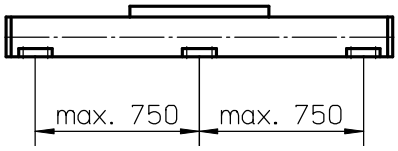
[1] Value for the complete unit, also see diagram Force Fx
[2] Value for the ball guide only

Carriage Idle Torque, (M idle) [Nm]

Input speed [rpm]	Idle torque [Nm]
150	6,5
450	7,7
885	9,3

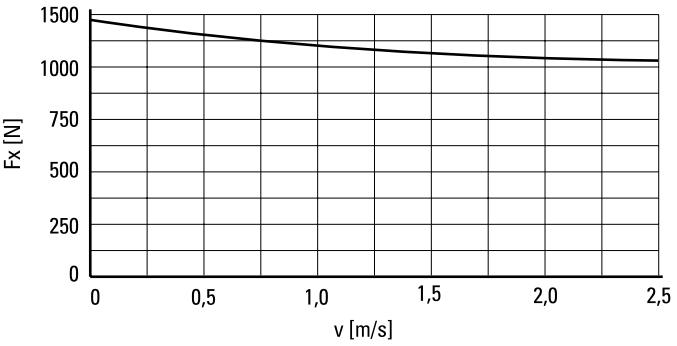
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

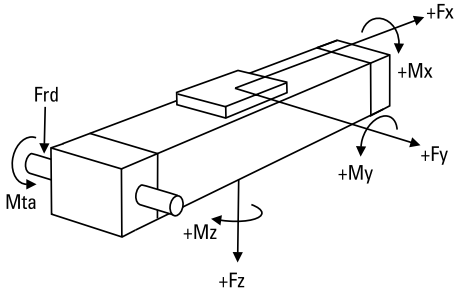


A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Force Fx as a Function of the Speed

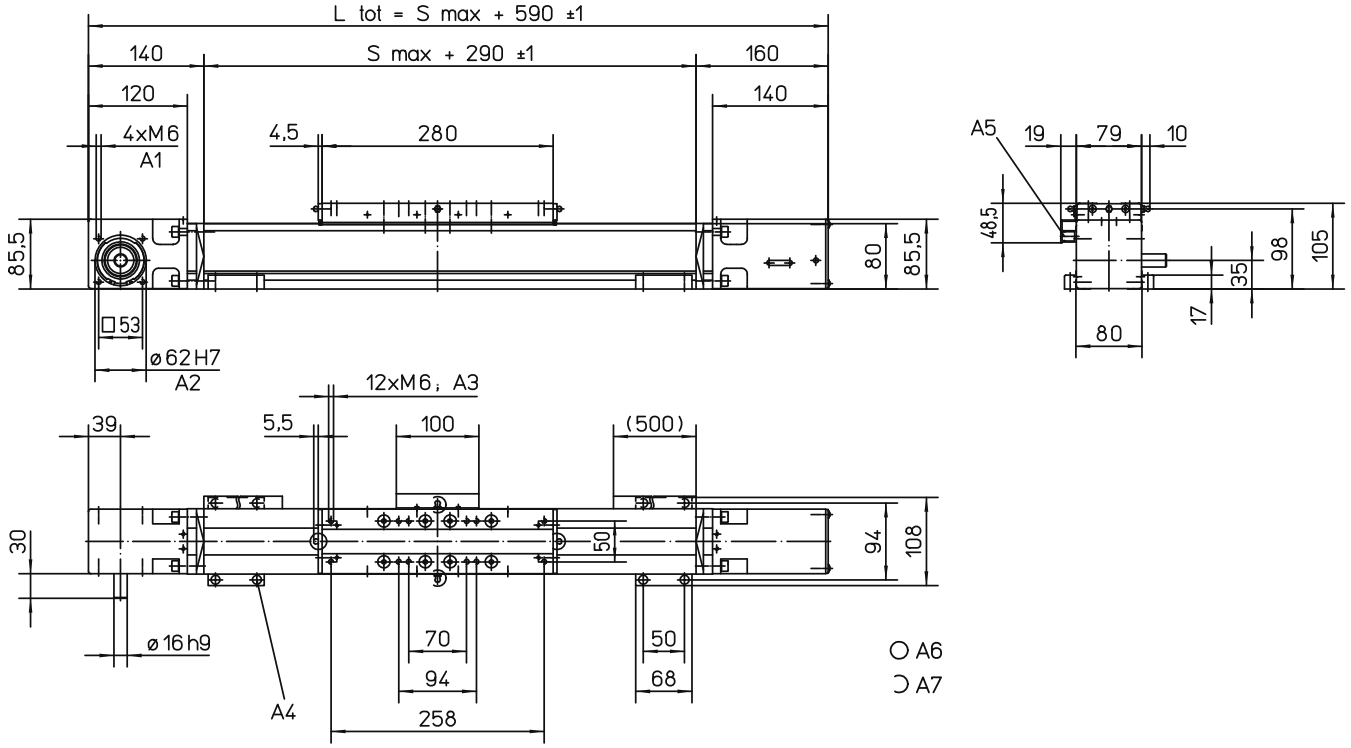


Definition of Forces



WM80Z

Belt Drive, Ball Guide, Standard Carriage

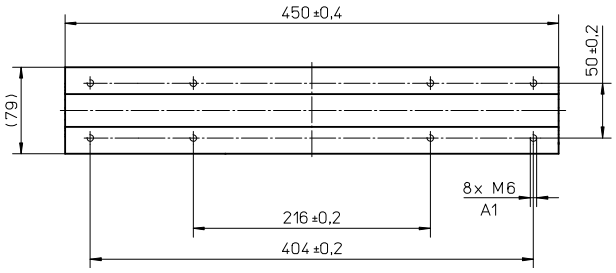


A1: depth 15
A2: depth 2,5
A3: depth 12
A4: socket cap screw ISO4762-M6×20 8.8

A5: ENF inductive sensor rail option kit (optional)
A6: tapered lubricating nipple to DIN71412 AM6 on fixed-bearing side as standard feature
A7: can be changed over to one of three alternative lubrications points by the customer

Long Carriage

Parameter		WM80Z
Carriage length	[mm]	450
Dynamic load torque (My), maximum	[Nm]	750
Dynamic load torque (Mz), maximum	[Nm]	750
Weight	[kg]	5,1

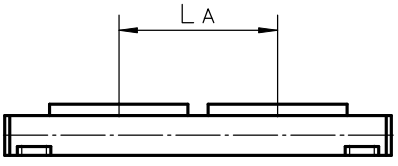


A1: depth 12 mm

Double Carriages

Parameter		WM80Z
Minimum distance between carriages (L_A)	[mm]	360
Dynamic load (Fy), maximum	[N]	6000
Dynamic load (Fz), maximum	[N]	6000
Dynamic load torque (My), maximum	[Nm]	$L_{A^1} \times 3$
Dynamic load torque (Mz), maximum	[Nm]	$L_{A^1} \times 3$
Force required to move second carriage	[N]	25
Total length (L tot)	[mm]	S max + 590 + L_A

[1] Value in mm



WM80Z

Belt Drive, Ball Guide, Short Carriage

» Ordering key - see page 189
» Accessories - see page 125
» Additional data - see page 172

General Specifications

Parameter	WM80Z
Profile size (w × h) [mm]	80 × 80
Type of belt	25 AT 10
Carriage sealing system	self-adjusting plastic cover band
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WM80Z
Stroke length (S max), maximum	[mm]	5500
Linear speed, maximum	[m/s]	5,0
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,05
Input speed, maximum	[rpm]	885
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	1470
Dynamic load (Fy), maximum	[N]	2100[1] / 37450[2]
Dynamic load (Fz), maximum	[N]	2100[1] / 35840[2]
Dynamic load torque (Mx), maximum	[Nm]	68[1] / 890[2]
Dynamic load torque (My), maximum	[Nm]	135[1] / 580[2]
Dynamic load torque (Mz), maximum	[Nm]	135[1] / 610[2]
Drive shaft force (Frd), maximum	[N]	600
Drive shaft torque (Mta), maximum	[Nm]	40
Pulley diameter	[mm]	54,11
Stroke per shaft revolution	[mm]	170
Weight	[kg]	
of unit with zero stroke		9,2
of every 100 mm of stroke		0,8
of each carriage		2,1

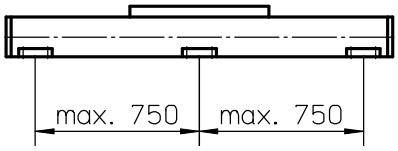
[1] Value for the complete unit, also see diagram Force Fx
[2] Value for the ball guide only

Carriage Idle Torque, (M idle) [Nm]

Input speed [rpm]	Idle torque [Nm]
150	4,0
450	5,4
885	6,2

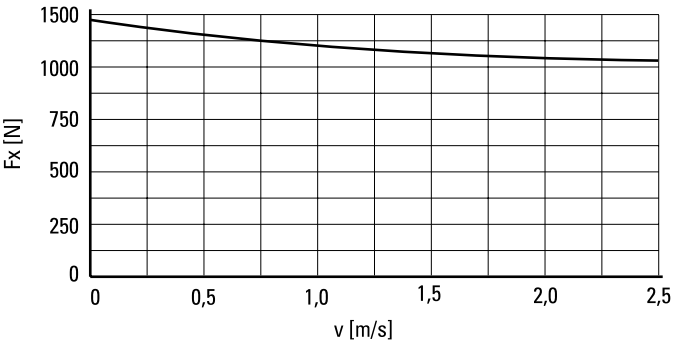
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

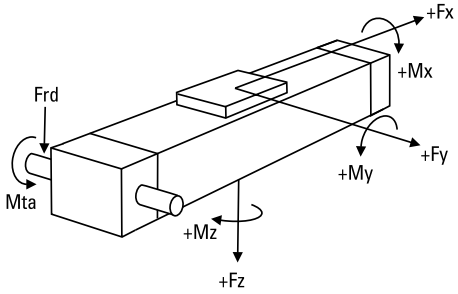


A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Force Fx as a Function of the Speed

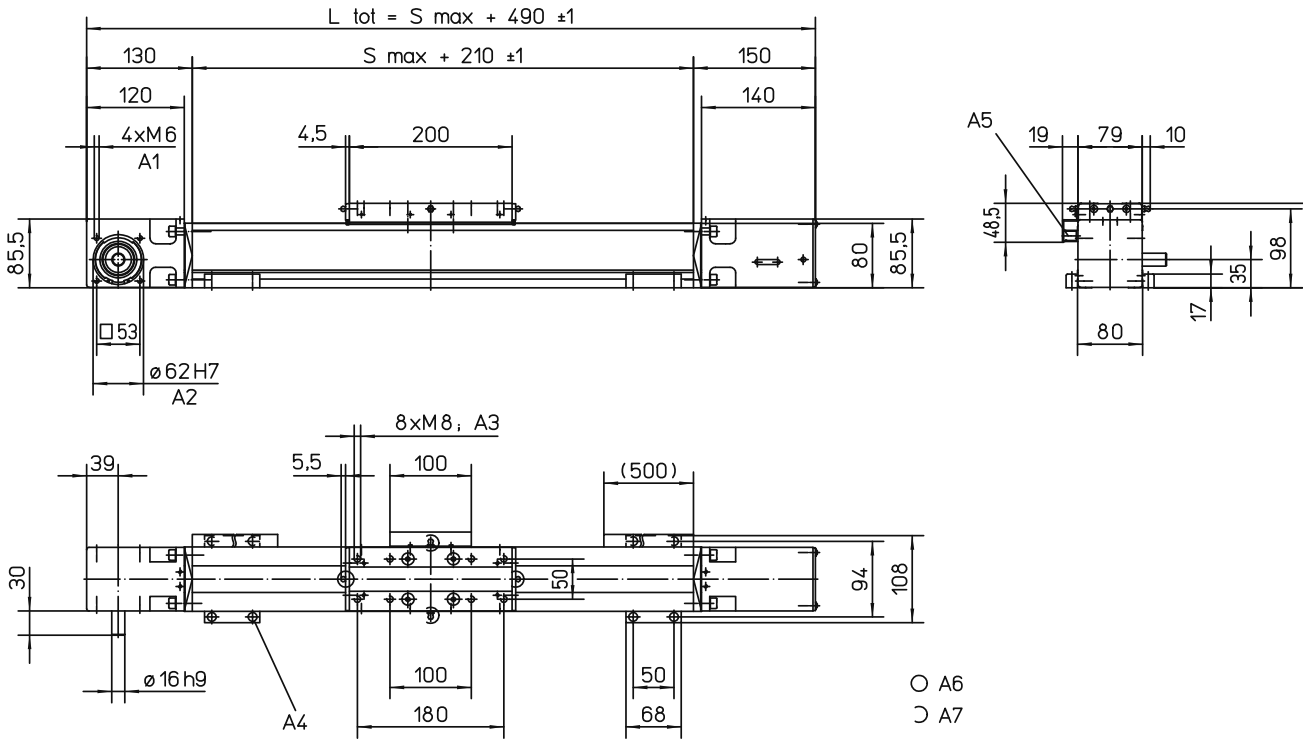


Definition of Forces



WM80Z

Belt Drive, Ball Guide, Short Carriage



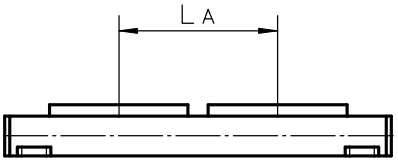
A1: depth 15
A2: depth 2,5
A3: depth 12
A4: socket cap screw ISO4762-M6×20 8.8

A5: ENF inductive sensor rail option kit (optional)
A6: tapered lubricating nipple to DIN71412 AM6 on fixed-bearing side as standard feature
A7: can be changed over to one of three alternative lubrications points by the customer

Double Short Carriages

Parameter		WM80Z
Minimum distance between carriages (L_A)	[mm]	280
Dynamic load (Fy), maximum	[N]	4200
Dynamic load (Fz), maximum	[N]	4200
Dynamic load torque (My), maximum	[Nm]	$L_{A^1} \times 2,1$
Dynamic load torque (Mz), maximum	[Nm]	$L_{A^1} \times 2,1$
Force required to move second carriage	[N]	22,5
Total length (L tot)	[mm]	S max + 490 + L_A

[1] Value in mm



M55

Belt Drive, Ball Guide

» Ordering key - see page 190
» Accessories - see page 125
» Additional data - see page 172

General Specifications

Parameter	M55
Profile size (w × h) [mm]	58 × 55
Type of belt	22-STD SM5-HP
Carriage sealing system	self-adjusting steel cover band
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	lubrication of ball guide carriages
Included accessories	none

Performance Specifications

Parameter		M55
Stroke length (S max), maximum	[mm]	7000
Linear speed, maximum	[m/s]	5,0
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,1
Input speed, maximum	[rpm]	2850
Operation temperature limits	[°C]	-20 – 70
Dynamic load (Fx), maximum < 2,5 m/s > 2,5 m/s	[N]	 400 200
Dynamic load (Fy), maximum	[N]	750[1] / 5435[2]
Dynamic load (Fz), maximum	[N]	750[1] / 6968[2]
Dynamic load torque (Mx), maximum	[Nm]	5[1] / 49[2]
Dynamic load torque (My), maximum	[Nm]	29[1] / 212[2]
Dynamic load torque (Mz), maximum	[Nm]	29[1] / 212[2]
Drive shaft force (Frd), maximum	[N]	200
Drive shaft torque (Mta), maximum	[Nm]	12
Pulley diameter	[mm]	33,42
Stroke per shaft revolution	[mm]	105
Weight of unit with zero stroke of every 100 mm of stroke of carriage	[kg]	 4,80 0,53 1,20

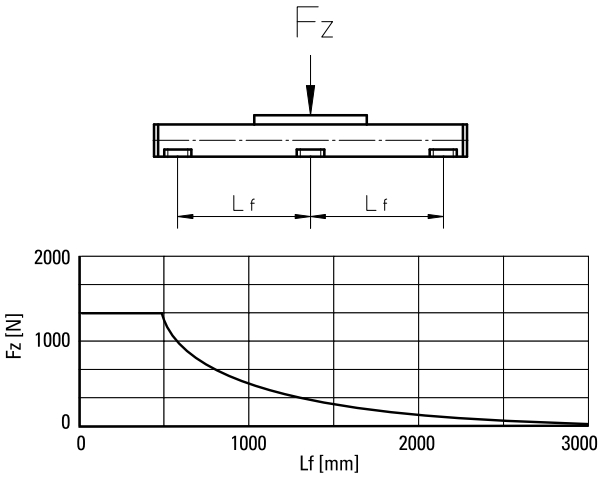
[1] Value for the complete unit
[2] Value for the ball guide only

Carriage Idle Torque (M idle) [Nm]

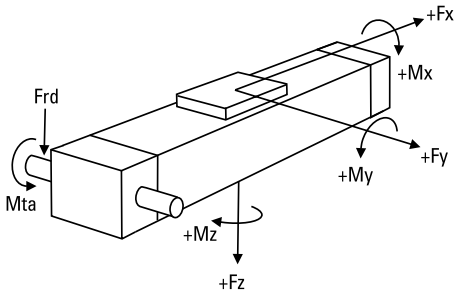
Input speed [rpm]	Single Carriage	Double Carriages
150	1,0	1,9

M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

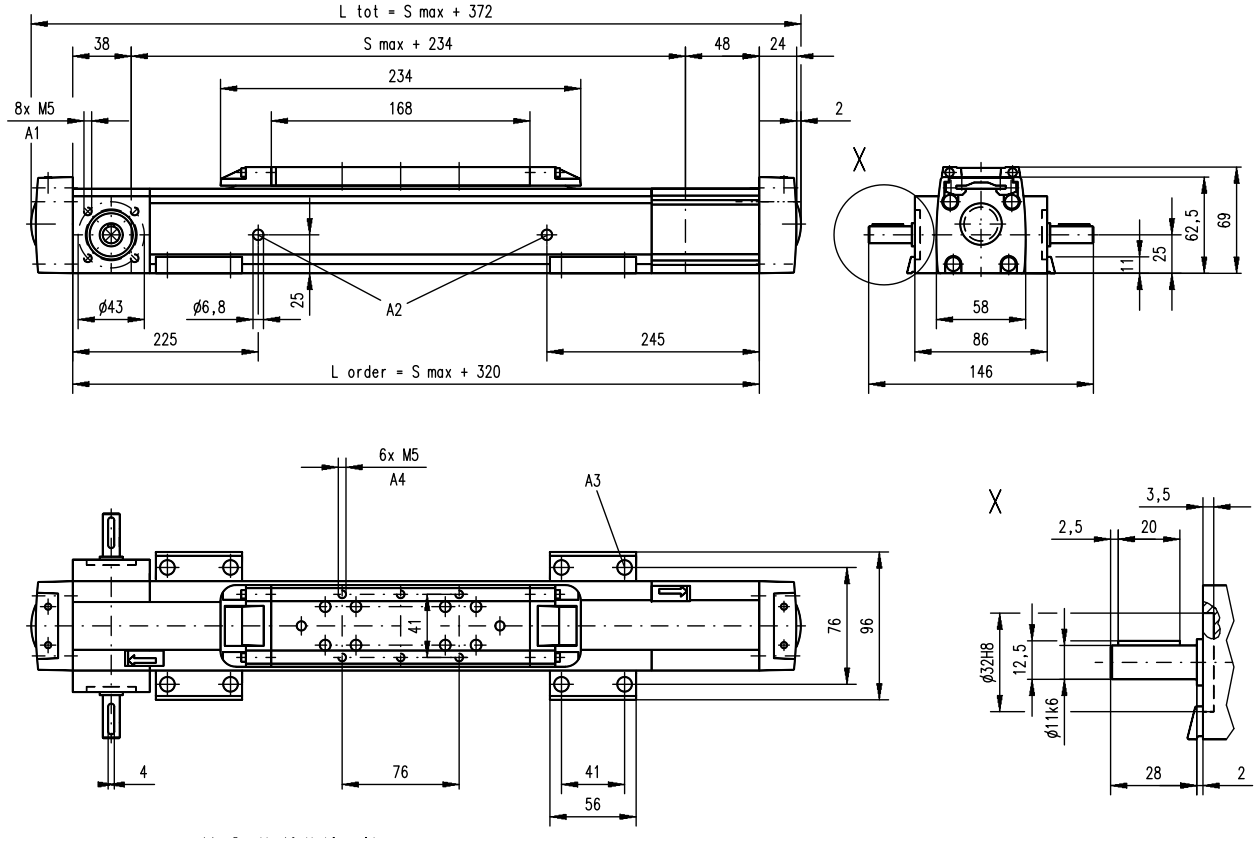


Definition of Forces



M55

Belt Drive, Ball Guide

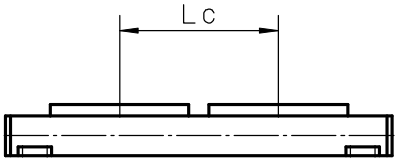


A1: depth 10, Heli coil
A2: lubrication holes
A3: ø9,5/ø5,5 for socket head cap screw M5
A4: depth 7,5 Heli coil

Double Carriages

Parameter		M55
Minimum distance between carriages (Lc)	[mm]	250
Dynamic load (Fy), maximum	[N]	1125
Dynamic load (Fz), maximum	[N]	1125
Dynamic load torque (My), maximum	[Nm]	Lc[1] × 0,56
Dynamic load torque (Mz), maximum	[Nm]	Lc[1] × 0,56
Force required to move second carriage	[N]	2
Ordering length (L order)	[mm]	S max + Lc + 320
Total length (L tot)	[mm]	L order + 52
Weight of unit with zero stroke of carriages	[kg]	 7,06 2,40

[1] Value in mm



M75

Belt Drive, Ball Guide

» Ordering key - see page 190
» Accessories - see page 125
» Additional data - see page 172

General Specifications

Parameter	M75
Profile size (w × h) [mm]	86 × 75
Type of belt	STD5-40
Carriage sealing system	self-adjusting steel cover band
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	lubrication of ball guide carriages
Included accessories	none

Performance Specifications

Parameter		M75
Stroke length (S max), maximum	[mm]	12000
Linear speed, maximum	[m/s]	5,0
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,1
Input speed, maximum	[rpm]	2300
Operation temperature limits	[°C]	-20 – 70
Dynamic load (Fx), maximum < 2,5 m/s > 2,5 m/s	[N]	 900 450
Dynamic load (Fy), maximum	[N]	1750[1] / 16413[2]
Dynamic load (Fz), maximum	[N]	1750[1] / 30968[2]
Dynamic load torque (Mx), maximum	[Nm]	16[1] / 150[2]
Dynamic load torque (My), maximum	[Nm]	84[1] / 743[2]
Dynamic load torque (Mz), maximum	[Nm]	84[1] / 787[2]
Drive shaft force (Frd), maximum	[N]	600
Drive shaft torque (Mta), maximum	[Nm]	30
Pulley diameter	[mm]	41,38
Stroke per shaft revolution	[mm]	130
Weight of unit with zero stroke of every 100 mm of stroke of carriage	[kg]	 7,50 0,88 2,00

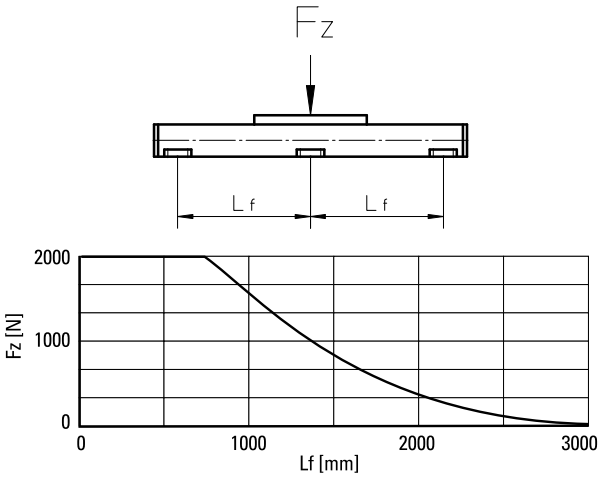
[1] Value for the complete unit
[2] Value for the ball guide only

Carriage Idle Torque (M idle) [Nm]

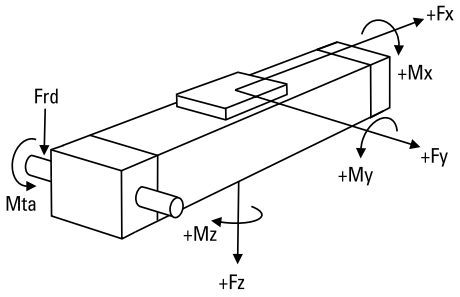
Input speed [rpm]	Single Carriage	Double Carriages
150	1,0	1,9

M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

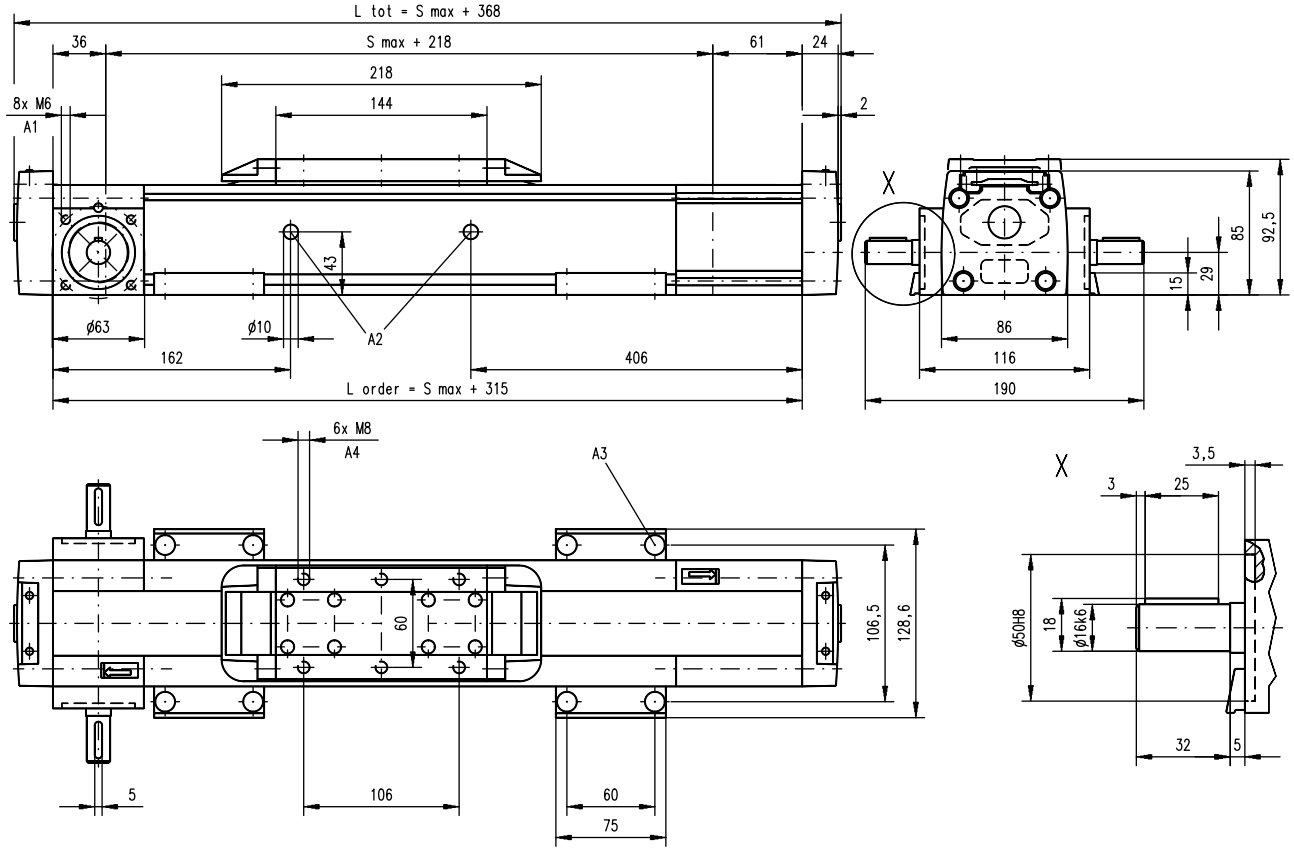


Definition of Forces



M75

Belt Drive, Ball Guide



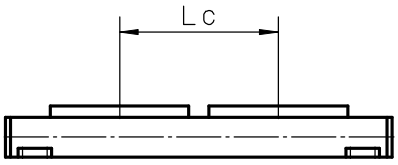
A1: depth 9, Heli coil
A2: lubrication holes

A3: ø13,5/ø8,5 for socket head cap screw M8
A4: depth 8, Heli coil

Double Carriages

Parameter		M75
Minimum distance between carriages (Lc)	[mm]	250
Dynamic load (Fy), maximum	[N]	2625
Dynamic load (Fz), maximum	[N]	2625
Dynamic load torque (My), maximum	[Nm]	Lc[1] × 1,313
Dynamic load torque (Mz), maximum	[Nm]	Lc[1] × 1,313
Force required to move second carriage	[N]	2
Ordering length (L order)	[mm]	S max + Lc + 315
Total length (L tot]	[mm]	L order + 52
Weight of unit with zero stroke of carriages	[kg]	 11,67 4,00

[1] Value in mm



M100

Belt Drive, Ball Guide

» Ordering key - see page 190
» Accessories - see page 125
» Additional data - see page 172

General Specifications

Parameter	M100
Profile size (w × h) [mm]	108 × 100
Type of belt	STD8-50
Carriage sealing system	self-adjusting steel cover band
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	lubrication of ball guide carriages
Included accessories	none

Performance Specifications

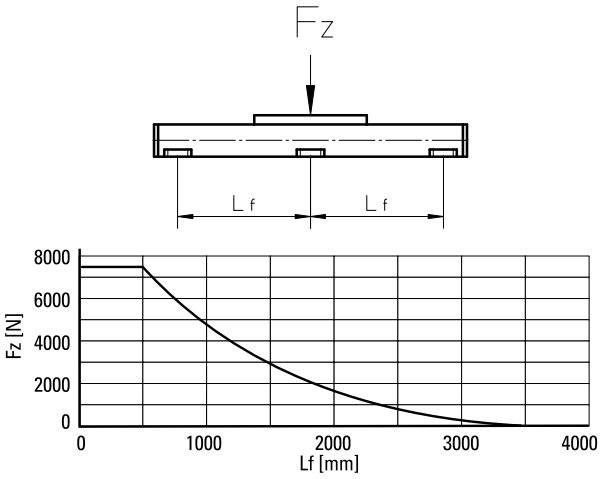
Parameter		M100
Stroke length (S max), maximum	[mm]	12000
Linear speed, maximum	[m/s]	5,0
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,1
Input speed, maximum	[rpm]	1700
Operation temperature limits	[°C]	-20 – 70
Dynamic load (Fx), maximum < 2,5 m/s > 2,5 m/s	[N]	 1250 625
Dynamic load (Fy), maximum	[N]	4000[1] / 26378[2]
Dynamic load (Fz), maximum	[N]	4000[1] / 49770[2]
Dynamic load torque (Mx), maximum	[Nm]	43[1] / 283[2]
Dynamic load torque (My), maximum	[Nm]	280[1] / 1742[2]
Dynamic load torque (Mz), maximum	[Nm]	280[1] / 1846[2]
Drive shaft force (Frd), maximum	[N]	1000
Drive shaft torque (Mta), maximum	[Nm]	45
Pulley diameter	[mm]	56,02
Stroke per shaft revolution	[mm]	176
Weight of unit with zero stroke of every 100 mm of stroke of carriage	[kg]	 11,61 1,43 2,20

Carriage Idle Torque (M idle) [Nm]

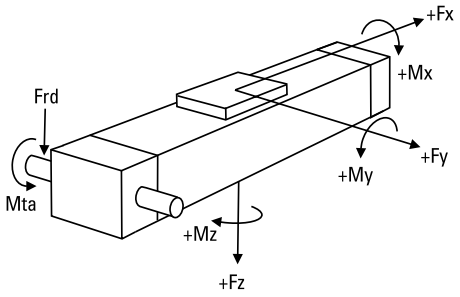
Input speed [rpm]	Single Carriage	Double Carriages
150	1,6	3,1

M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

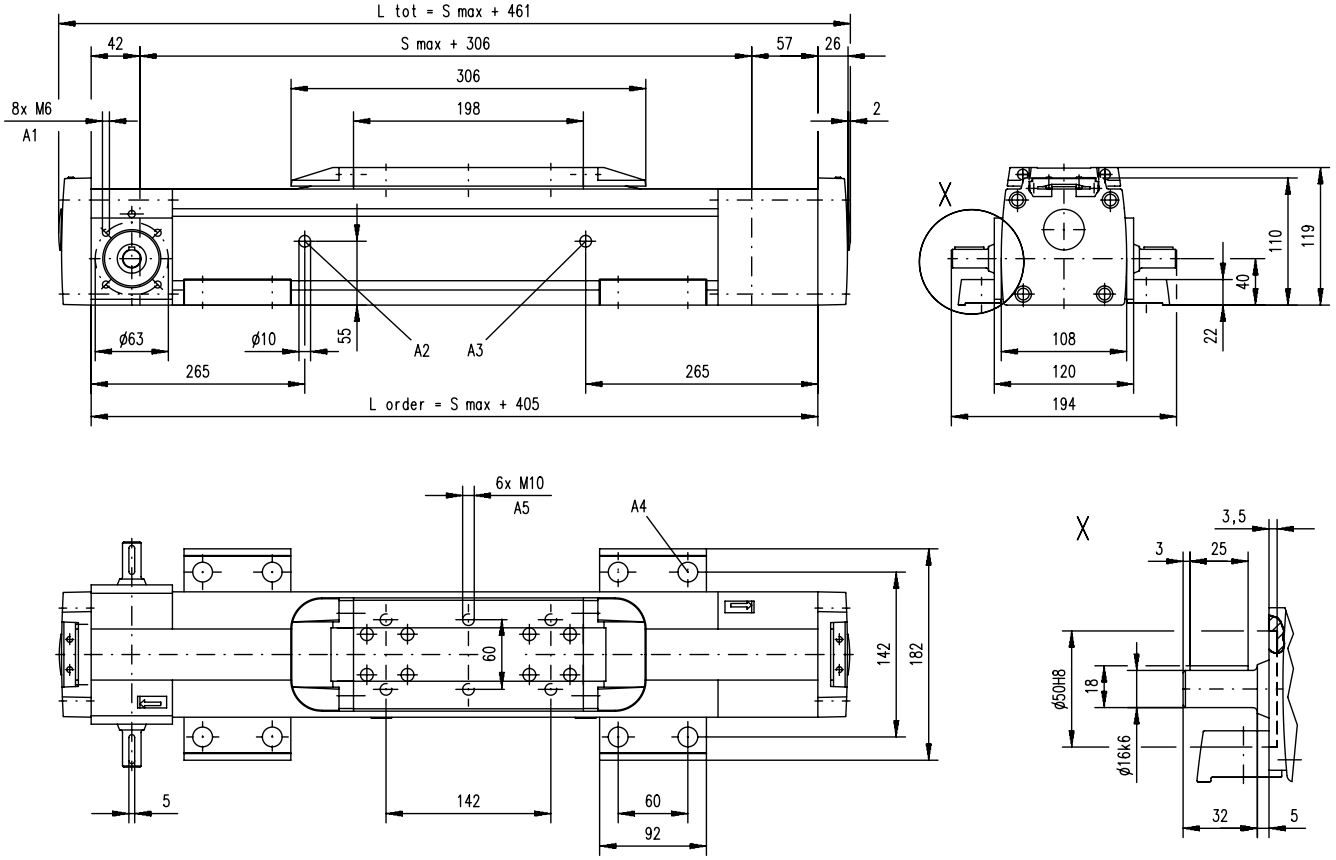


Definition of Forces



M100

Belt Drive, Ball Guide

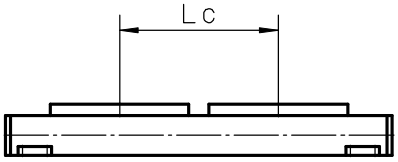


A1: depth 9, Heli coil
A2: lubrication hole
A3: lubrication hole (no hole if L order is < 856 mm)
A4: ø17/ø10,5 for socket head cap screw M10

Double Carriages

Parameter		M100
Minimum distance between carriages (Lc)	[mm]	350
Dynamic load (Fy), maximum	[N]	6000
Dynamic load (Fz), maximum	[N]	6000
Dynamic load torque (My), maximum	[Nm]	Lc[1] × 3
Dynamic load torque (Mz), maximum	[Nm]	Lc[1] × 3
Force required to move second carriage	[N]	2
Ordering length (L order)	[mm]	S max + Lc + 405
Total length (L tot)	[mm]	L order + 56
Weight of unit with zero stroke of carriagess	[kg]	 18,92 4,40

[1] Value in mm



MLSM80Z

Belt Drive, Ball Guide

» Ordering key - see page 191
» Accessories - see page 125
» Additional data - see page 172

General Specifications

Parameter	MLSM80Z
Profile size (w × h) [mm]	240 × 85
Type of belt	75 ATL 10
Carriage sealing system	plastic cover band
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		MLSM80Z
Stroke length (S max), maximum	[mm]	5900
Linear speed, maximum	[m/s]	5,0
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,05
Input speed, maximum	[rpm]	1500
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	5000[3]
Dynamic load (Fy), maximum	[N]	6400[1] / 71860[2]
Dynamic load (Fz), maximum	[N]	6400[1] / 71860[2]
Dynamic load torque (Mx), maximum	[Nm]	600[1] / 5890[2]
Dynamic load torque (My), maximum	[Nm]	720[1] / 6640[2]
Dynamic load torque (Mz), maximum	[Nm]	720[1] / 6640[2]
Drive shaft force (Frd), maximum	[N]	700
Drive shaft torque (Mta), maximum	[Nm]	150
Pulley diameter	[mm]	63,66
Stroke per shaft revolution	[mm]	200
Weight	[kg]	
of unit with zero stroke		30,8
of every 100 mm of stroke		2,2
of each carriage		9,6

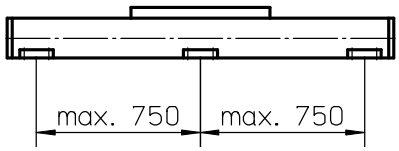
[1] Value for the complete unit
[2] Value for the ball guide only
[3] See diagram Force Fx

Carriage Idle Torque, (M idle) [Nm]

Input speed [rpm]	Idle torque [Nm]
150	8,5
750	12
1500	14,5

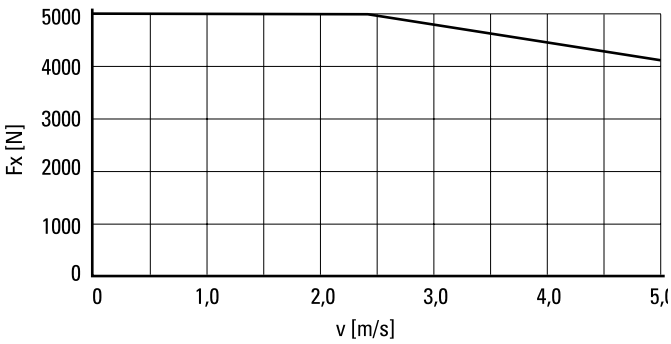
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

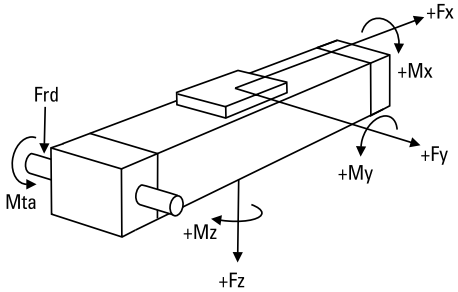


A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Force Fx as a Function of the Speed

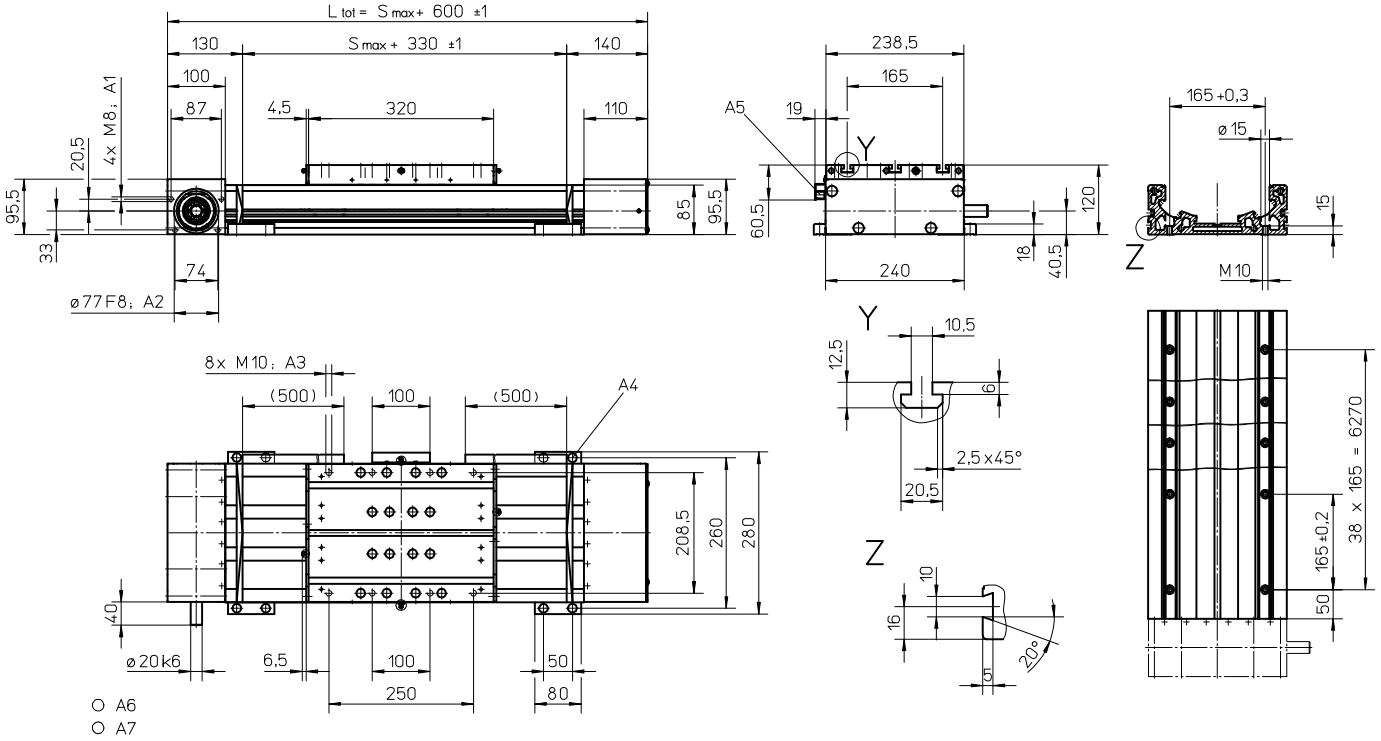


Definition of Forces



MLSM80Z

Belt Drive, Ball Guide

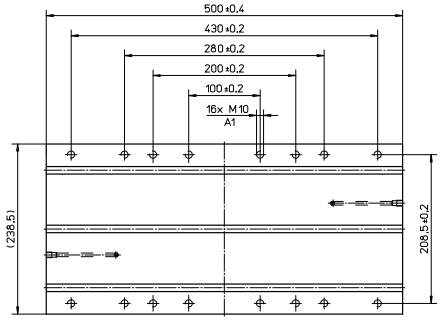


A1: depth 18
A2: depth 4
A3: depth 15
A4: socket cap screw ISO4762-M8×20 8.8

A5: ENF inductive sensor rail option kit (optional)
A6: tapered lubricating nipple to DIN71412 M8×1 on fixed-bearing side as standard feature
A7: can be changed over to one of the three alternative lubricating points by the customer

Long Carriage

Parameter		MLSM80Z
Carriage length	[mm]	500
Dynamic load torque (My), maximum	[Nm]	1400
Dynamic load torque (Mz), maximum	[Nm]	1400
Weight	[kg]	14

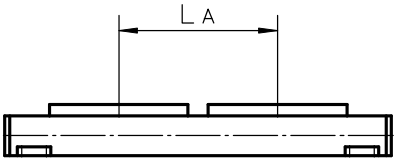


A1: depth 15

Double Carriages

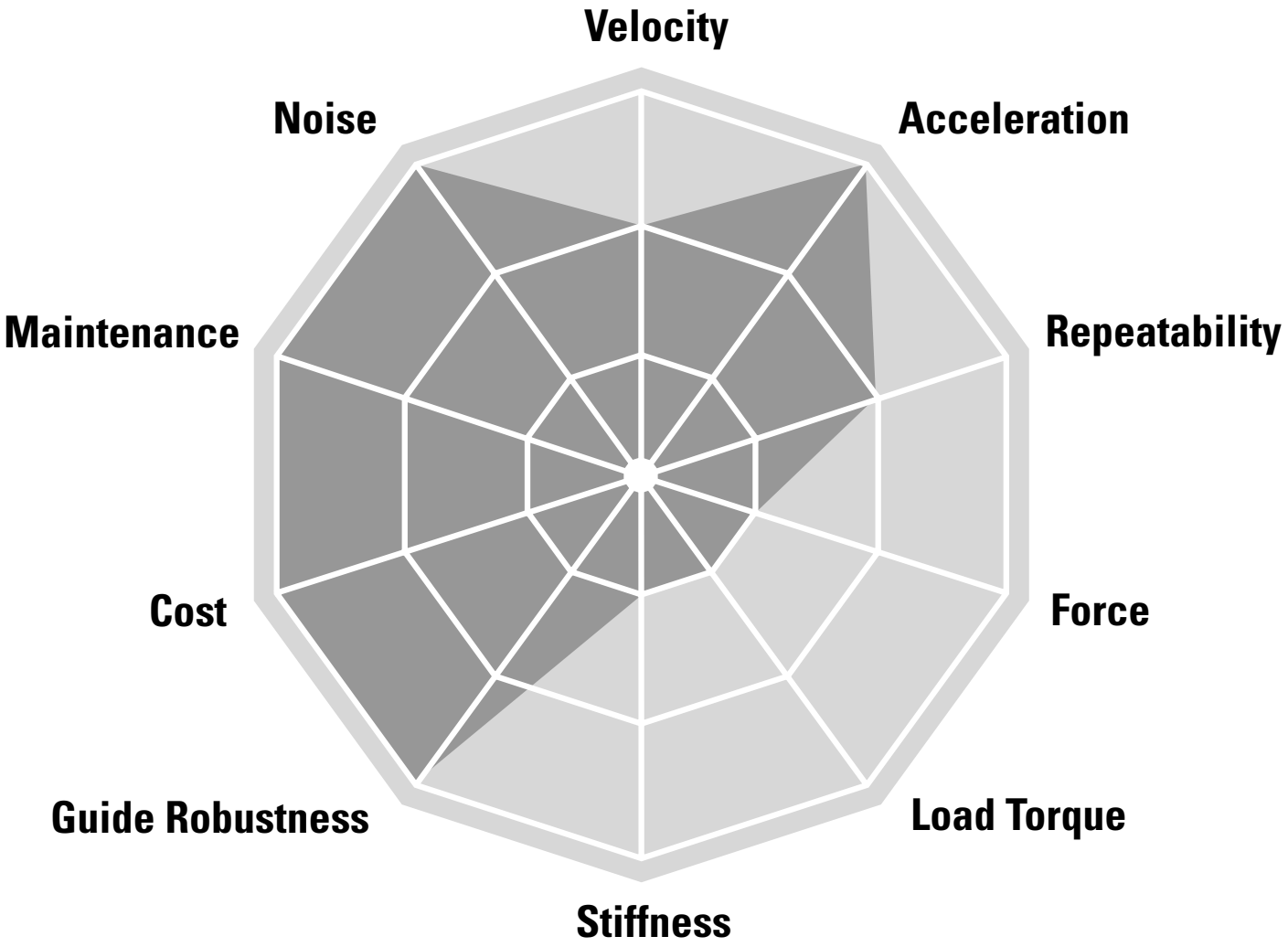
Parameter		MLSM80Z
Minimum distance between carriages (L_A)	[mm]	400
Dynamic load (Fy), maximum	[N]	12800
Dynamic load (Fz), maximum	[N]	12800
Dynamic load torque (My), maximum	[Nm]	$L_{A^1} \times 6,4$
Dynamic load torque (Mz), maximum	[Nm]	$L_{A^1} \times 6,4$
Force required to move second carriage	[N]	35
Total length (L tot)	[mm]	S max + 600 + L_A

[1] Value in mm



Linear Motion Systems with Belt Drive and Slide Guide

Movopart



Typical Applications

Typical applications are where low loads need to be moved at medium speed and high acceleration at low cost. These units are suited to harsh environments. Typical examples are for machines in the food, chemical, paper and wood working industry, in materials handling, cutting, scanning and printing applications.

Linear Motion Systems with Belt Drive and Slide Guide

Overview

Movopart M


M50

Features

- Can be installed in all directions
- Patented self-adjusting prism slide guides
- Resistant to shock loads and vibrations
- Low cost

Parameter		M50
Profile size (width × height)	[mm]	50 × 50
Stroke length (S max), maximum	[mm]	5000
Linear speed, maximum	[m/s]	5,0
Dynamic carriage load (Fz), maximum	[N]	400
Remarks		no cover band
Page		80

Movopart M


M100

Features

- Can be installed in all directions
- Self-adjusting stainless steel cover band
- Patented self-adjusting prism slide guides
- Wash down and chemical protected versions available

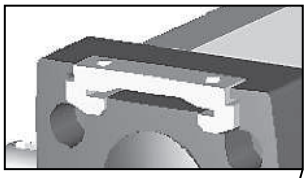
Parameter		M55	M75	M100
Profile size (width × height)	[mm]	58 × 55	86 × 75	108 × 100
Stroke length (S max), maximum	[mm]	7000	12000	12000
Linear speed, maximum	[m/s]	5,0	5,0	5,0
Dynamic carriage load (Fz), maximum	[N]	400	1485	3005
Remarks		-	-	-
Page		82	84	86

Linear Motion Systems with Belt Drive and Slide Guide

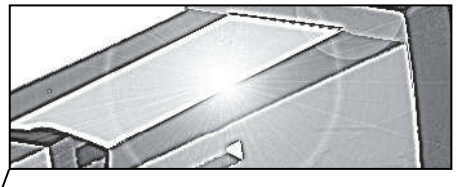
Overview

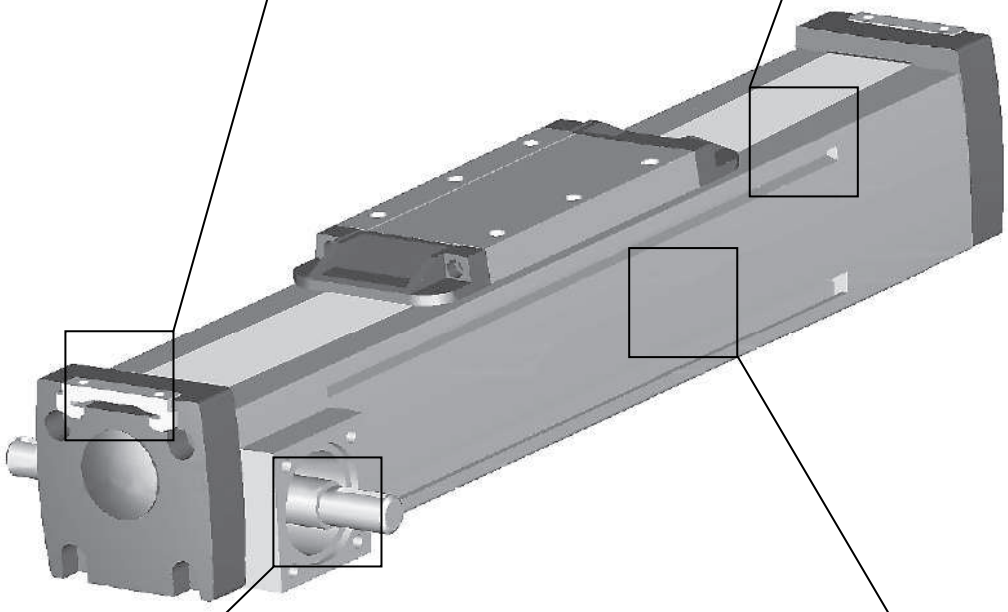
M-Series Technical Presentation

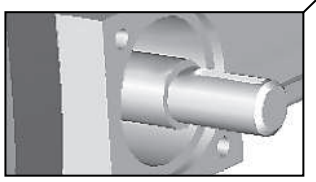
Cover band
The self-adjusting magnetically sealed stainless steel cover band protect the unit from the penetration of dirt, dust and liquids.



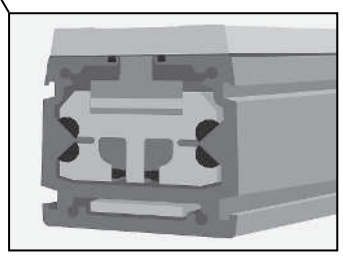
Environmental protection
The unit can as standard operate in harsh environments but is also available in wash down or chemically protected versions for the thoughest environments.







Belt drive
The belt runs on the inside of the profile and can easily be re-tensioned without removing the load from the carriage.



Prism slide guides
The patented self aligning prism slide guides are accurate, durable and are resistant to vibrations and shock loads.

M50

Belt Drive, Slide Guide

» Ordering key - see page 192
» Accessories - see page 125
» Additional data - see page 173

General Specifications

Parameter	M50
Profile size (w × h) [mm]	50 × 50
Type of belt	GT 5MR-19
Carriage sealing system	none
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	lubricated for life
Included accessories	none

Performance Specifications

Parameter		M50
Stroke length (S max), maximum	[mm]	5000
Linear speed, maximum	[m/s]	5,0
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,2
Input speed, maximum	[rpm]	2300
Operation temperature limits	[°C]	-20 – 70
Dynamic load (Fx), maximum < 2,5 m/s > 2,5 m/s	[N]	 400 200
Dynamic load (Fy), maximum	[N]	400[1]
Dynamic load (Fz), maximum	[N]	400[1]
Dynamic load torque (Mx), maximum	[Nm]	5[1]
Dynamic load torque (My), maximum	[Nm]	21[1]
Dynamic load torque (Mz), maximum	[Nm]	21[1]
Drive shaft force (Frd), maximum	[N]	350
Drive shaft torque (Mta), maximum	[Nm]	10
Pulley diameter	[mm]	41,38
Stroke per shaft revolution	[mm]	130
Weight of unit with zero stroke of every 100 mm of stroke of carriage	[kg]	 0,71 0,96 0,33

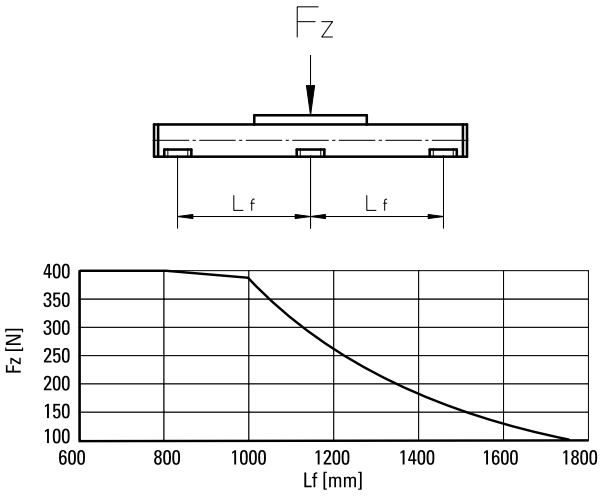
[1] Value for the complete unit

Carriage Idle Torque (M idle) [Nm]

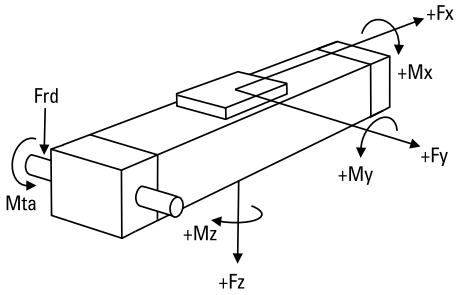
Input speed [rpm]	Idle torque [Nm]
150	2,1

M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

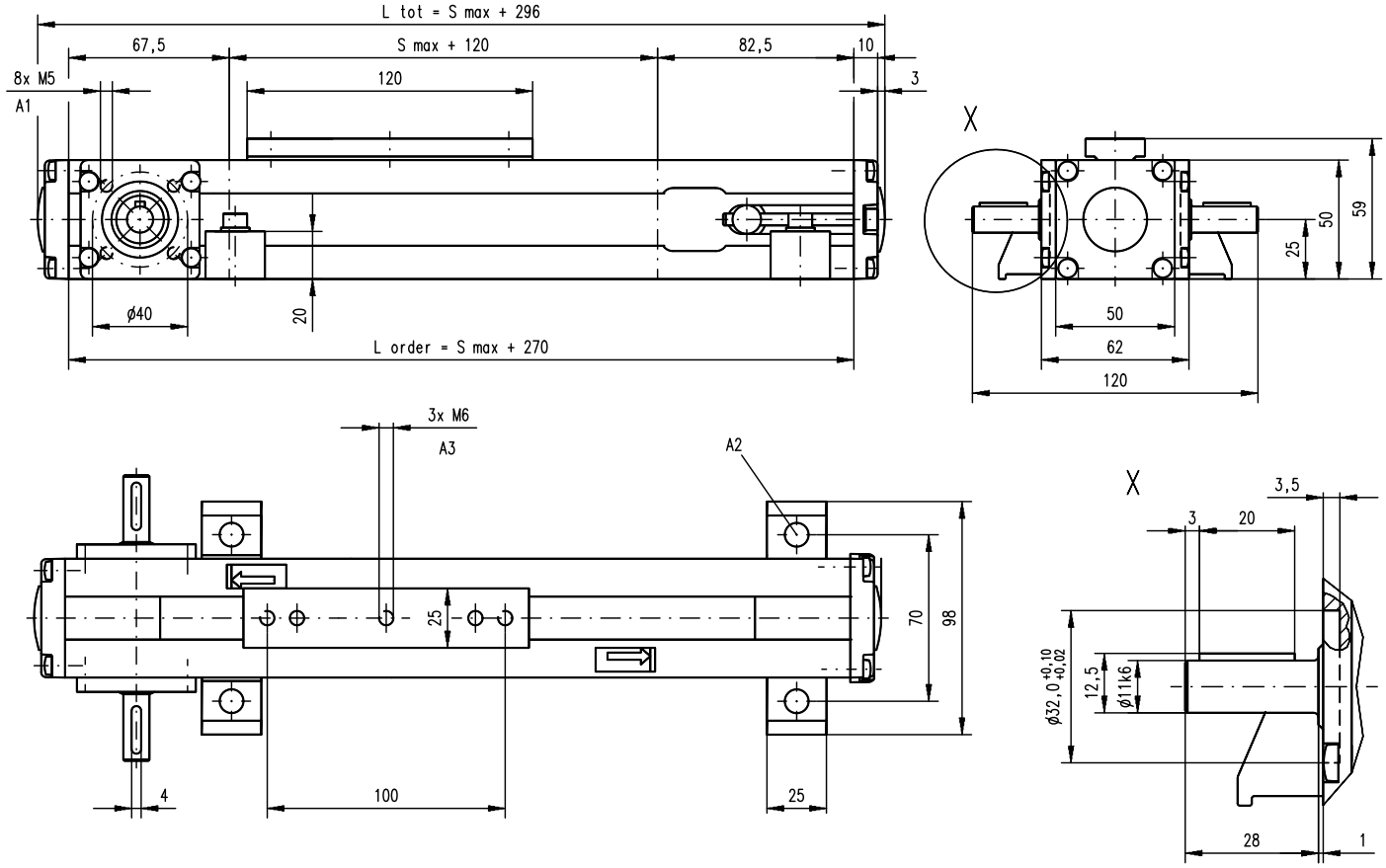


Definition of Forces



M50

Belt Drive, Slide Guide



A1: depth 8,5
A2: ø6,5 for M6 screw
A3: depth 9, Heli coil

M55

Belt Drive, Slide Guide

» Ordering key - see page 192
» Accessories - see page 125
» Additional data - see page 173

General Specifications

Parameter	M55
Profile size (w × h) [mm]	58 × 50
Type of belt	22-STD SM5-HP
Carriage sealing system	self-adjusting steel cover band
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	lubricated for life
Included accessories	none

Performance Specifications

Parameter		M55
Stroke length (S max), maximum	[mm]	7000
Linear speed, maximum	[m/s]	5,0
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,2
Input speed, maximum	[rpm]	2850
Operation temperature limits	[°C]	-20 – 70
Dynamic load (Fx), maximum < 2,5 m/s > 2,5 m/s	[N]	 400 200
Dynamic load (Fy), maximum	[N]	400[1]
Dynamic load (Fz), maximum	[N]	400[1]
Dynamic load torque (Mx), maximum	[Nm]	9[1]
Dynamic load torque (My), maximum	[Nm]	21[1]
Dynamic load torque (Mz), maximum	[Nm]	21[1]
Drive shaft force (Frd), maximum	[N]	200
Drive shaft torque (Mta), maximum	[Nm]	7
Pulley diameter	[mm]	33,42
Stroke per shaft revolution	[mm]	105
Weight of unit with zero stroke of every 100 mm of stroke of carriage	[kg]	 4,10 0,41 1,10

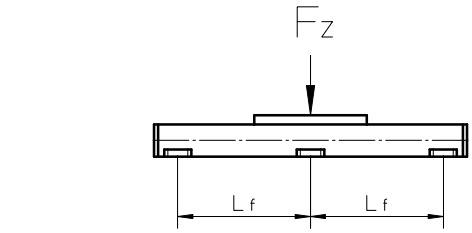
[1] Value for the complete unit

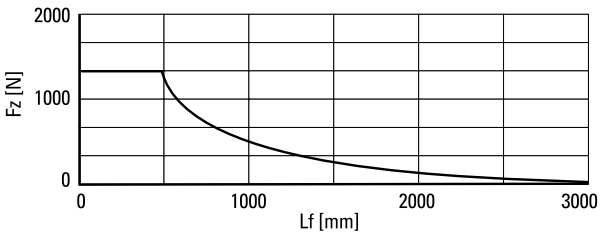
Carriage Idle Torque (M idle) [Nm]

Input speed [rpm]	Single Carriage	Double Carriages
150	2,1	3,8

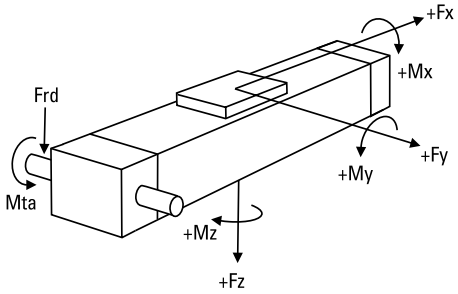
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile



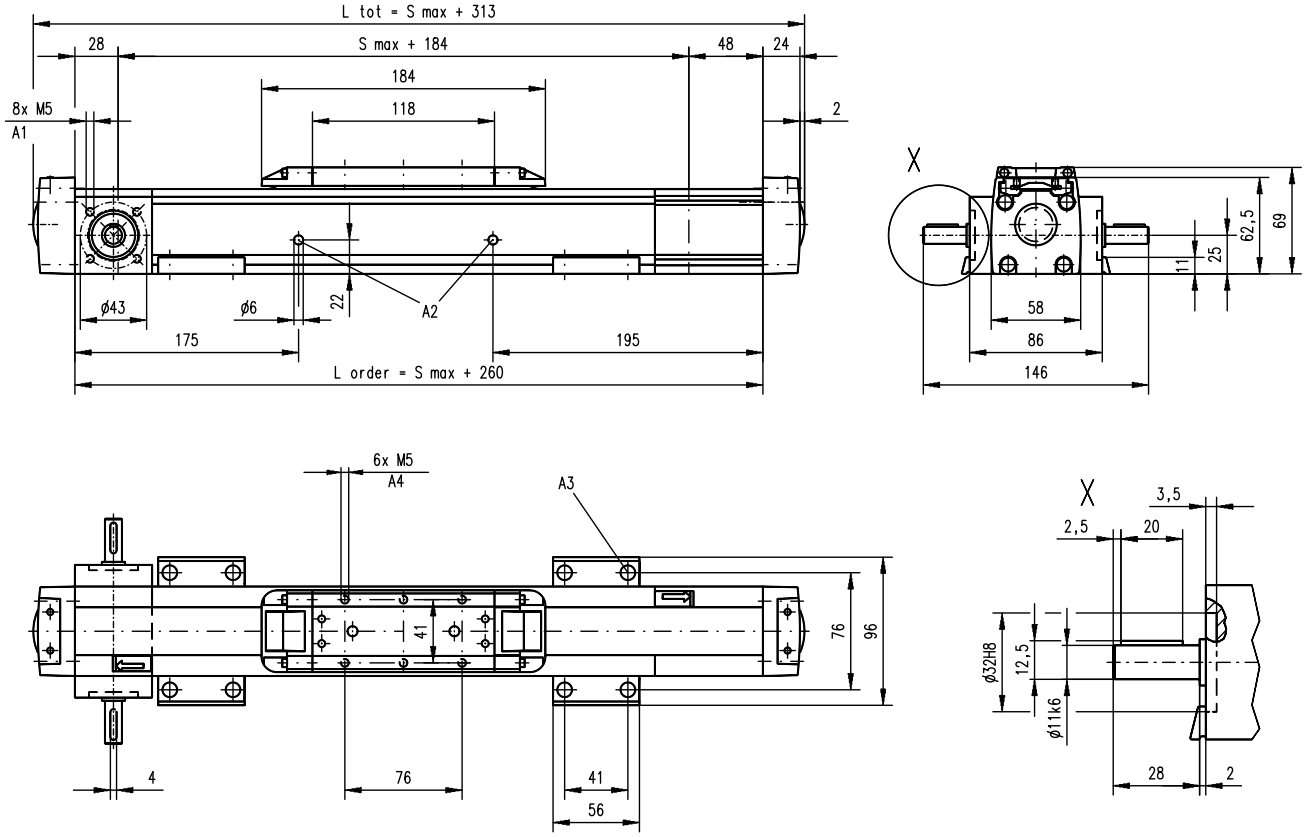


Definition of Forces



M55

Belt Drive, Slide Guide

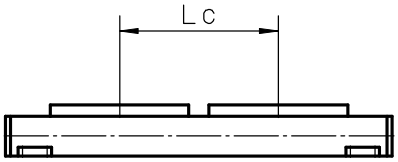


A1: depth 10, Heli coil
A2: lubrication holes
A3: ø9,5/ø5,5 for socket head cap screw M5
A4: depth 7,5, Heli coil

Double Carriages

Parameter		M55
Minimum distance between carriages (Lc)	[mm]	200
Dynamic load (Fy), maximum	[N]	600
Dynamic load (Fz), maximum	[N]	600
Dynamic load torque (My), maximum	[Nm]	Lc[1] × 0,3
Dynamic load torque (Mz), maximum	[Nm]	Lc[1] × 0,3
Force required to move second carriage	[N]	35
Ordering length (L order)	[mm]	S max + Lc + 260
Total length (L tot)	[mm]	L order + 53
Weight of unit with zero stroke of carriages	[kg]	 6,00 2,20

[1] Value in mm



M75

Belt Drive, Slide Guide

» Ordering key - see page 192
» Accessories - see page 125
» Additional data - see page 173

General Specifications

Parameter	M75
Profile size (w × h) [mm]	86 × 75
Type of belt	STD5-40
Carriage sealing system	self-adjusting steel cover band
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	lubricated for life
Included accessories	none

Performance Specifications

Parameter		M75
Stroke length (S max), maximum	[mm]	12000
Linear speed, maximum	[m/s]	5,0
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,2
Input speed, maximum	[rpm]	2300
Operation temperature limits	[°C]	-20 – 70
Dynamic load (Fx), maximum < 2,5 m/s > 2,5 m/s	[N]	 900 450
Dynamic load (Fy), maximum	[N]	1485[1]
Dynamic load (Fz), maximum	[N]	1485[1]
Dynamic load torque (Mx), maximum	[Nm]	49[1]
Dynamic load torque (My), maximum	[Nm]	85[1]
Dynamic load torque (Mz), maximum	[Nm]	85[1]
Drive shaft force (Frd), maximum	[N]	600
Drive shaft torque (Mta), maximum	[Nm]	30
Pulley diameter	[mm]	41,38
Stroke per shaft revolution	[mm]	130
Weight of unit with zero stroke of every 100 mm of stroke of carriage	[kg]	 6,30 0,67 1,50

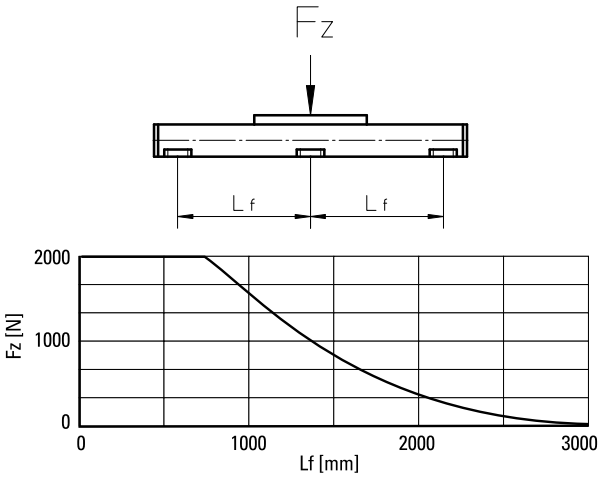
[1] Value for the complete unit

Carriage Idle Torque (M idle) [Nm]

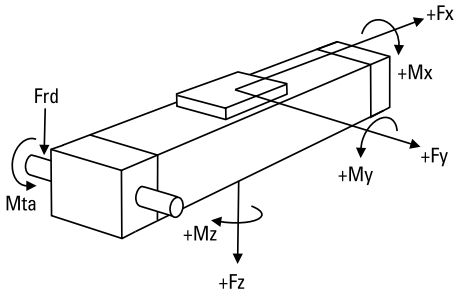
Input speed [rpm]	Single Carriage	Double Carriages
150	2,2	4,0

M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

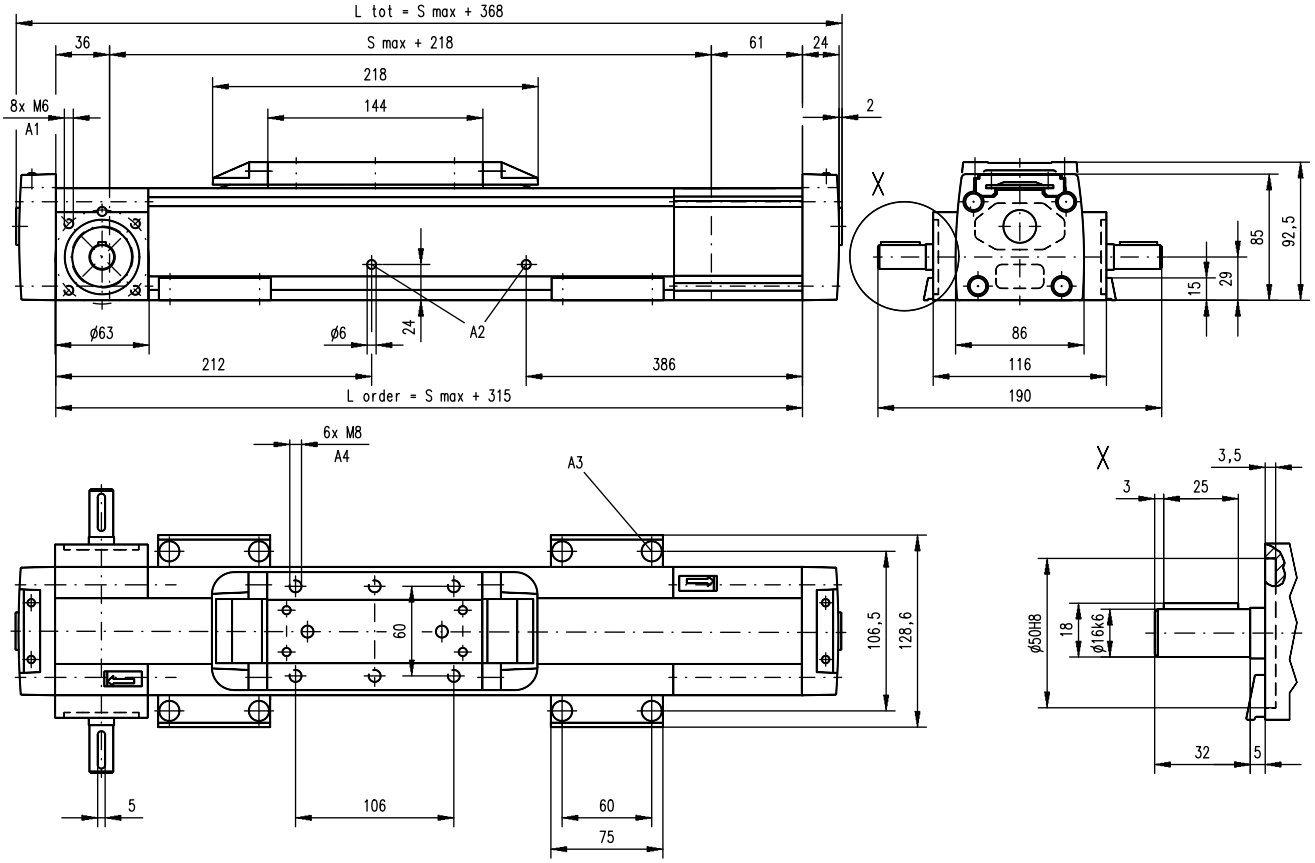


Definition of Forces



M75

Belt Drive, Slide Guide

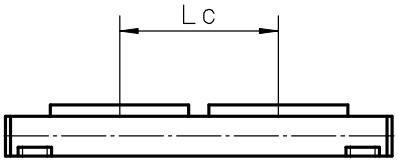


A1: depth 9, Heli coil
A2: lubrication holes
A3: ø13,5/ø8,5 for socket head cap screw M8
A4: depth 8, Heli coil

Double Carriages

Parameter		M75
Minimum distance between carriages (Lc)	[mm]	250
Dynamic load (Fy), maximum	[N]	2227
Dynamic load (Fz), maximum	[N]	2227
Dynamic load torque (My), maximum	[Nm]	Lc[1] × 1,114
Dynamic load torque (Mz), maximum	[Nm]	Lc[1] × 1,114
Force required to move second carriage	[N]	40
Ordering length (L order)	[mm]	S max + Lc + 315
Total length (L tot]	[mm]	L order + 53
Weight of unit with zero stroke of carriages	[kg]	 9,50 3,00

[1] Value in mm



M100

Belt Drive, Slide Guide

» Ordering key - see page 192
» Accessories - see page 125
» Additional data - see page 173

General Specifications

Parameter	M100
Profile size (w × h) [mm]	108 × 100
Type of belt	STD8-50
Carriage sealing system	self-adjusting steel cover band
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	lubricated for life
Included accessories	none

Performance Specifications

Parameter		M100
Stroke length (S max), maximum	[mm]	12000
Linear speed, maximum	[m/s]	5,0
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,2
Input speed, maximum	[rpm]	1700
Operation temperature limits	[°C]	-20 – 70
Dynamic load (Fx), maximum < 2,5 m/s > 2,5 m/s	[N]	 1250 625
Dynamic load (Fy), maximum	[N]	3005[1]
Dynamic load (Fz), maximum	[N]	3005[1]
Dynamic load torque (Mx), maximum	[Nm]	117[1]
Dynamic load torque (My), maximum	[Nm]	279[1]
Dynamic load torque (Mz), maximum	[Nm]	279[1]
Drive shaft force (Frd), maximum	[N]	1000
Drive shaft torque (Mta), maximum	[Nm]	45
Pulley diameter	[mm]	56,02
Stroke per shaft revolution	[mm]	176
Weight of unit with zero stroke of every 100 mm of stroke of carriage	[kg]	 11,10 1,16 2,40

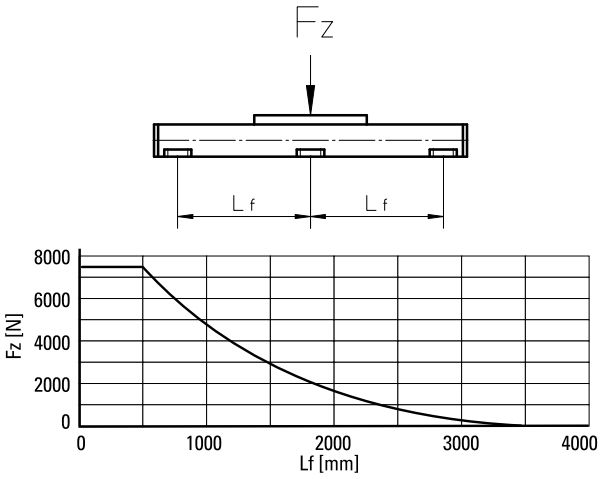
[1] Value for the complete unit

Carriage Idle Torque (M idle) [Nm]

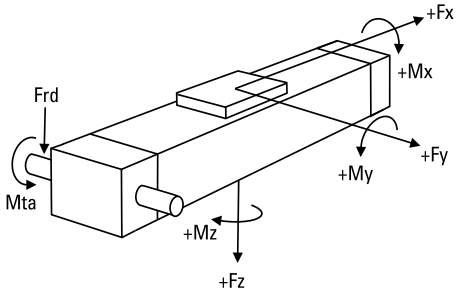
Input speed [rpm]	Single Carriage	Double Carriages
150	3,8	5,8

M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

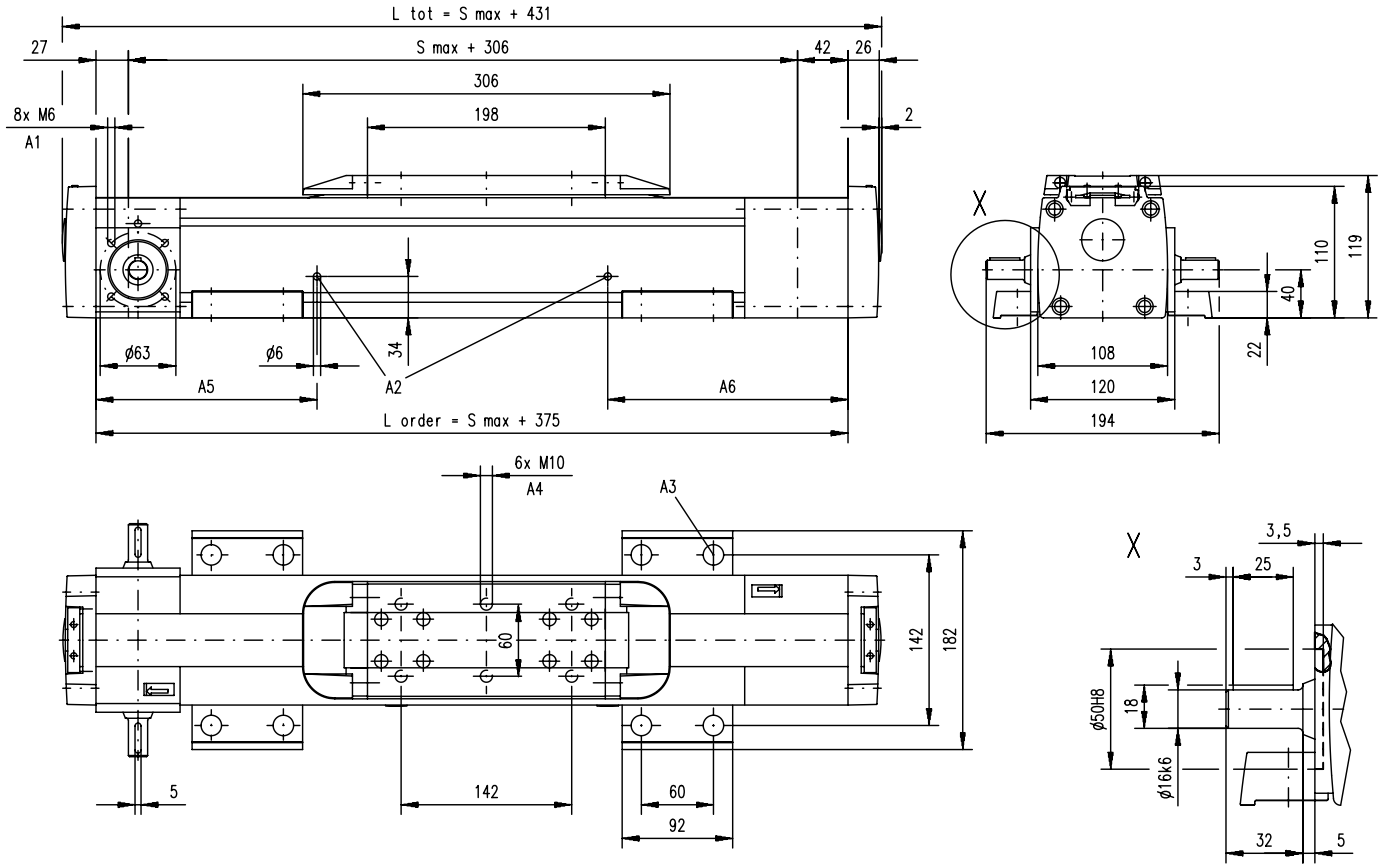


Definition of Forces



M100

Belt Drive, Slide Guide

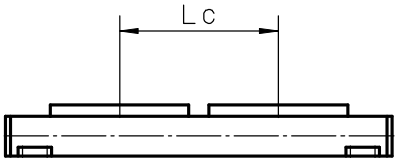


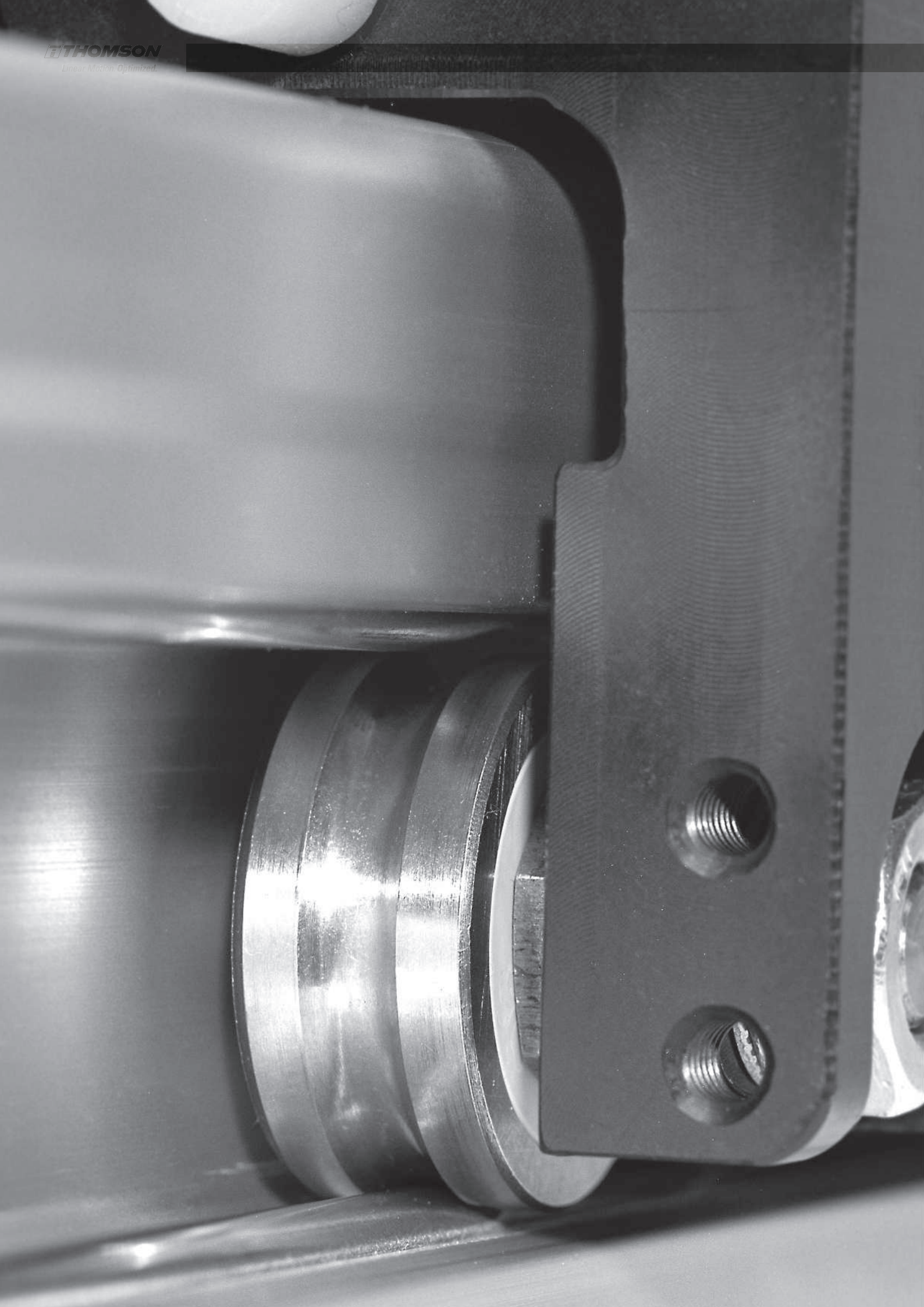
A1: Depth 9, Heli coil
A2: lubrication holes
A3: ø17/ø10,5 for socket head cap screw M10
A4: depth 10, Heli coil
A5: 170 (L order <= 1 m), 270 (L order > 1 m)
A6: 186 (L order < = 1 m), 436 (L order > 1 m)

Double Carriages

Parameter		M100
Minimum distance between carriages (Lc)	[mm]	350
Dynamic load (Fy), maximum	[N]	4508
Dynamic load (Fz), maximum	[N]	4508
Dynamic load torque (My), maximum	[Nm]	Lc[1] × 2,254
Dynamic load torque (Mz), maximum	[Nm]	Lc[1] × 2,254
Force required to move second carriage	[N]	45
Ordering length (L order)	[mm]	S max + Lc + 375
Total length (L tot]	[mm]	L order + 56
Weight of unit with zero stroke of carriages	[kg]	 17,40 4,80

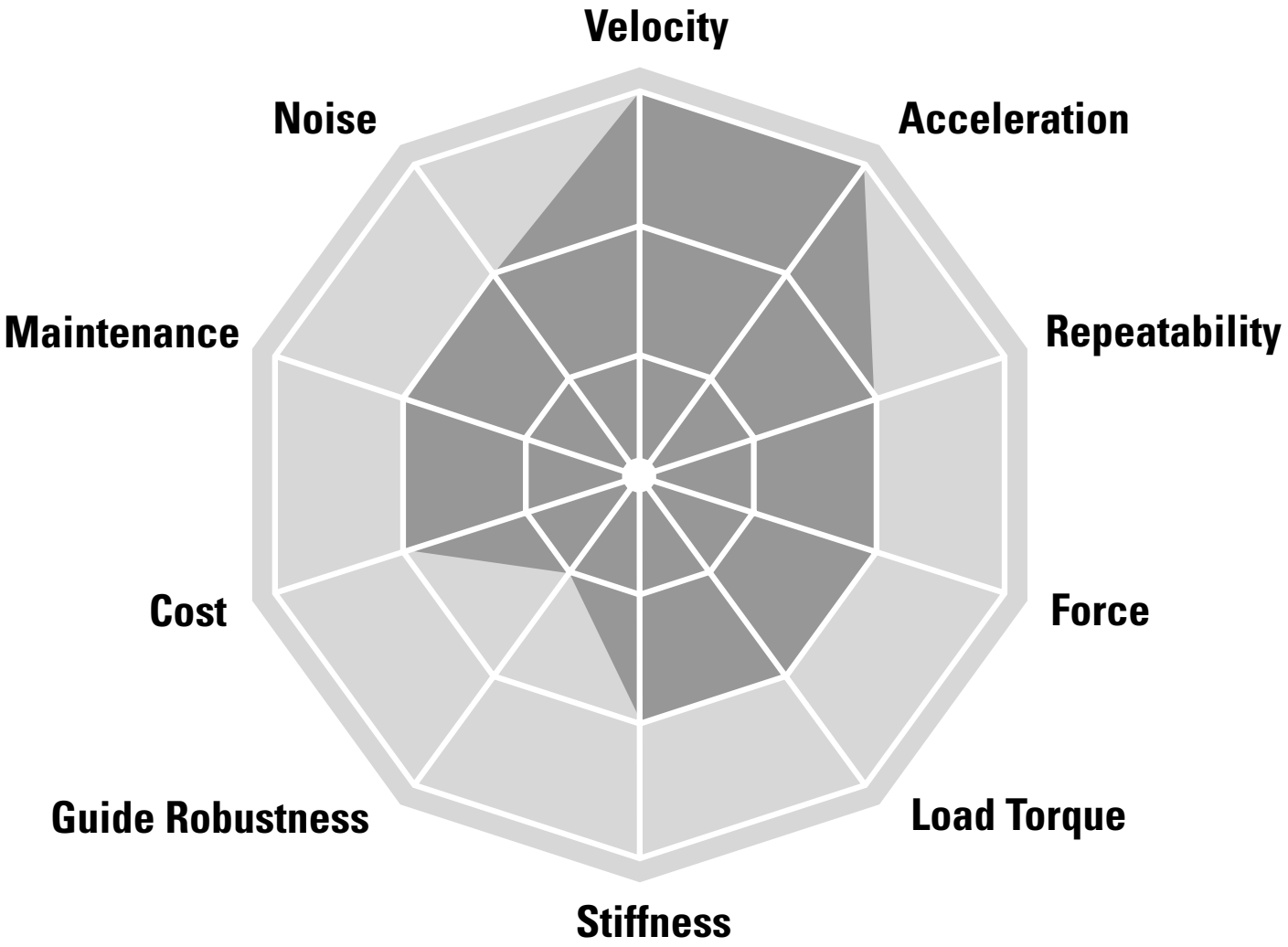
[1] Value in mm





Linear Units with Belt Drive and Wheel Guide

SpeedLine, ForceLine



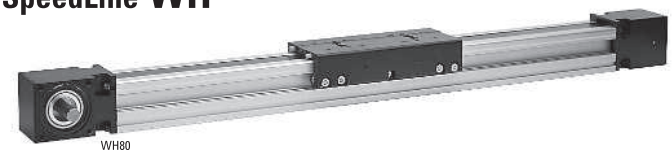
Typical Applications

Typical applications are where low to medium loads needs to be moved at high speed and acceleration. Typical examples are in packaging, cutting, pick and place and materials handling applications where the cycle times are critical.

Linear Units with Belt Drive and Wheel Guide

Overview

SpeedLine WH


WH80

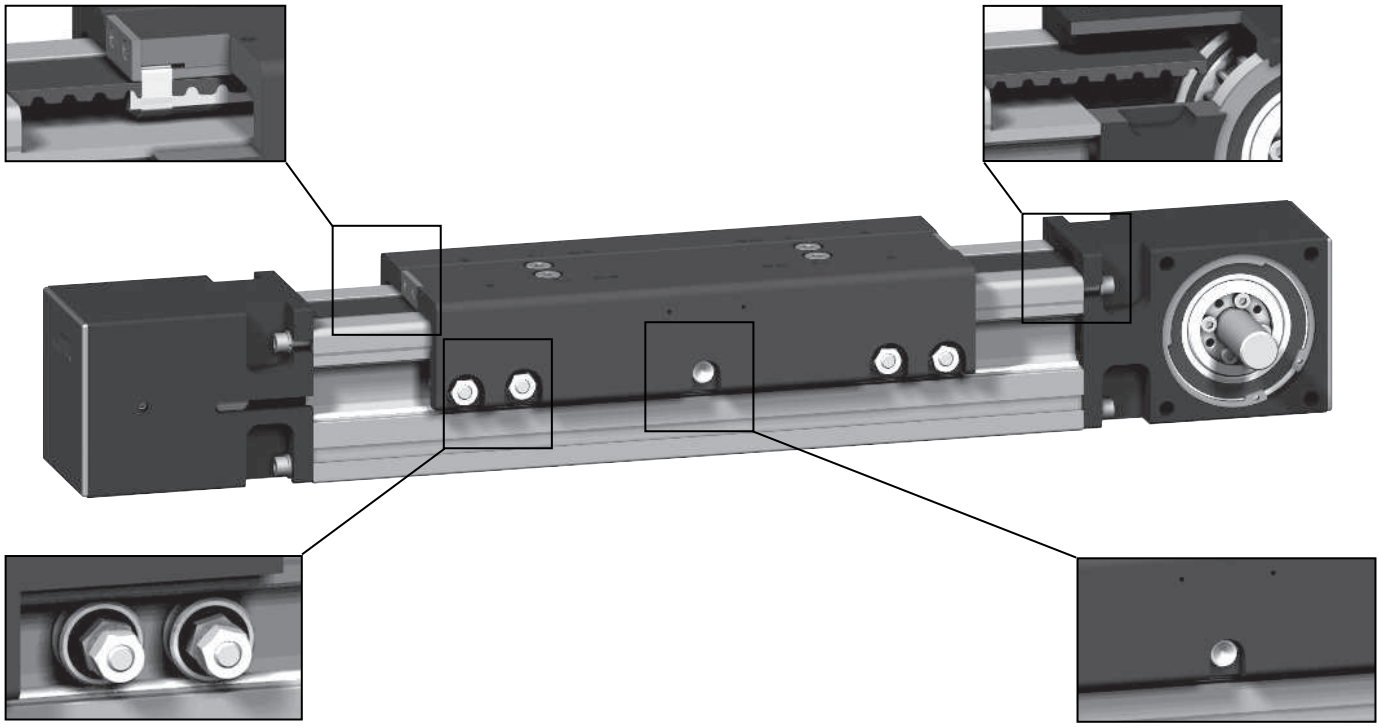
Features
- Can be installed in all directions
- Speed up to 11 m/s
- Acceleration up to 40 m/s^2
- Stroke up to 11 m

Parameter		WH50	WH80	WH120
Profile size (width × height)	[mm]	50 × 50	80 × 80	120 × 110
Stroke length (S max), maximum	[mm]	3000	11000	11000
Linear speed, maximum	[m/s]	6,5	10,0	10,0
Dynamic carriage load (Fz), maximum	[N]	730	2100	9300
Remarks		external wheel guides no cover band	external wheel guides no cover band	external wheel guides no cover band
Page		92	94	96

WH-Series Technical Presentation

Belt tensioning
The belt can easily be replaced or re-tensioned from the outside of the unit without the load being removed from the carriage.

Belt drive
The steel reinforced belt is wear resistant, highly efficient and very accurate even at high speeds and loads.



Wheel guides
The H-type arrangement of the guides allows fast moves and high forces and moments.

Central lubrication
The guides are lubricated from a central point that are easy and fast to access.

Linear Units with Belt Drive and Wheel Guide

Overview

ForceLine **MLSH**

MLSH60Z

Features

- Can be installed in all directions
- Patented plastic cover band
- Speed up to 10 m/s
- Low profile height

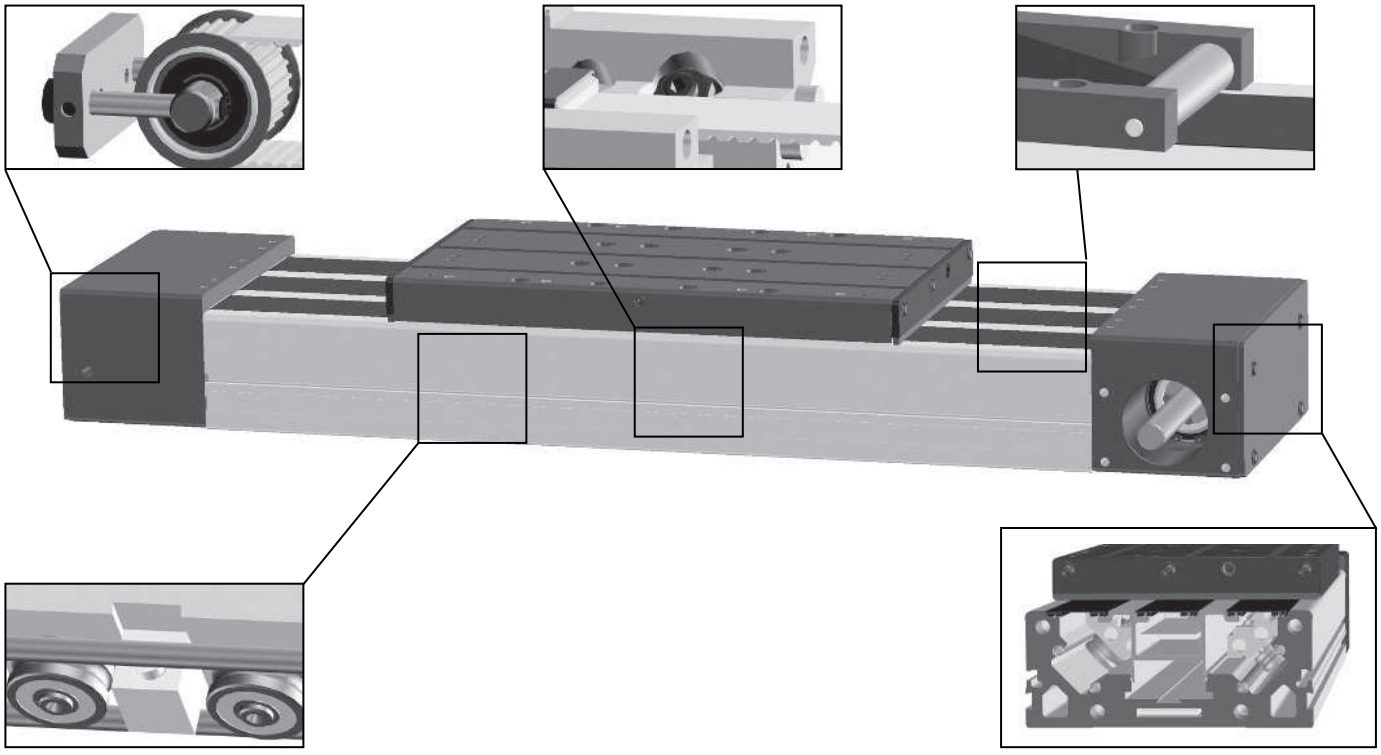
Parameter		MLSH60Z	MLSH80Z
Profile size (width × height)	[mm]	160 × 65	240 × 85
Stroke length (S max), maximum	[mm]	5500	5900
Linear speed, maximum	[m/s]	10,0	10,0
Dynamic carriage load (Fz), maximum	[N]	3000	5000
Remarks		internal wheel guides	internal wheel guides
Page		98	100

MLSH-Series Technical Presentation

Belt tensioning
The belt can easily be re-tensioned from the outside of the unit without the load being removed from the carriage.

Belt drive
The highly dynamic and accurate belt is protected by the cover band ensuring long and trouble free operation.

Cover band
The patented self-adjusting cover band protect the interior of the unit from the penetration of dirt, dust and liquids.



Wheel guides
The robust wheel guides runs inside of the profile providing superior motion dynamics.

Unique profile
The unique design of the profile guarantees the highest performance and protection of the guides and belt.

WH50

Belt Drive, Wheel Guide

» Ordering key - see page 193
» Accessories - see page 125
» Additional data - see page 173

General Specifications

Parameter	WH50
Profile size (w × h) [mm]	50 × 50
Type of belt	16ATL5
Carriage sealing system	none
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	lubrication og guiding surfaces
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WH50
Stroke length (S max), maximum	[mm]	3000
Linear speed, maximum	[m/s]	6,5
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,05
Input speed, maximum	[rpm]	3250
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	670[3]
Dynamic load (Fy), maximum	[N]	415[1] / 2820[2]
Dynamic load (Fz), maximum	[N]	730[1] / 5080[2]
Dynamic load torque (Mx), maximum	[Nm]	16[1] / 99[2]
Dynamic load torque (My), maximum	[Nm]	87[1] / 500[2]
Dynamic load torque (Mz), maximum	[Nm]	50[1] / 280[2]
Drive shaft force (Frd), maximum	[N]	150
Drive shaft torque (Mta), maximum	[Nm]	17
Pulley diameter	[mm]	38,2
Stroke per shaft revolution	[mm]	120
Weight	[kg]	
of unit with zero stroke		3,50
of every 100 mm of stroke		0,44
of each carriage		0,90

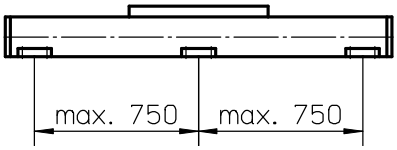
[1] Value for the complete unit
[2] Value for the wheel guide only
[3] See diagram Force Fx

Carriage Idle Torque, (M idle) [Nm]

Input speed [rpm]	Idle torque [Nm]
150	1,7
1500	2,4
3250	3,8

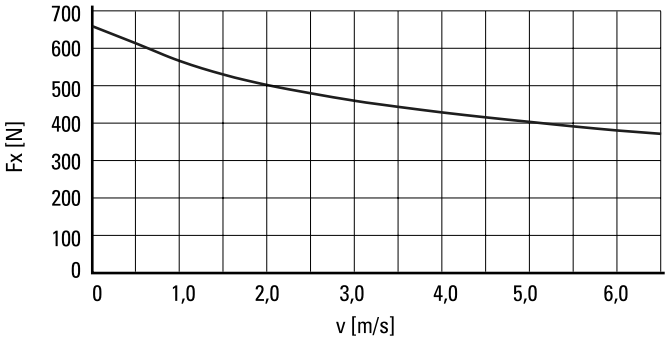
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

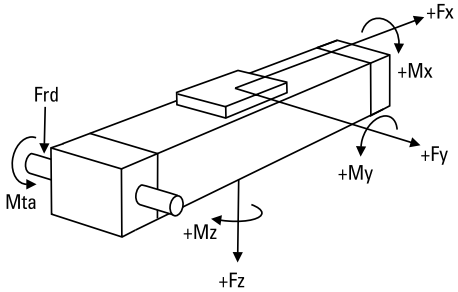


A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Force Fx as a Function of the Speed

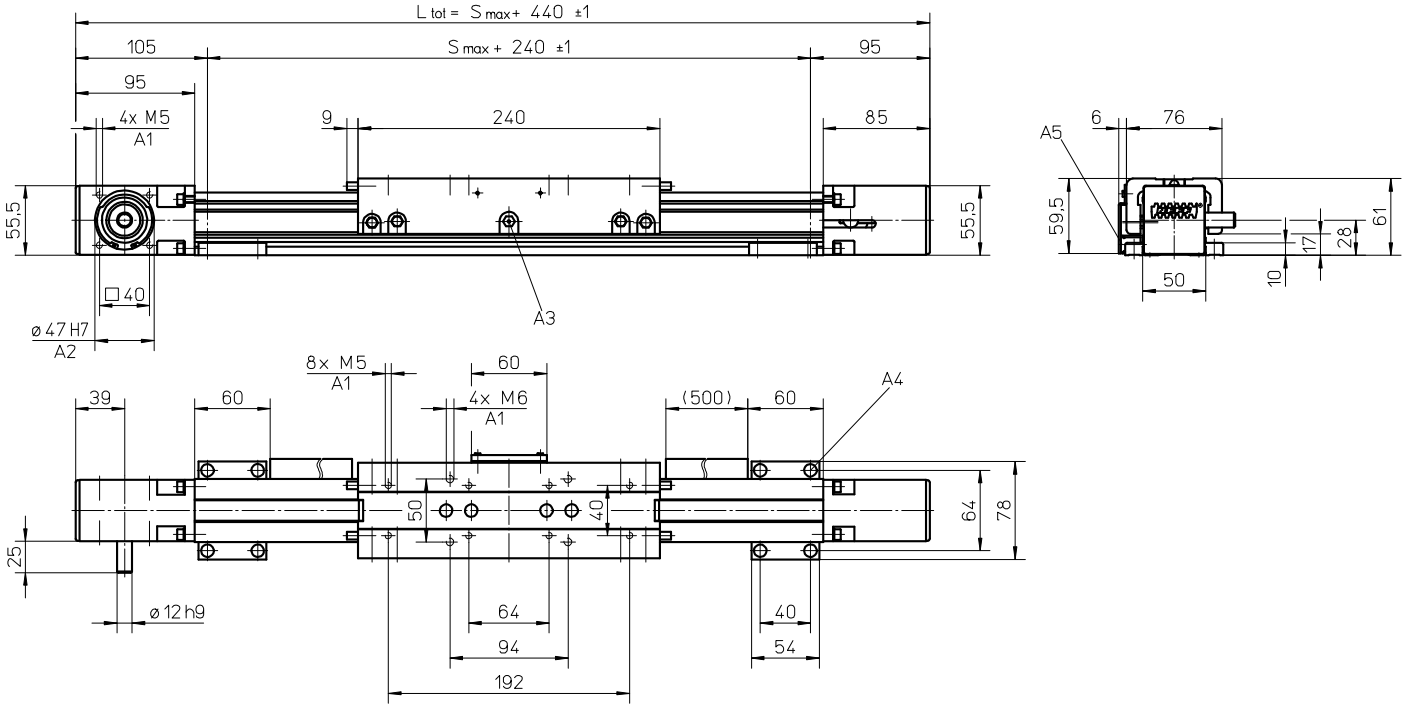


Definition of Forces



WH50

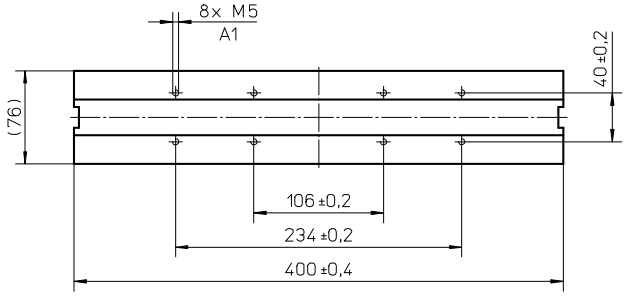
Belt Drive, Wheel Guide



A1: depth 10
A2: depth 3
A3: funnel type lubricating nipple DIN3405-M6×1-D1
A4: socket cap screw ISO4762-M5×12 8.8
A5: ENF inductive sensor rail option kit (optional)

Long Carriage

Parameter		WH50
Carriage length	[mm]	400
Dynamic load torque (My), maximum	[Nm]	130
Dynamic load torque (Mz), maximum	[Nm]	75
Weight	[kg]	1,47

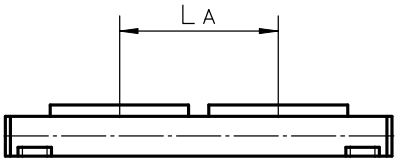


A1: depth 10

Double Carriages

Parameter		WH50
Minimum distance between carriages (L_A)	[mm]	260
Dynamic load (Fy), maximum	[N]	830
Dynamic load (Fz), maximum	[N]	1460
Dynamic load torque (My), maximum	[Nm]	L_A[1] × 0,415
Dynamic load torque (Mz), maximum	[Nm]	L_A[1] × 0,73
Force required to move second carriage	[N]	16
Total length (L tot)	[mm]	S max + 440 + L_A

[1] Value in mm



WH80

Belt Drive, Wheel Guide

» Ordering key - see page 193
» Accessories - see page 125
» Additional data - see page 173

General Specifications

Parameter	WH80
Profile size (w × h) [mm]	80 × 80
Type of belt	32ATL10
Carriage sealing system	none
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	lubrication og guiding surfaces
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WH80
Stroke length (S max), maximum	[mm]	11000
Linear speed, maximum	[m/s]	10,0
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,05
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	2700[3]
Dynamic load (Fy), maximum	[N]	882[1] / 8150[2]
Dynamic load (Fz), maximum	[N]	2100[1] / 14680[2]
Dynamic load torque (Mx), maximum	[Nm]	75[1] / 480[2]
Dynamic load torque (My), maximum	[Nm]	230[1] / 1610[2]
Dynamic load torque (Mz), maximum	[Nm]	100[1] / 900[2]
Drive shaft force (Frd), maximum	[N]	500
Drive shaft torque (Mta), maximum	[Nm]	100
Pulley diameter	[mm]	63,66
Stroke per shaft revolution	[mm]	200
Weight	[kg]	
of unit with zero stroke		8,63
of every 100 mm of stroke		0,93
of each carriage		2,75

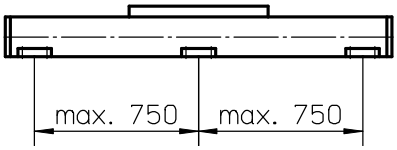
[1] Value for the complete unit
[2] Value for the wheel guide only
[3] See diagram Force Fx

Carriage Idle Torque, (M idle) [Nm]

Input speed [rpm]	Idle torque [Nm]
150	2,4
1500	3,5
3000	5,0

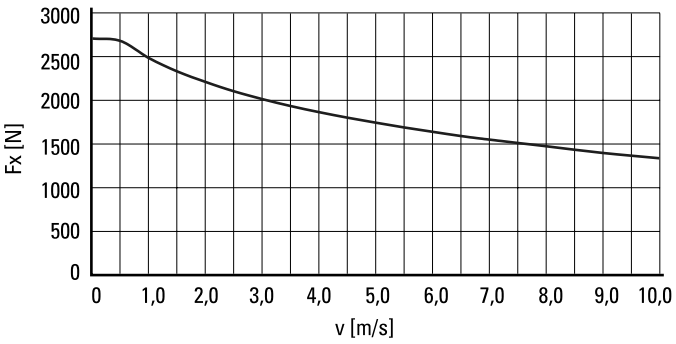
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

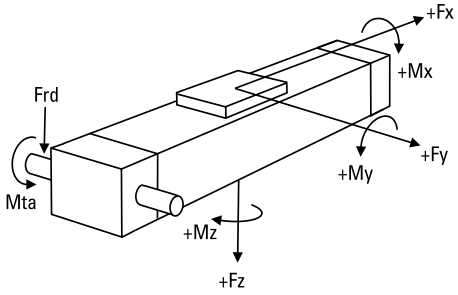


A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information. Units with a profile length over 6300 mm consists of two profiles where the joint between the two profiles must be addequately supported on both sides.

Force Fx as a Function of the Speed

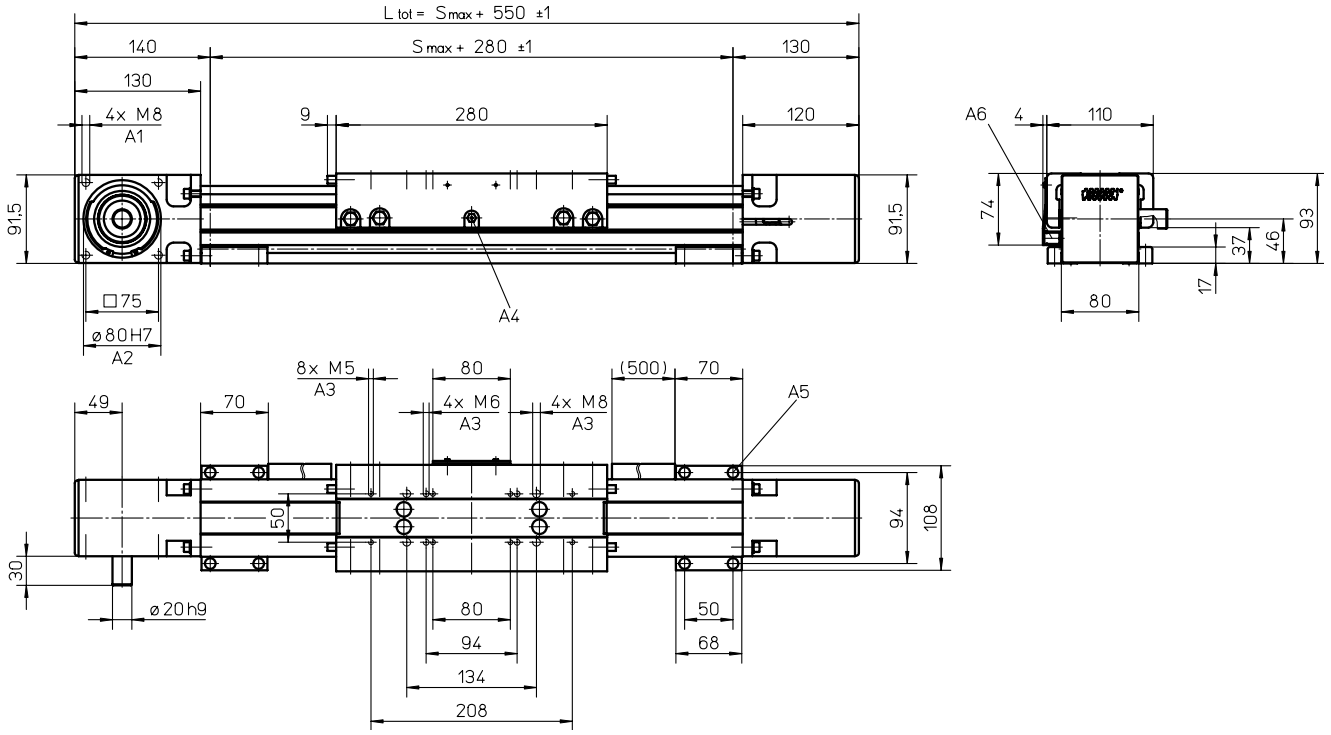


Definition of Forces



WH80

Belt Drive, Wheel Guide

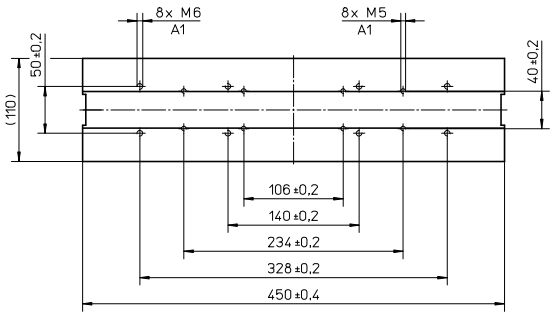


A1: depth 16
A2: depth 2,5
A3: depth 12

A4: funnel type lubricating nipple DIN3405-M6×1-D1
A5: socket cap screw ISO4762-M6×20 8.8
A6: ENF inductive sensor rail option kit (optional)

Long Carriage

Parameter		WH80
Carriage length	[mm]	450
Dynamic load torque (My), maximum	[Nm]	345
Dynamic load torque (Mz), maximum	[Nm]	150
Weight	[kg]	3,43

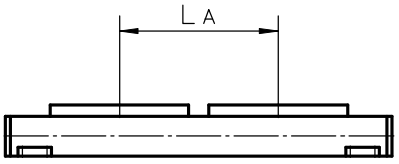


A1: depth 12

Double Carriages

Parameter		WH80
Minimum distance between carriages (L_A)	[mm]	300
Dynamic load (Fy), maximum	[N]	1764
Dynamic load (Fz), maximum	[N]	4200
Dynamic load torque (My), maximum	[Nm]	L_A[1] × 0,882
Dynamic load torque (Mz), maximum	[Nm]	L_A[1] × 2,1
Force required to move second carriage	[N]	20
Total length (L tot)	[mm]	S max + 550 + L_A

[1] Value in mm



WH120

Belt Drive, Wheel Guide

» Ordering key - see page 193
» Accessories - see page 125
» Additional data - see page 173

General Specifications

Parameter	WH120
Profile size (w × h) [mm]	120 × 110
Type of belt	50ATL10
Carriage sealing system	none
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	lubrication og guiding surfaces
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WH120
Stroke length (S max), maximum	[mm]	11000
Linear speed, maximum	[m/s]	10,0
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,05
Input speed, maximum	[rpm]	2308
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	5000[3]
Dynamic load (Fy), maximum	[N]	4980[1] / 40500[2]
Dynamic load (Fz), maximum	[N]	9300[1] / 64800[2]
Dynamic load torque (Mx), maximum	[Nm]	500[1] / 3140[2]
Dynamic load torque (My), maximum	[Nm]	930[1] / 5830[2]
Dynamic load torque (Mz), maximum	[Nm]	500[1] / 3640[2]
Drive shaft force (Frd), maximum	[N]	700
Drive shaft torque (Mta), maximum	[Nm]	200
Pulley diameter	[mm]	82,76
Stroke per shaft revolution	[mm]	260
Weight	[kg]	
of unit with zero stroke		17,00
of every 100 mm of stroke		1,64
of each carriage		5,50

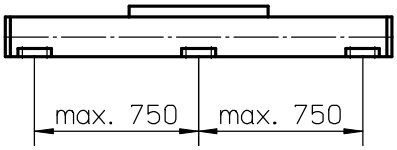
[1] Value for the complete unit
[2] Value for the wheel guide only
[3] See diagram Force Fx

Carriage Idle Torque, (M idle) [Nm]

Input speed [rpm]	Idle torque [Nm]
150	4,8
1500	7,0
2308	10,0

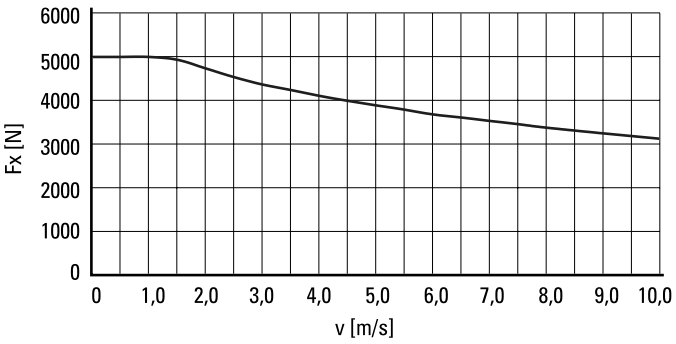
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

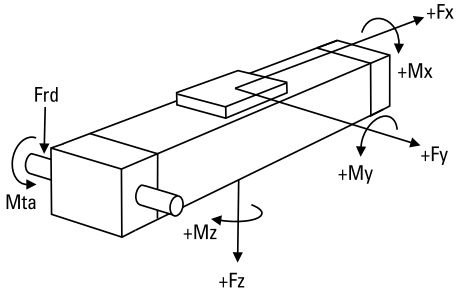


A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information. Units with a profile length over 4900 mm consists of two profiles where the joint between the two profiles must be addequately supported on both sides.

Force Fx as a Function of the Speed

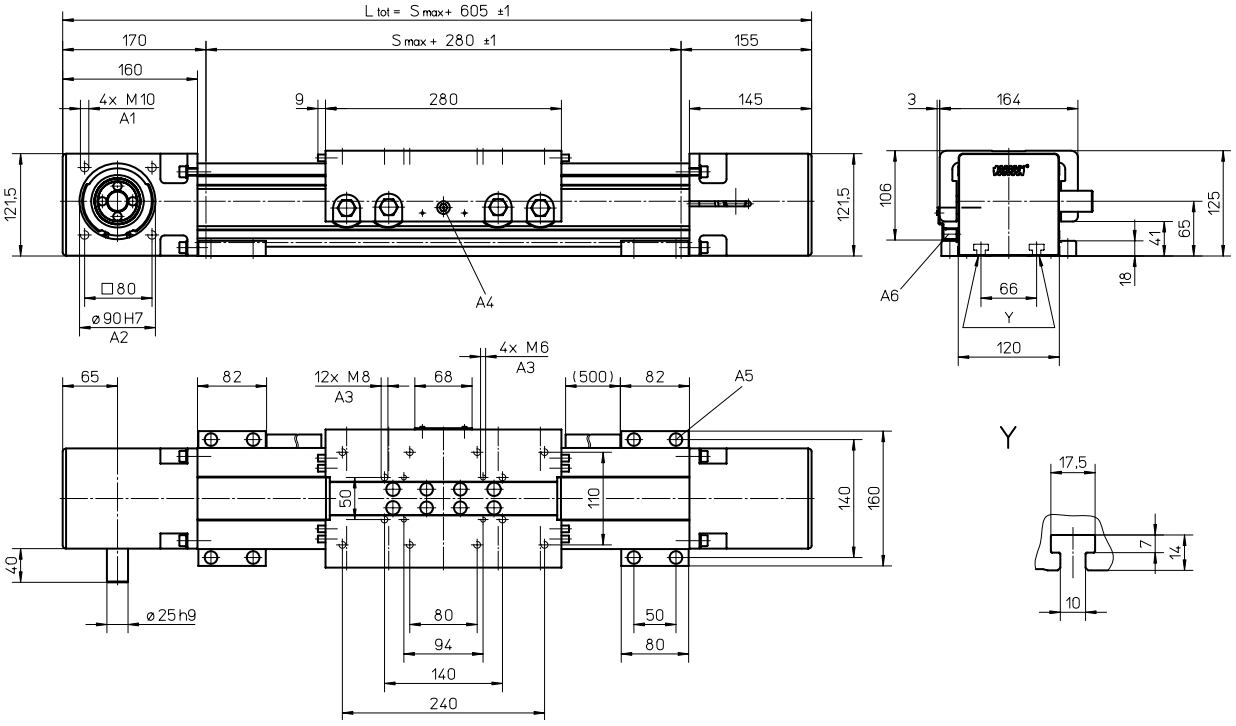


Definition of Forces



WH120

Belt Drive, Wheel Guide

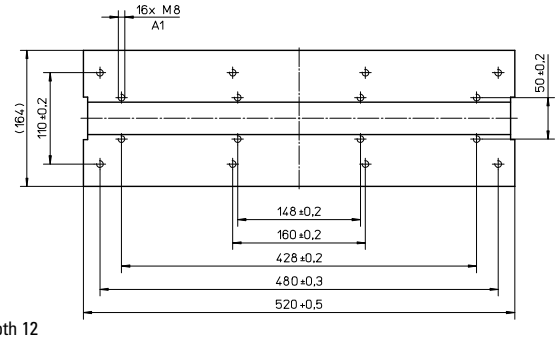


A1: depth 20
A2: depth 7
A3: depth 12

A4: funnel type lubricating nipple DIN3405-M6×1-D1
A5: socket cap screw ISO4762-M8×20 8.8
A6: ENF inductive sensor rail option kit (optional)

Long Carriage

Parameter		WH120
Carriage length	[mm]	520
Dynamic load torque (My), maximum	[Nm]	1395
Dynamic load torque (Mz), maximum	[Nm]	750
Weight	[kg]	8,67

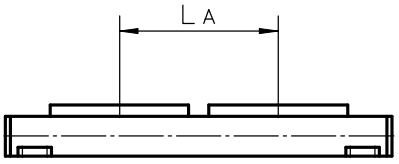


A1: depth 12

Double Carriages

Parameter		WH120
Minimum distance between carriages (LA)	[mm]	300
Dynamic load (Fy), maximum	[N]	9960
Dynamic load (Fz), maximum	[N]	18600
Dynamic load torque (My), maximum	[Nm]	L A[1] × 4,98
Dynamic load torque (Mz), maximum	[Nm]	L A[1] × 9,3
Force required to move second carriage	[N]	30
Total length (L tot)	[mm]	S max + 605 + L A

[1] Value in mm



MLSH60Z

Belt Drive, Wheel Guide

» Ordering key - see page 194
» Accessories - see page 125
» Additional data - see page 173

General Specifications

Parameter	MLSH60Z
Profile size (w × h) [mm]	160 × 65
Type of belt	32ATL5
Carriage sealing system	plastic cover band
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	no lubrication required
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		MLSH60Z
Stroke length (S max), maximum	[mm]	5500
Linear speed, maximum	[m/s]	6,5
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,05
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	1480[3]
Dynamic load (Fy), maximum	[N]	3000[1] / 24760[2]
Dynamic load (Fz), maximum	[N]	3000[1] / 24760[2]
Dynamic load torque (Mx), maximum	[Nm]	165[1] / 1920[2]
Dynamic load torque (My), maximum	[Nm]	310[1] / 2600[2]
Dynamic load torque (Mz), maximum	[Nm]	310[1] / 2600[2]
Drive shaft force (Frd), maximum	[N]	200
Drive shaft torque (Mta), maximum	[Nm]	45
Pulley diameter	[mm]	42,97
Stroke per shaft revolution	[mm]	135
Weight	[kg]	
of unit with zero stroke		12,60
of every 100 mm of stroke		1,33
of each carriage		3,90

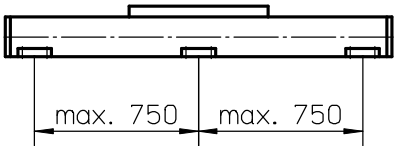
[1] Value for the complete unit
[2] Value for the wheel guide only
[3] See diagram Force Fx

Carriage Idle Torque, (M idle) [Nm]

Input speed [rpm]	Idle torque [Nm]
150	4,6
1500	9,0
3000	12,0

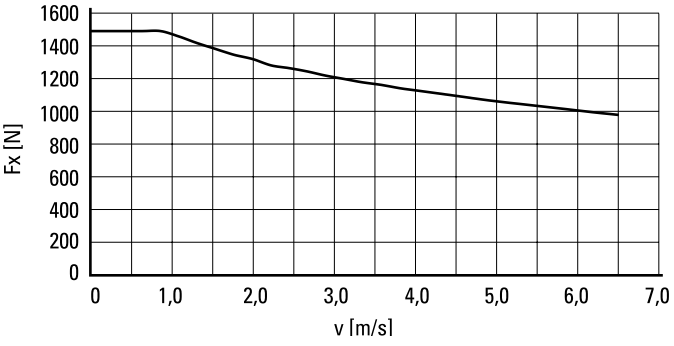
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

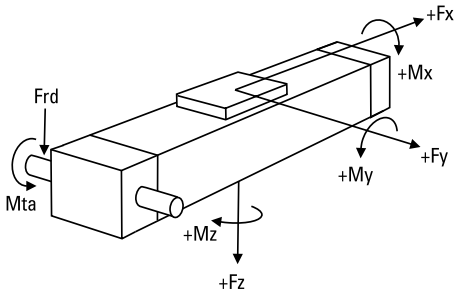


A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Force Fx as a Function of the Speed

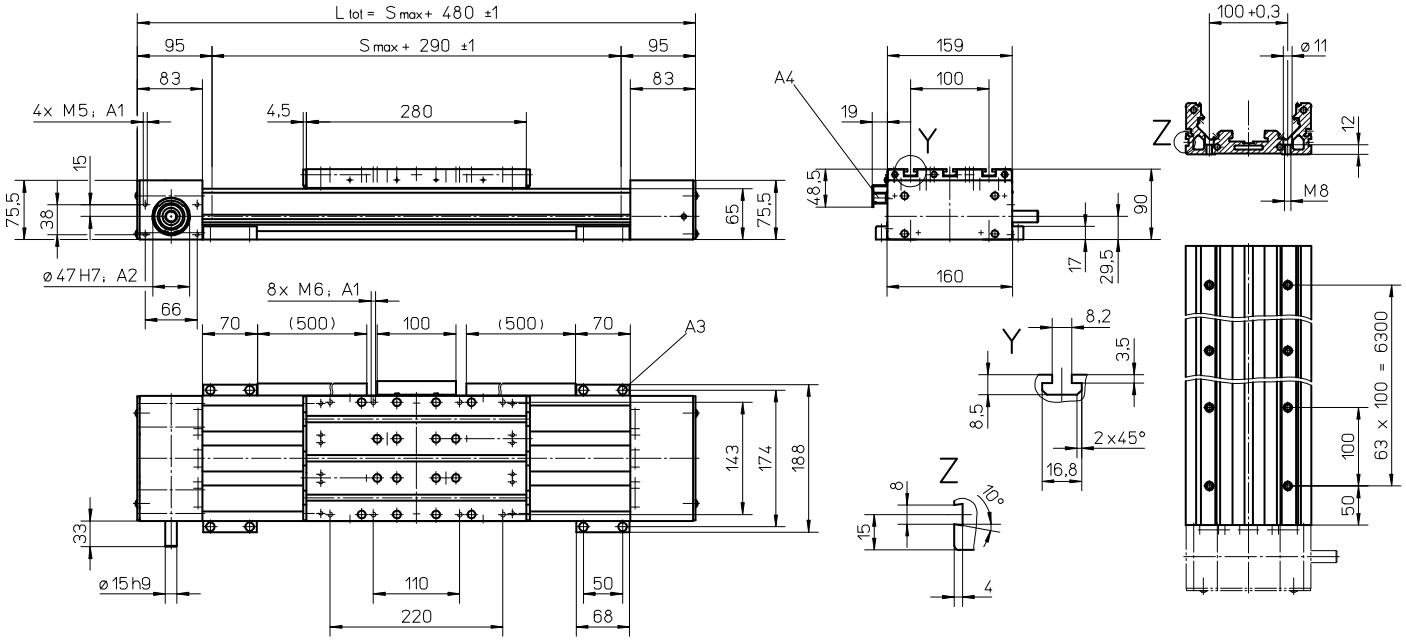


Definition of Forces



MLSH60Z

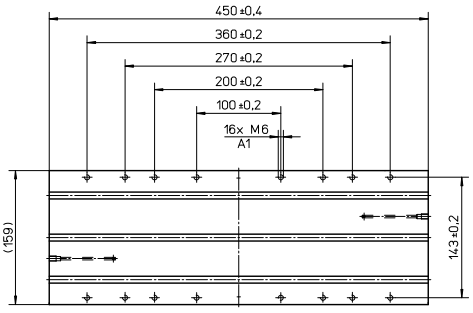
Belt Drive, Wheel Guide



A1: depth 10
A2: depth 4
A3: socket cap screw ISO4762-M6x20 8.8
A4: ENF inductive sensor rail option kit (optional)

Long Carriage

Parameter		MLSH60Z
Carriage length	[mm]	450
Dynamic load torque (My), maximum	[Nm]	585
Dynamic load torque (Mz), maximum	[Nm]	585
Weight	[kg]	6

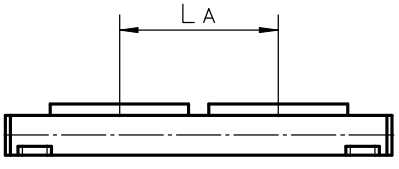


A1: depth 10

Double Carriages

Parameter		MLSH60Z
Minimum distance between carriages (L_A)	[mm]	290
Dynamic load (Fy), maximum	[N]	6000
Dynamic load (Fz), maximum	[N]	6000
Dynamic load torque (My), maximum	[Nm]	L_A[1] × 3
Dynamic load torque (Mz), maximum	[Nm]	L_A[1] × 3
Force required to move second carriage	[N]	10
Total length (L tot)	[mm]	S max + 480 + L_A

[1] Value in mm



MLSH80Z

Belt Drive, Wheel Guide

» Ordering key - see page 194
» Accessories - see page 125
» Additional data - see page 173

General Specifications

Parameter	MLSH80Z
Profile size (w × h) [mm]	240 × 85
Type of belt	75ATL10
Carriage sealing system	plastic cover band
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	no lubrication required
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		MLSH80Z
Stroke length (S max), maximum	[mm]	5900
Linear speed, maximum	[m/s]	10,0
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,05
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	5000[3]
Dynamic load (Fy), maximum	[N]	5000[1] / 55090[2]
Dynamic load (Fz), maximum	[N]	5000[1] / 55090[2]
Dynamic load torque (Mx), maximum	[Nm]	350[1] / 2890[2]
Dynamic load torque (My), maximum	[Nm]	450[1] / 4490[2]
Dynamic load torque (Mz), maximum	[Nm]	450[1] / 4490[2]
Drive shaft force (Frd), maximum	[N]	700
Drive shaft torque (Mta), maximum	[Nm]	150
Pulley diameter	[mm]	63,66
Stroke per shaft revolution	[mm]	200
Weight of unit with zero stroke of every 100 mm of stroke of each carriage	[kg]	 30,7 2,4 10,0

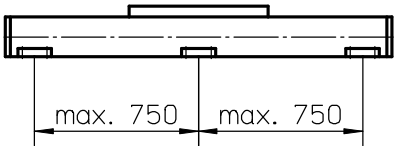
[1] Value for the complete unit
[2] Value for the wheel guide only
[3] See diagram Force Fx

Carriage Idle Torque, (M idle) [Nm]

Input speed [rpm]	Idle torque [Nm]
150	8,5
1500	12,5
3000	15,5

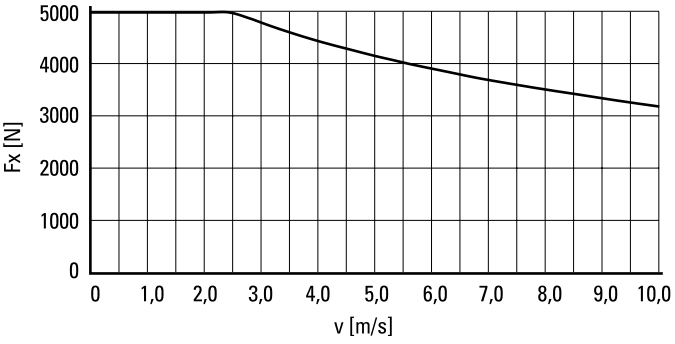
M idle = the input torque needed to move the carriage with no load on it.

Deflection of the Profile

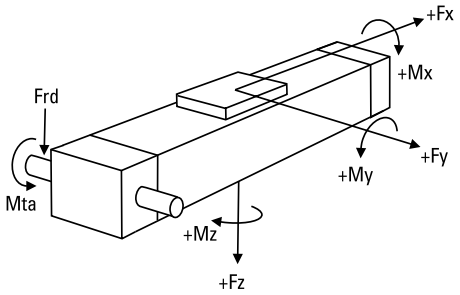


A mounting clamp must be installed at least at every 750 mm to be able to operate the maximum load. Less clamps may be required if less load is being operated, see the additional technical data for more information.

Force Fx as a Function of the Speed

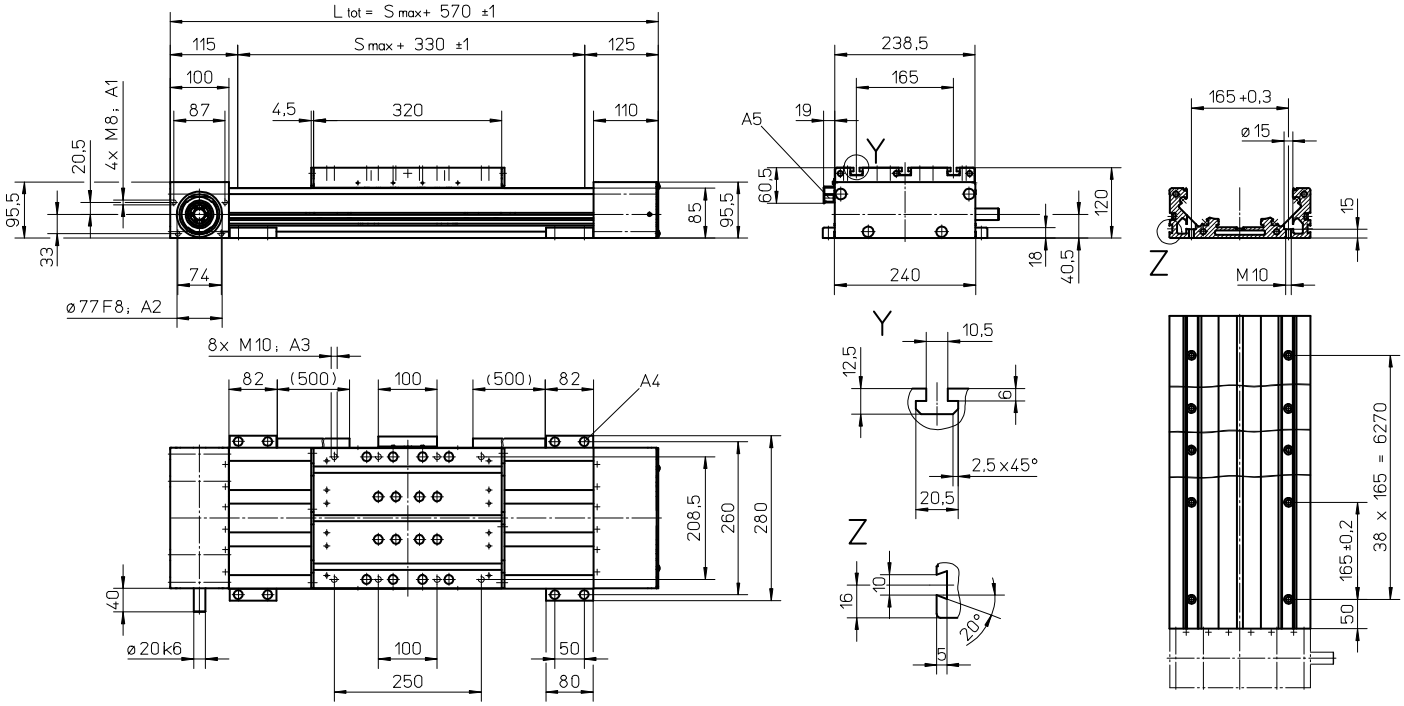


Definition of Forces



MLSH80Z

Belt Drive, Wheel Guide

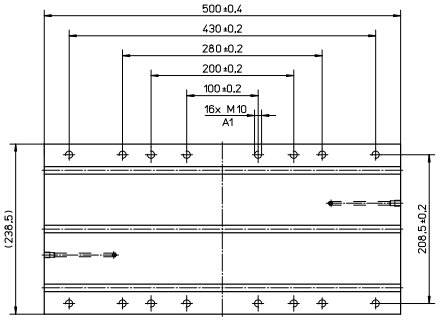


A1: depth 18
A2: depth 4
A3: depth 15

A4: socket cap screw ISO4762-M8×20 8.8
A5: ENF inductive sensor rail option kit (optional)

Long Carriage

Parameter		MLSH80Z
Carriage length	[mm]	500
Dynamic load torque (My), maximum	[Nm]	700
Dynamic load torque (Mz), maximum	[Nm]	700
Weight	[kg]	14,1

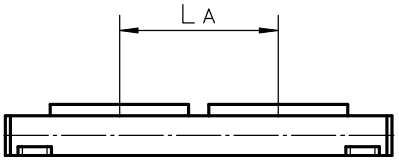


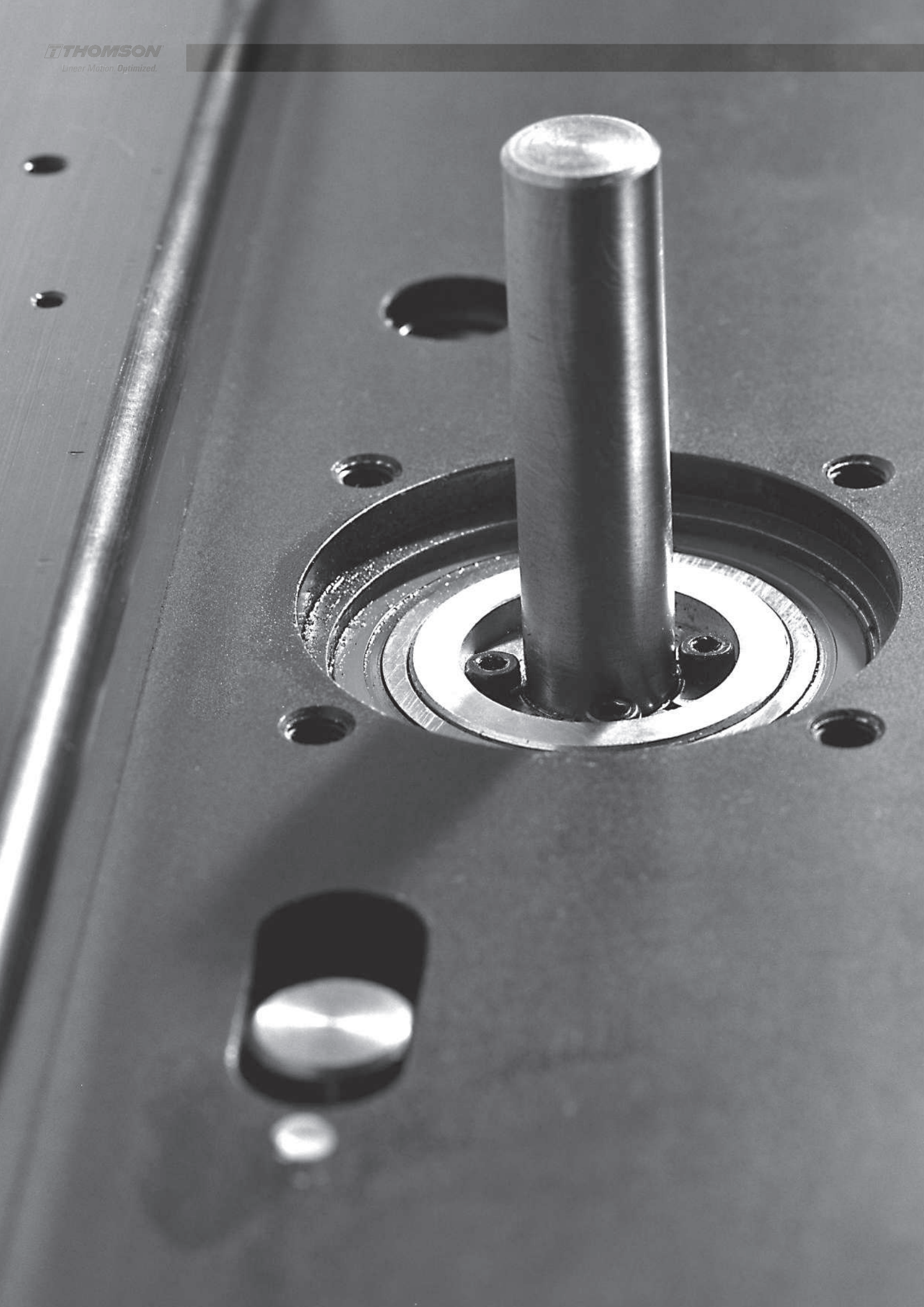
A1: depth 15

Double Carriages

Parameter		MLSH80Z
Minimum distance between carriages (L_A)	[mm]	340
Dynamic load (Fy), maximum	[N]	10000
Dynamic load (Fz), maximum	[N]	10000
Dynamic load torque (My), maximum	[Nm]	L_A[1] × 5
Dynamic load torque (Mz), maximum	[Nm]	L_A[1] × 5
Force required to move second carriage	[N]	20
Total length (L tot)	[mm]	S max + 570 + L_A

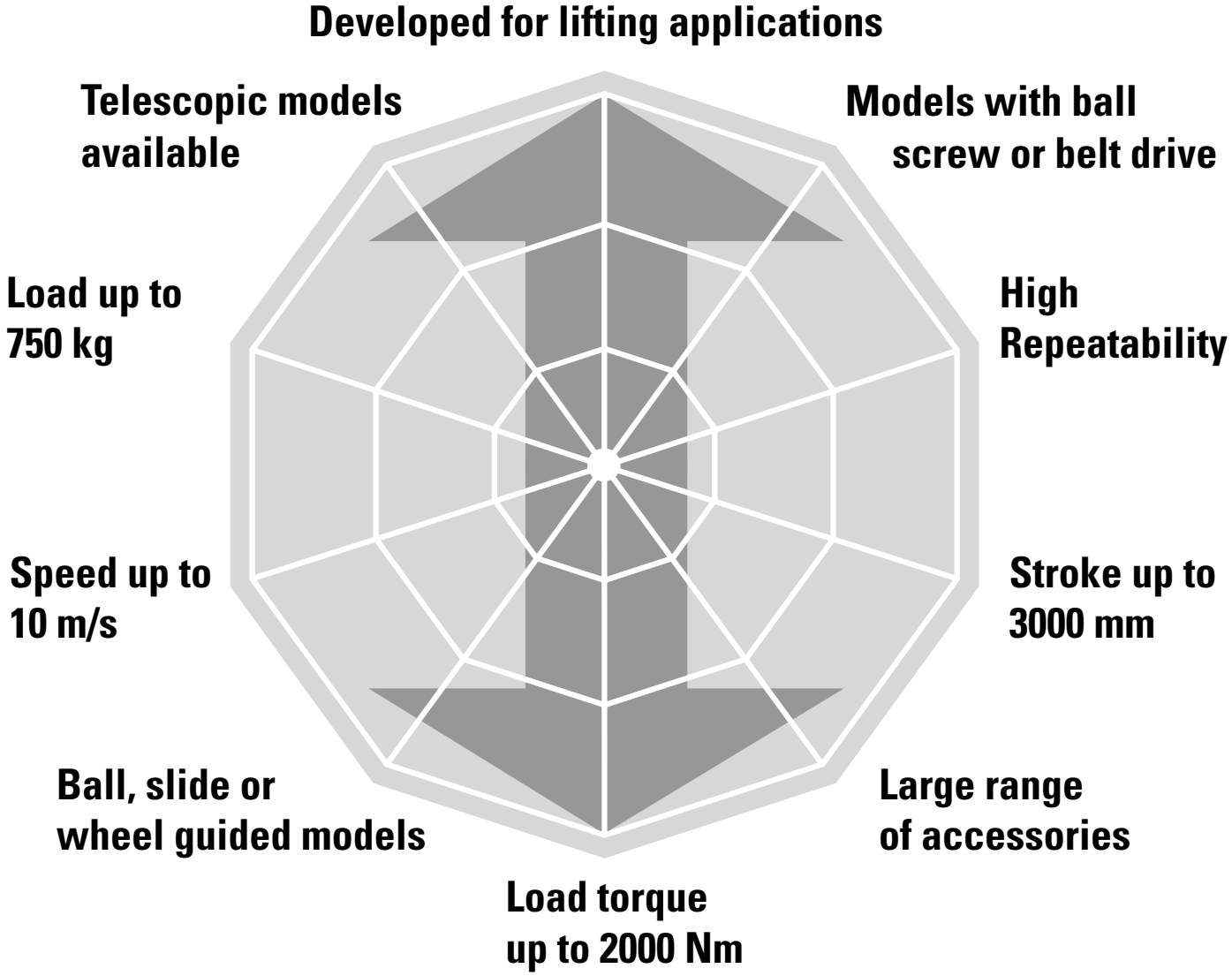
[1] Value in mm





Linear Lifting Units

SpeedLine, Movo Z



Typical Applications

Typical applications are found in most industries where light, medium or heavy loads needs to be lifted. Examples are pick and place operations, materials handling, electronic assembly and for lifting equipment in automotive assembly lines.

Linear Lifting Units

Overview

SpeedLine WHZ


WHZ50

Features

- Can be installed in all directions
- Belt drive
- External wheel guides
- Speed up to 10 m/s
- Acceleration up to 40 m/s^2

Parameter		WHZ50	WHZ80
Profile size (width × length)	[mm]	50 × 50	80 × 80
Stroke length (S max), maximum	[mm]	1500	3000
Linear speed, maximum	[m/s]	6,5	10,0
Dynamic load (Fx), maximum	[N]	670	1480
Remarks		the load is always attached to the end of the lifting profile	the load is always attached to the end of the lifting profile
Page		106	108

Movo Z


Z2

Features

- Telescopic movement
- Ball screw drive
- Internal slide guides
- Load up to 7500 N
- Load torque up to 2000 Nm
- Two end stop limit switches (Z2 only)

Parameter		Z2	Z3
Profile size (width × height)	[mm]	188 × 150	188 × 150
Stroke length (S max), maximum	[mm]	1500	1500
Linear speed, maximum	[m/s]	1,25	1,25
Dynamic load (Fz), maximum	[N]	7500	7500
Remarks		Can be installed in any direction. The load must be attached at the end of the lifting profile	Can only be installed vertically with motor up. The load must be attached at the end of the lifting profile.
Page		110	112

Linear Lifting Units

Overview

Movo ZB

Features

- Can be installed in all directions
- Belt drive
- Internal ball guides
- Stroke up to 2,5 m

Parameter		ZB
Profile size (width × height)	[mm]	88 × 88
Stroke length (S max), maximum	[mm]	2500
Linear speed, maximum	[m/s]	3,0
Dynamic load (Fz), maximum	[N]	500
Remarks		the load is always attached to the end of the lifting profile
Page		114

WHZ50

Belt Drive, Wheel Guide

» Ordering key - see page 195
» Accessories - see page 125
» Additional data - see page 174

General Specifications

Parameter	WHZ50
Profile size (w × h) [mm]	50 × 50
Type of belt	16 ATL 5
Carriage sealing system	none
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	lubrication of carriage and guide surfaces
Included accessories	-

Performance Specifications

Parameter		WHZ50
Stroke length (S max), maximum	[mm]	1500
Linear speed, maximum	[m/s]	6,5
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,05
Input speed, maximum	[rpm]	3250
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	670[3]
Dynamic load (Fy), maximum	[N]	415[1] / 2820[2]
Dynamic load (Fz), maximum	[N]	730[1] / 5080[2]
Dynamic load torque (Mx), maximum	[Nm]	16[1] / 100[2]
Dynamic load torque (My), maximum	[Nm]	87[1] / 500[2]
Dynamic load torque (Mz), maximum	[Nm]	50[1] / 280[2]
Drive shaft force (Frd), maximum	[N]	150
Drive shaft torque (Mta), maximum	[Nm]	17
Pulley diameter	[mm]	38,2
Stroke per shaft revolution	[mm]	120
Weight	[kg]	
of unit with zero stroke		4,50
of every 100 mm of stroke		0,42
of each drive station box		2,90

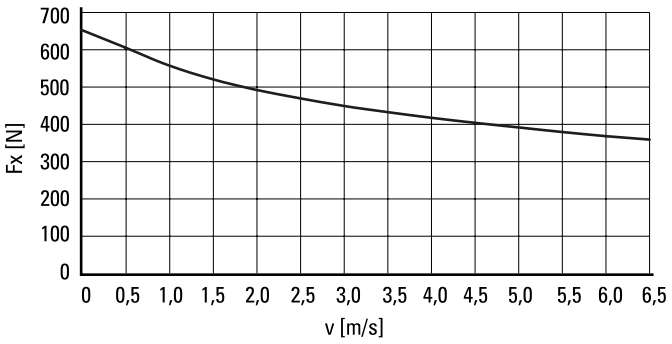
[1] Value for the complete unit
[2] Value for the wheel guide only
[3] See diagram Force Fx

Carriage Idle Torque, (M idle) [Nm]

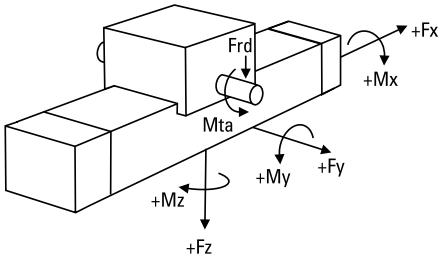
Input speed [rpm]	Idle torque [Nm]
150	1,7
1500	2,4
3250	3,8

M idle = the input torque needed to move the carriage with no load on it.

Force Fx as a Function of the Speed

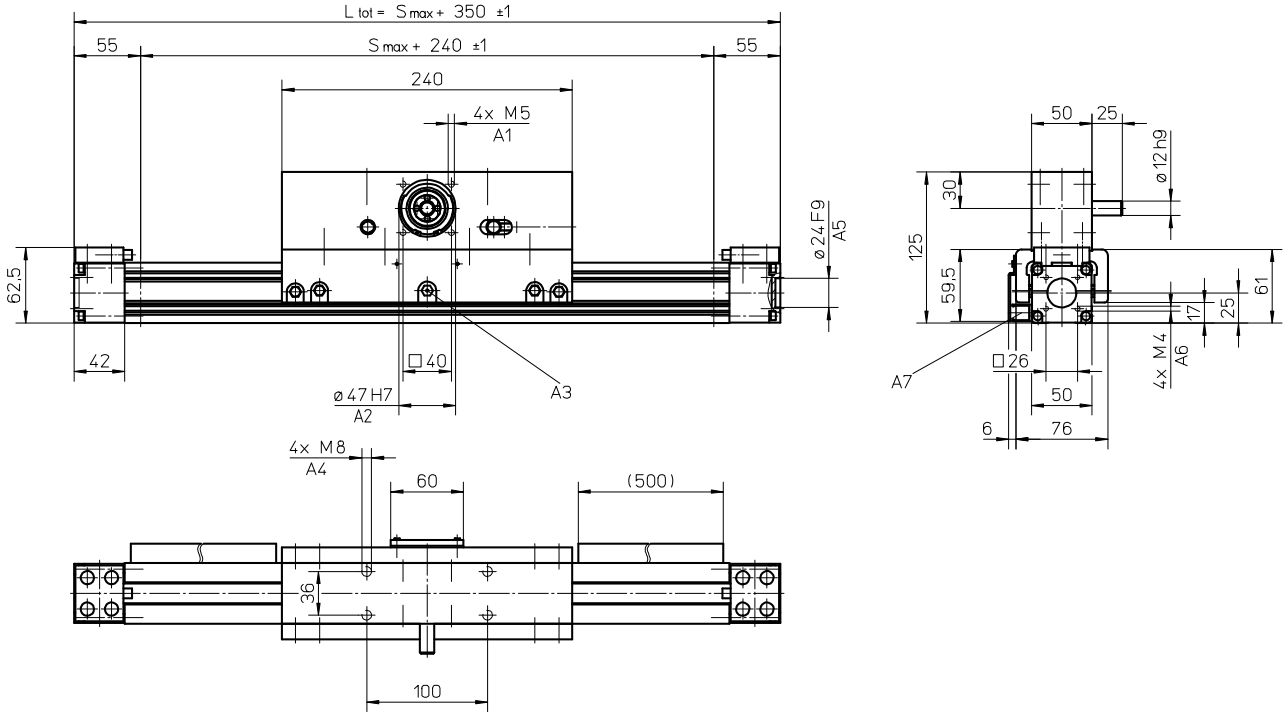


Definition of Forces



WHZ50

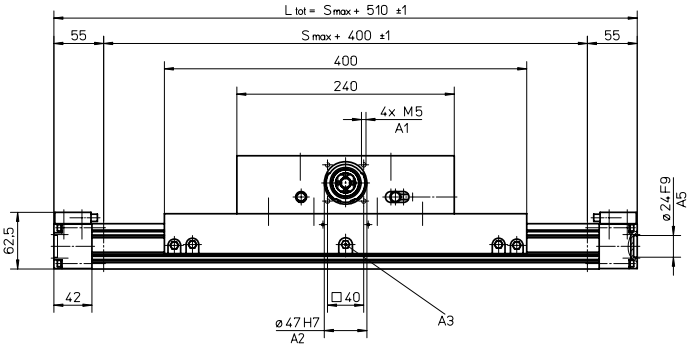
Belt Drive, Wheel Guide



A1: depth 12
A2: depth 3,5
A3: funnel type lubricating nipple DIN3405-M6×1-D1
A4: depth 16
A5: depth 4
A6: depth 8
A7: ENF inductive sensor rail option kit (optional)

Long Carriage

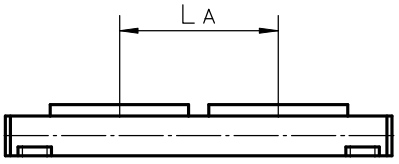
Parameter		WHZ50
Carriage length	[mm]	400
Dynamic load torque (My), maximum	[Nm]	130
Dynamic load torque (Mz), maximum	[Nm]	75
Weight	[kg]	3,3



A1: depth 12
A2: depth 3,5
A3: funnel type lubricating nipple DIN3405-M6×1-D1
A5: depth 4

Double Carriages[2]

Parameter		WHZ50
Minimum distance between carriages (L_A)	[mm]	260
Dynamic load (Fy), maximum	[N]	830
Dynamic load (Fz), maximum	[N]	1460
Dynamic load torque (My), maximum	[Nm]	L_A[1] × 0,415
Dynamic load torque (Mz), maximum	[Nm]	L_A[1] × 0,73
Force required to move second carriage	[N]	16
Total length (L tot)	[mm]	S max + 350 + L_A



[1] Value in mm
[2] Second carriage is always a long carriage

WHZ80

Belt Drive, Wheel Guide

» Ordering key - see page 195
» Accessories - see page 125
» Additional data - see page 174

General Specifications

Parameter	WHZ80
Profile size (w × h) [mm]	80 × 80
Type of belt	32 ATL 5
Carriage sealing system	none
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	lubrication of carriage and guide surfaces
Included accessories	-

Performance Specifications

Parameter		WHZ80
Stroke length (S max), maximum	[mm]	3000
Linear speed, maximum	[m/s]	10,0
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,05
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	1480[3]
Dynamic load (Fy), maximum	[N]	882[1] / 8160[2]
Dynamic load (Fz), maximum	[N]	2100[1] / 14680[2]
Dynamic load torque (Mx), maximum	[Nm]	75[1] / 480[2]
Dynamic load torque (My), maximum	[Nm]	230[1] / 1610[2]
Dynamic load torque (Mz), maximum	[Nm]	100[1] / 900[2]
Drive shaft force (Frd), maximum	[N]	500
Drive shaft torque (Mta), maximum	[Nm]	50
Pulley diameter	[mm]	63,66
Stroke per shaft revolution	[mm]	200
Weight	[kg]	
of unit with zero stroke		11,20
of every 100 mm of stroke		0,91
of each drive station box		6,65

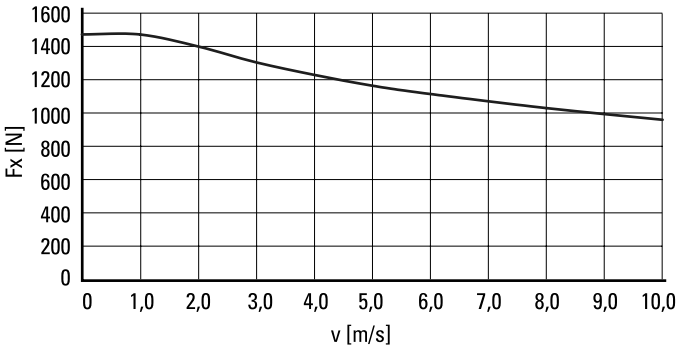
[1] Value for the complete unit
[2] Value for the wheel guide only
[3] See diagram Force Fx

Carriage Idle Torque, (M idle) [Nm]

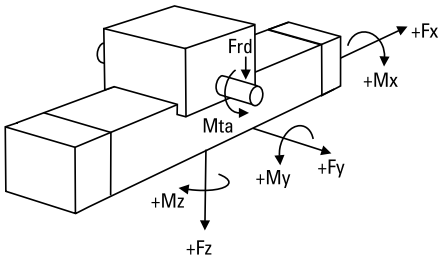
Input speed [rpm]	Idle torque [Nm]
150	2,4
1500	3,5
3000	5,0

M idle = the input torque needed to move the carriage with no load on it.

Force Fx as a Function of the Speed

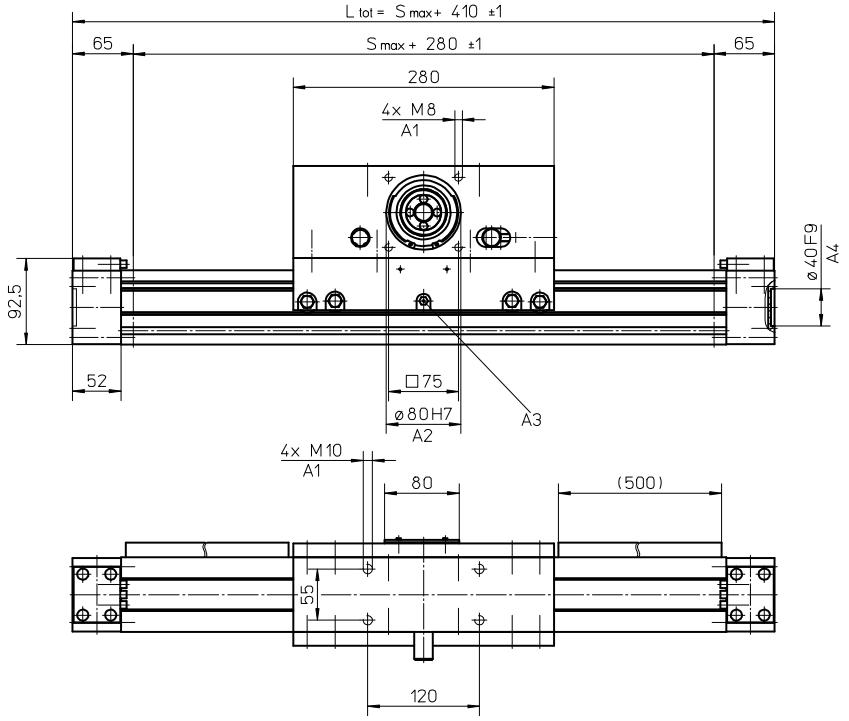


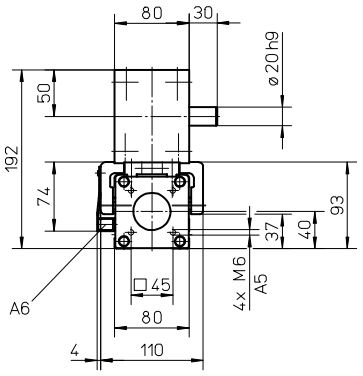
Definition of Forces



WHZ80

Belt Drive, Wheel Guide

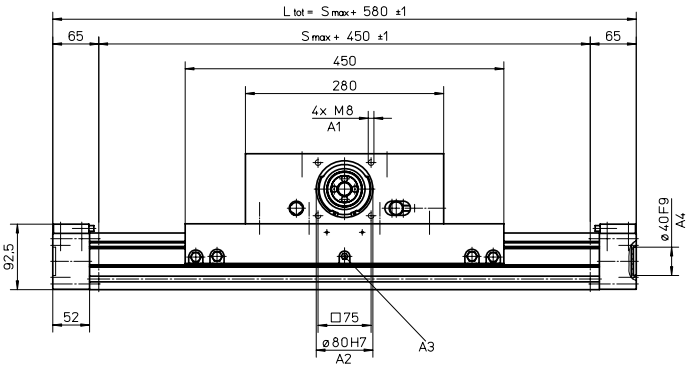




A1: depth 20
A2: depth 3,5
A3: funnel type lubricating nipple DIN3405-M6×1-D1
A4: depth 4
A5: depth 15
A6: ENF inductive sensor rail option kit (optional)

Long Carriage

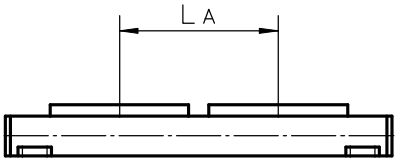
Parameter		WHZ80
Carriage length	[mm]	450
Dynamic load torque (My), maximum	[Nm]	345
Dynamic load torque (Mz), maximum	[Nm]	150
Weight	[kg]	7,4



A1: depth 20
A2: depth 3,5
A3: funnel type lubricating nipple DIN3405-M6×1-D1
A4: depth 4

Double Carriages[2]

Parameter		WHZ80
Minimum distance between carriages (L_A)	[mm]	300
Dynamic load (Fy), maximum	[N]	1764
Dynamic load (Fz), maximum	[N]	4200
Dynamic load torque (My), maximum	[Nm]	L_A[1] × 0,882
Dynamic load torque (Mz), maximum	[Nm]	L_A[1] × 2,1
Force required to move second carriage	[N]	20
Total length (L tot)	[mm]	S max + 410 + L_A



[1] Value in mm
[2] Second carriage is always a long carriage

Z2

Ball Screw Drive, Slide Guide

» Ordering key - see page 195
» Accessories - see page 125
» Additional data - see page 174

General Specifications

Parameter	Z2
Profile size (w × h) [mm]	188 × 150
Type of screw	ball screw with single nut
Sealing system	none
Screw supports	none
Lubrication	lubrication of screw and slide surfaces
Included accessories	none

Performance Specifications

Parameter		Z2
Stroke length (S max), maximum	[mm]	1500
Linear speed, maximum	[m/s]	1,25
Acceleration, maximum	[m/s²]	8
Repeatability	[± mm]	0,1
Input speed, maximum screw diameter/lead [mm] 25/10, 25/25 screw diameter/lead [mm] 32/20	[rpm]	 3000 2500
Operation temperature limits	[°C]	-20 – 70
Dynamic load (Fz), maximum screw diameter/lead [mm] 25/10, 25/25 screw diameter/lead [mm] 32/20	[N]	 5000 7500
Dynamic load torque (Mx), maximum	[Nm]	700[1]
Dynamic load torque (My), maximum	[Nm]	700[1]
Dynamic load torque (Mz), maximum	[Nm]	330[1]
Drive shaft force (Frd), maximum screw diameter/lead [mm] 25/10, 25/25 screw diameter/lead [mm] 32/20	[N]	 1000 1200
Drive shaft torque (Mta), maximum screw diameter/lead [mm] 25/10, 25/25 screw diameter/lead [mm] 32/20	[Nm]	 45 93
Screw versions, diameter (d_0) / lead (p)	[mm]	25/10, 25/25, 32/20
Weight of unit with zero stroke, ball screw ø 25 mm of unit with zero stroke, ball screw ø 32 mm of every 100 mm of stroke, ball screw ø 25 mm of every 100 mm of stroke, ball screw ø 32 mm	[kg]	 19,00 23,64 2,50 2,80

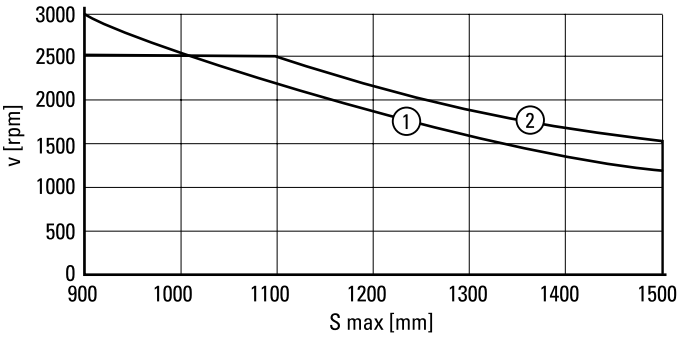
[1] Value for the complete uniy

Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw diameter/lead [mm]		
	d_0 = 25 / p = 10	d_0 = 25 / p = 25	d_0 = 32 / p = 20
500	0,7	1,9	1,5

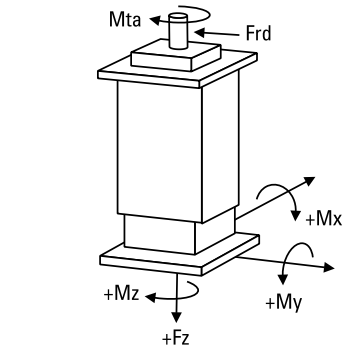
M idle = the input torque needed to move the lifting profiles without any load.

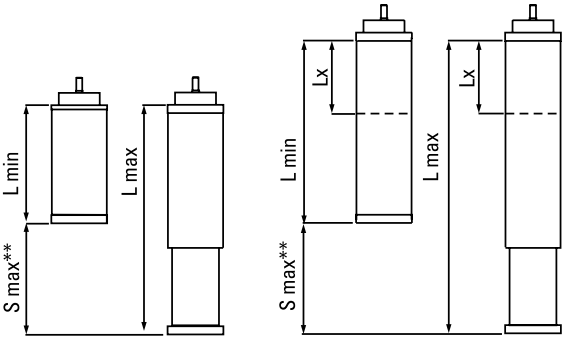
Critical Speed



1: screw diameter 25 mm
2: screw diameter 32 mm

Definition of Forces and Stroke



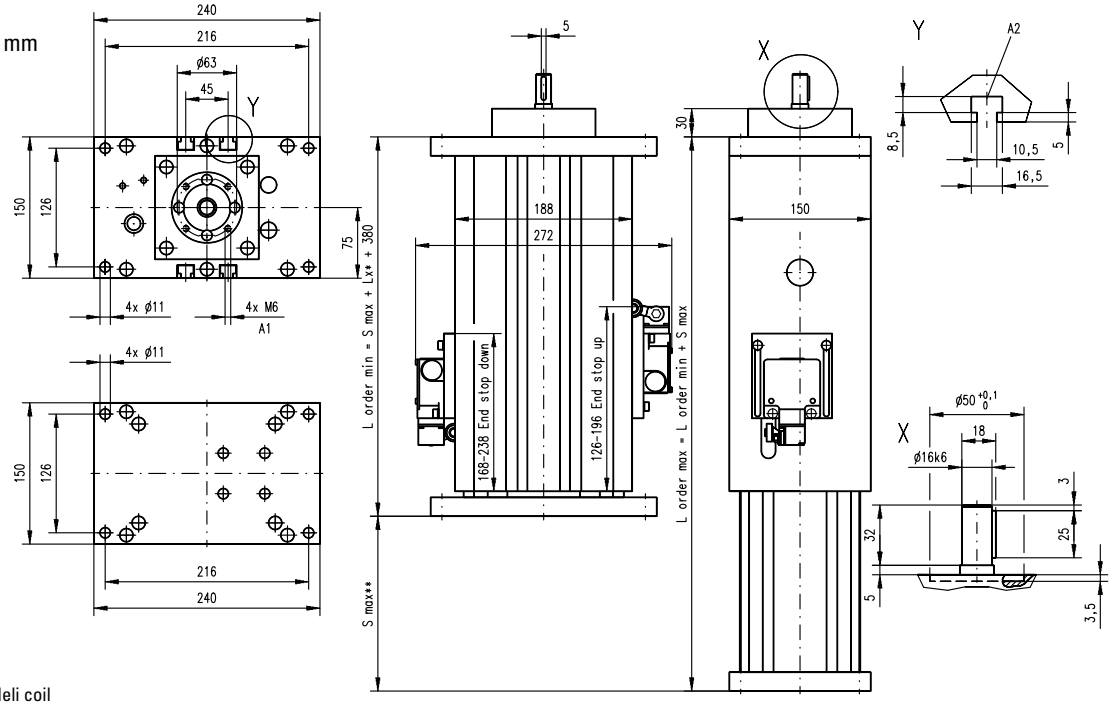


** S max = maximum stroke between the mechanical ends of the unit. The practical stroke is normally 100 mm shorter to avoid running into the ends of the unit.

Z2

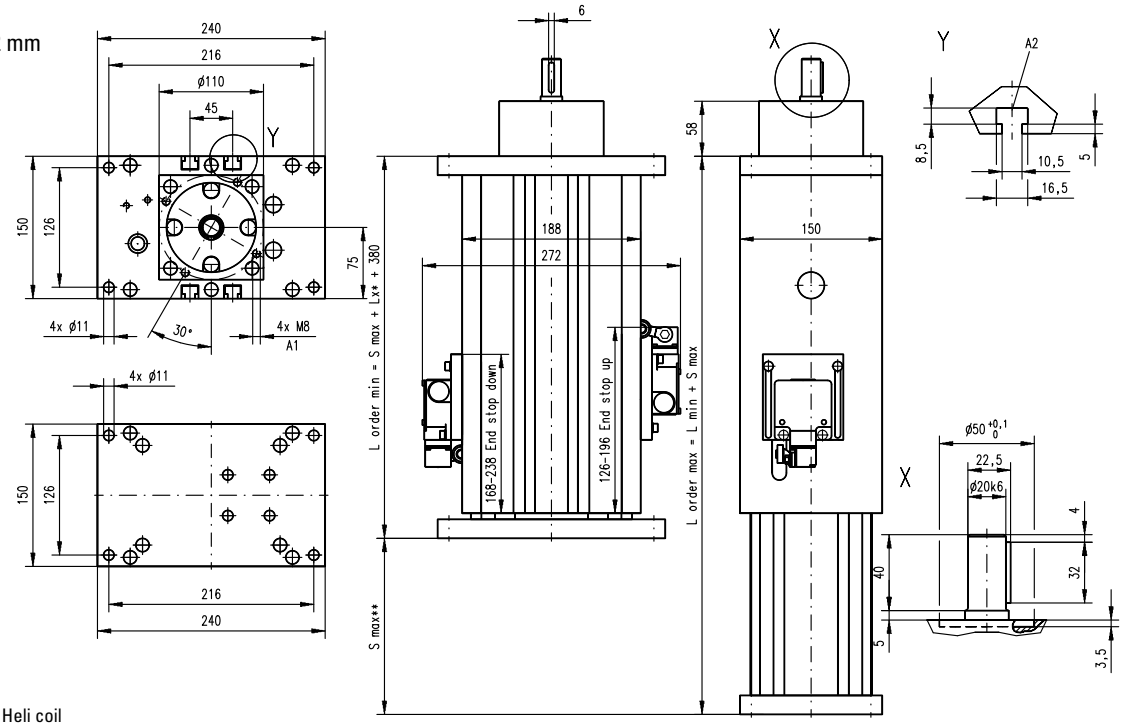
Ball Screw Drive, Slide Guide

MGZ2K25
screw ø25 mm



A1: depth 9, Heli coil
A2: T-slot

MGZ2K32
screw ø32 mm



A1: depth 12, Heli coil
A2: T-slot

Type of unit	Minimum retracted length (L min) [mm]	Maximum extended length (L max) [mm]
Standard	L min = S max + 380	L max = L min + S max
Elongated*	L min = S max + 380 + Lx	L max = L min + S max

* Elongated versions have an extra length (Lx) added to the total length of the unit which makes the unit longer but does not add any extra length to the stroke (S max).

Z3

Ball Screw Drive, Slide Guide

» Ordering key - see page 195
» Accessories - see page 125
» Additional data - see page 174

General Specifications

Parameter	Z3
Profile size (w × h) [mm]	188 × 150
Type of screw	ball screw with single nut
Sealing system	none
Screw supports	none
Lubrication	lubrication of screw and slide surfaces
Included accessories	none

Performance Specifications

Parameter		Z3
Stroke length (S max), maximum	[mm]	1500
Linear speed, maximum	[m/s]	1,25
Acceleration, maximum	[m/s²]	8
Repeatability	[± mm]	0,1
Input speed, maximum screw diameter/lead [mm] 25/10, 25/25 screw diameter/lead [mm] 32/20	[rpm]	 3000 2500
Operation temperature limits	[°C]	-20 – 70
Dynamic load (Fz), maximum screw diameter/lead [mm] 25/10, 25/25 screw diameter/lead [mm] 32/20	[N]	 5000 7500
Dynamic load torque (Mx), maximum	[Nm]	2000[1]
Dynamic load torque (My), maximum	[Nm]	2000[1]
Dynamic load torque (Mz), maximum	[Nm]	330[1]
Drive shaft force (Frd), maximum screw diameter/lead [mm] 25/10, 25/25 screw diameter/lead [mm] 32/20	[N]	 1000 1200
Drive shaft torque (Mta), maximum screw diameter/lead [mm] 25/10, 25/25 screw diameter/lead [mm] 32/20	[Nm]	 45 93
Screw versions, diameter (d0) / lead (p)	[mm]	25/10, 25/25, 32/20
Weight of unit with zero stroke, ball screw ø 25 mm of unit with zero stroke, ball screw ø 32 mm of every 100 mm of stroke, ball screw ø 25 mm of every 100 mm of stroke, ball screw ø 32 mm	[kg]	 21,14 22,65 4,20 4,50

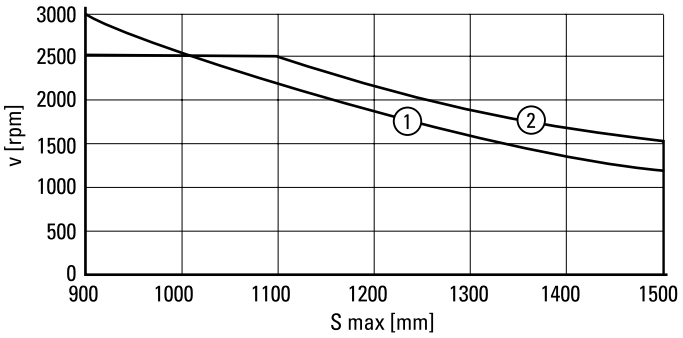
[1] Value for the complete uniy

Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw diameter/lead [mm]		
	d0 = 25 / p = 10	d0 = 25 / p = 25	d0 = 32 / p = 20
500	1,1	2,7	2,2

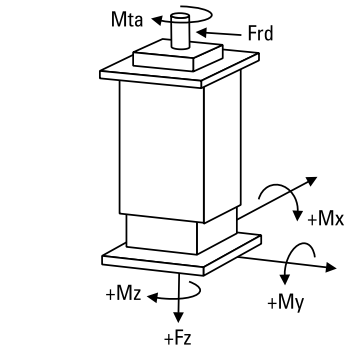
M idle = the input torque needed to move the lifting profiles without any load.

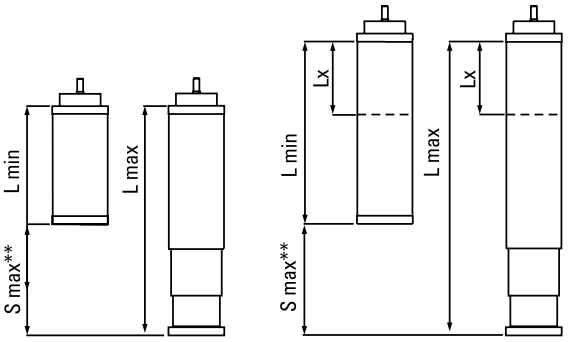
Critical Speed



1: screw diameter 25 mm
2: screw diameter 32 mm

Definition of Forces and Stroke



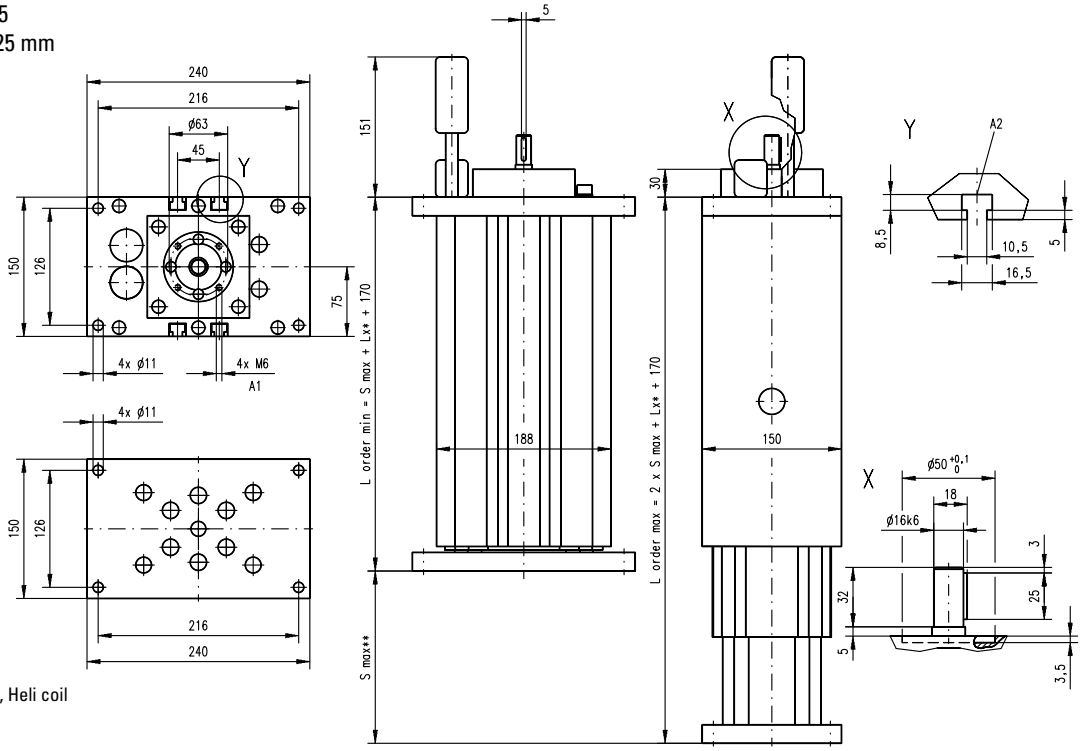


** S max = maximum stroke between the mechanical ends of the unit. The practical stroke is normally 100 mm shorter to avoid running into the ends of the unit.

Z3

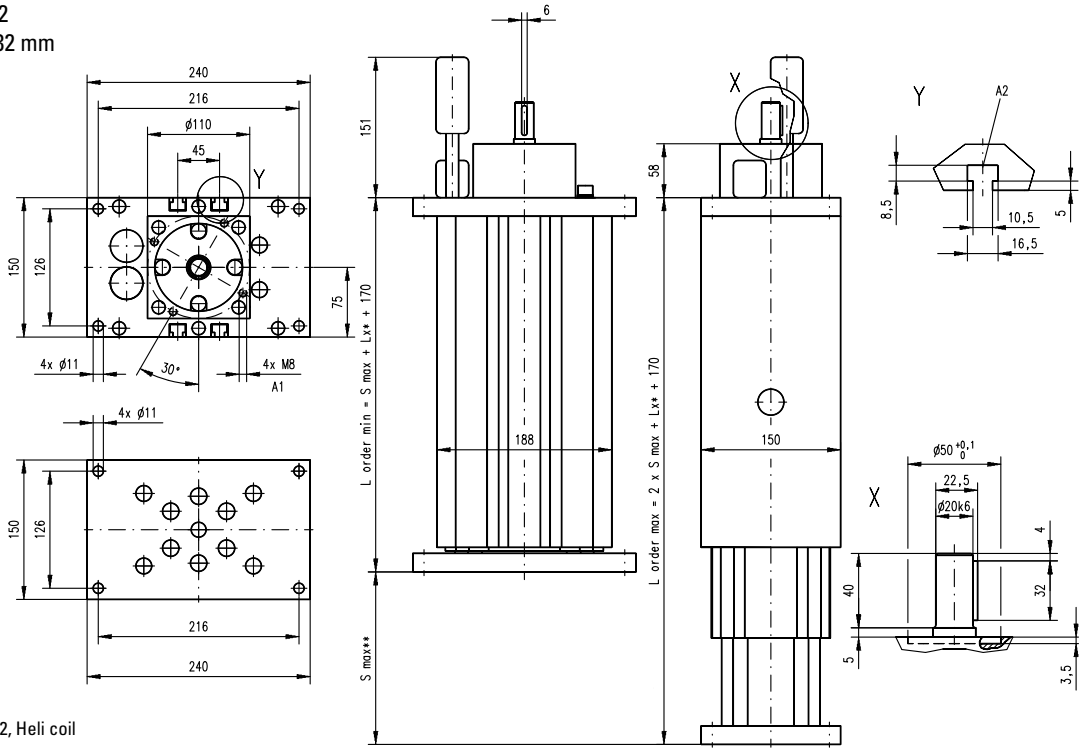
Ball Screw Drive, Slide Guide

MGZ3K25
screw ø25 mm



A1: depth 9, Heli coil
A2: T-slot

MGZ3K32
screw ø32 mm



A1: depth 12, Heli coil
A2: T-slot

Type of unit	Minimum retracted length (L min) [mm]	Maximum extended length (L max) [mm]
Standard	L min = S max + 170	L max = L min + S max
Elongated*	L min = S max + 170 + Lx	L max = L min + S max

* Elongated versions have an extra length (Lx) added to the total length of the unit which makes the unit longer but does not add any extra length to the stroke (S max).

ZB

Belt Drive, Ball Guide

» Ordering key - see page 196
» Accessories - see page 125
» Additional data - see page 174

General Specifications

Parameter	ZB
Profile size (w × h) [mm]	88 × 88
Type of belt	50 AT 10
Carriage sealing system	none
Adjustable belt tensioning	the belt can be retensioned by the customer if necessary
Lubrication	lubrication of drive station in two points
Included accessories	none

Performance Specifications

Parameter		ZB
Stroke length (S max), maximum	[mm]	2500
Linear speed, maximum	[m/s]	3,0
Acceleration, maximum	[m/s²]	40
Repeatability	[± mm]	0,1
Input speed, maximum	[rpm]	900
Operation temperature limits	[°C]	-20 – 70
Dynamic load (Fz), maximum	[N]	500
Dynamic load torque (Mx), maximum	[Nm]	445[1] / 3340[2]
Dynamic load torque (My), maximum	[Nm]	445[1] / 3340[2]
Dynamic load torque (Mz), maximum	[Nm]	35[1] / 262[2]
Drive shaft force (Frd), maximum	[N]	600
Drive shaft torque (Mta), maximum	[Nm]	34
Pulley diameter	[mm]	63,66
Stroke per shaft revolution	[mm]	200
Weight of unit with zero stroke of every 100 mm of stroke of the drive station box	[kg]	 15,50 0,86 16,20

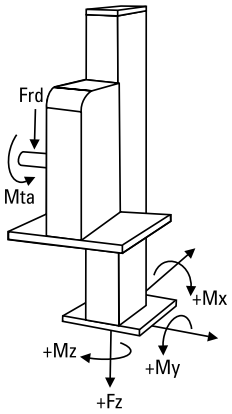
[1] Value for the complete unit
[2] Value for the ball guide only

Idle Torque, (M idle) [Nm]

Input speed [rpm]	Idle torque [Nm]
500	6,4

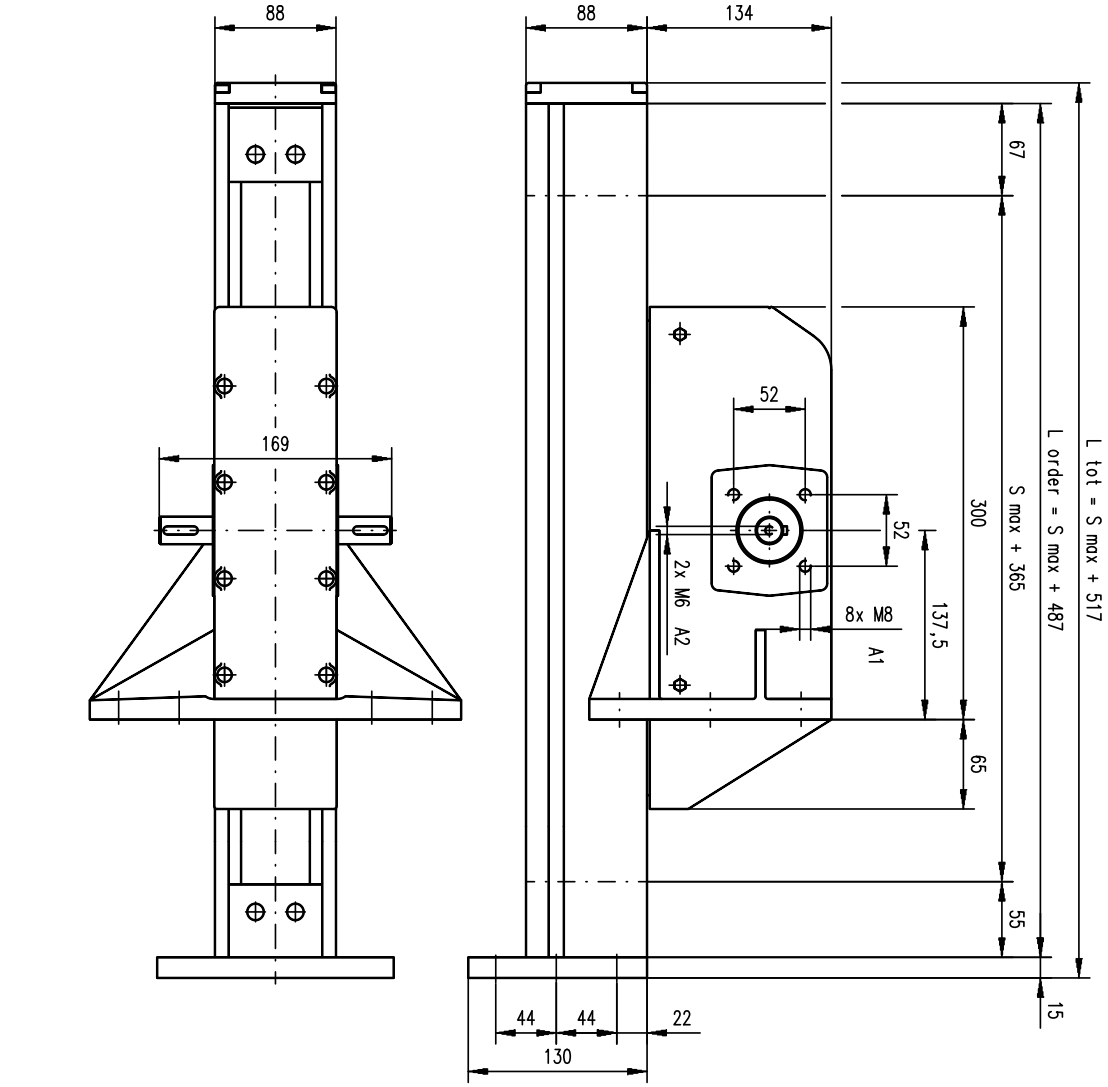
M idle = the input torque needed to move the lifting profile with no load on it.

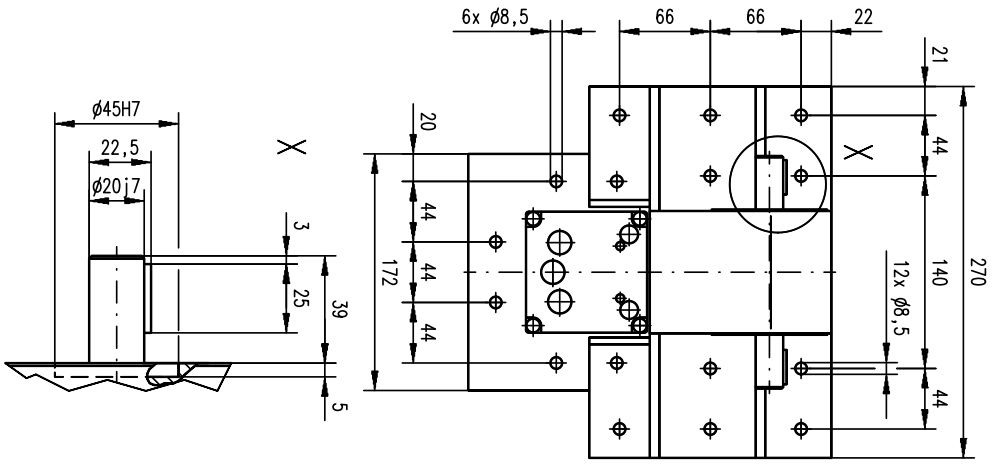
Definition of Forces



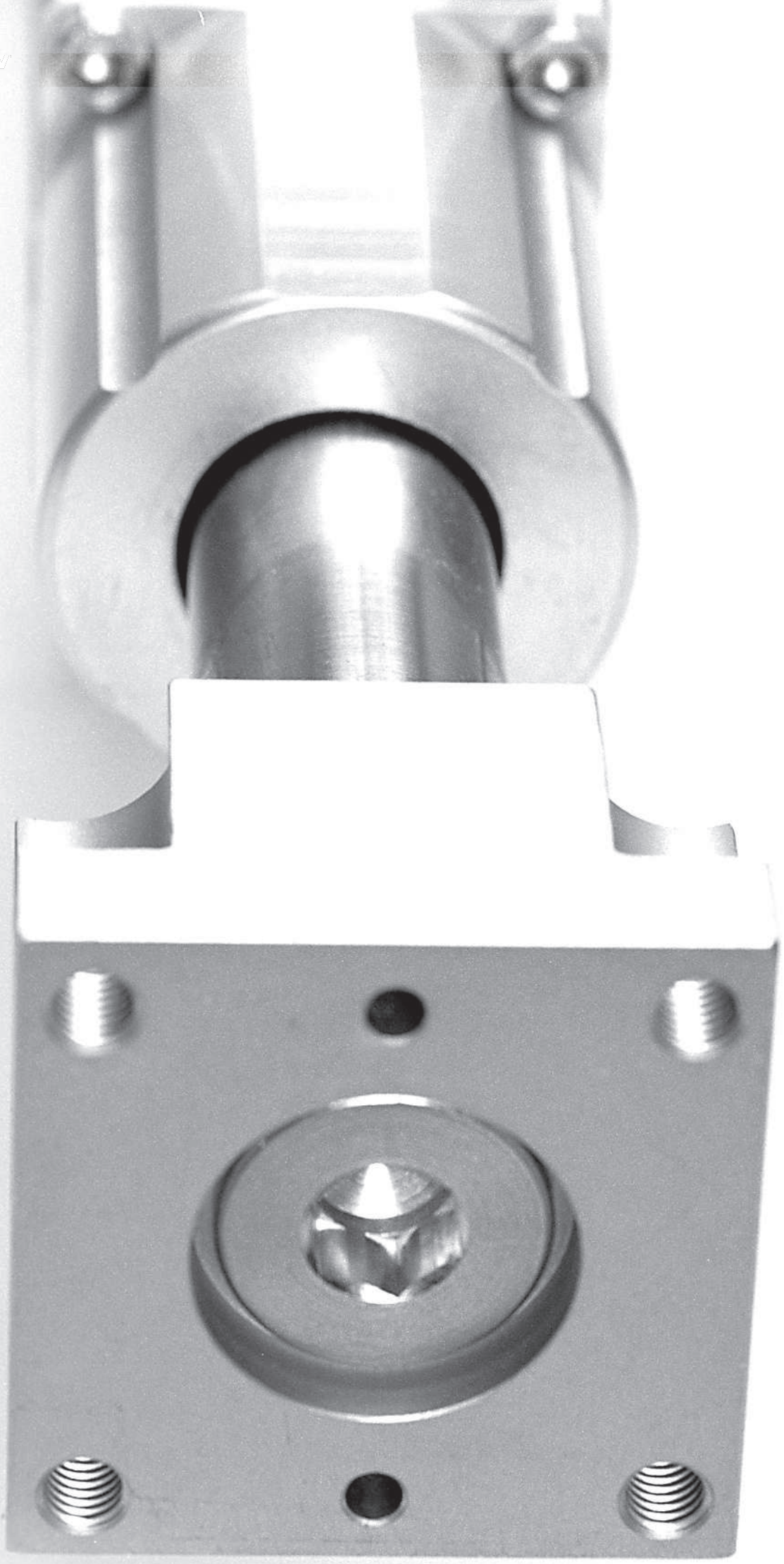
ZB

Belt Drive, Ball Guide



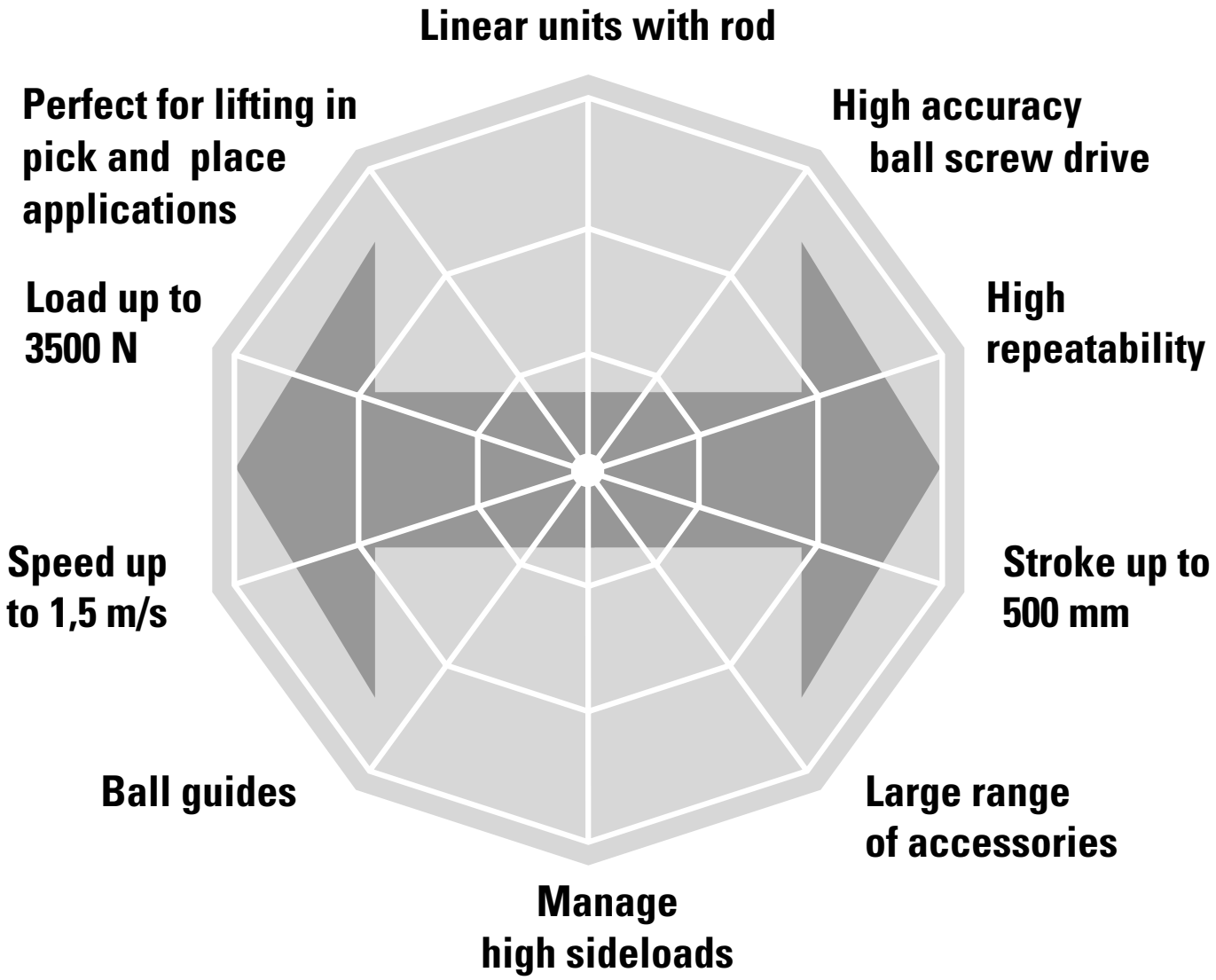


A1: depth 17
A2: depth 20



Linear Rod Units

VarioLine



Typical Applications

The typical use for these units are as a Z-axis in various types of machines. Other suitable areas are in the replacement of pneumatic cylinders needs or where a rod type unit is prefered.

Linear Rod Units

Overview

VarioLine WZ

Features

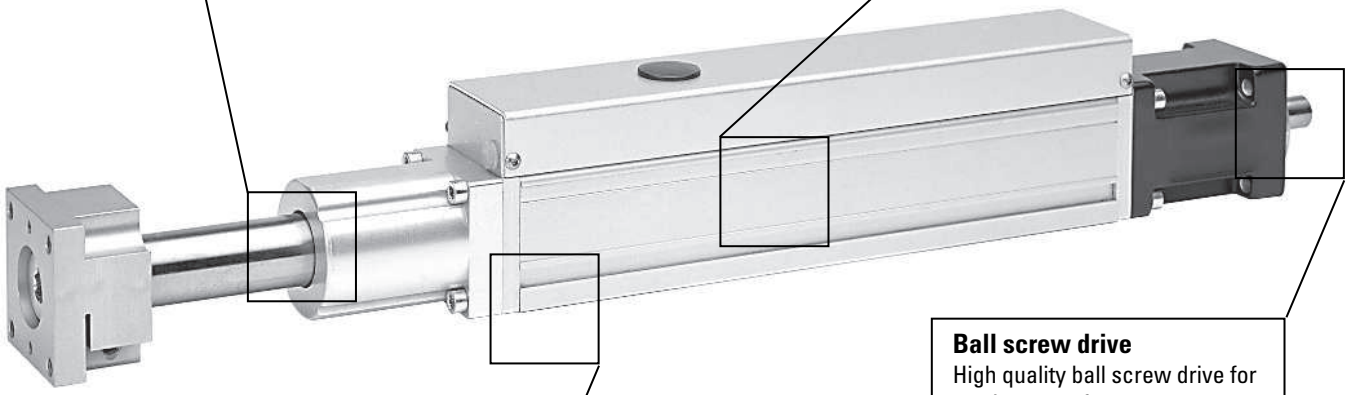
- Can be installed in all directions
- Ball screw drive
- Ball guides
- Compact

Parameter		WZ60	WZ80
Profile size (width × height)	[mm]	60 × 60	80 × 80
Stroke length (S max), maximum	[mm]	400	500
Linear speed, maximum	[m/s]	1,5	1,5
Dynamic carriage load (Fx), maximum	[N]	2800	3500
Remarks		-	-
Page		120	122

Linear Rod Units

Overview

WZ-Series Technical Presentation



High sideloads
The design of the extension tube allows the unit to handle high sideloads as well as torsional forces.

Ball guides
The ball guides ensure smooth and accurate operation.

Ball screw drive
High quality ball screw drive for maximum performance.

Compact design
The compact design allow the unit to be used in equipment where a linear motion system with a carriage would not fit.

WZ60

Ball Screw Drive, Ball Guide

» Ordering key - see page 197
» Accessories - see page 125
» Additional data - see page 175

General Specifications

Parameter	WZ60
Profile size (w × h) [mm]	60 × 60
Type of screw	single nut ball screw
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WZ60
Stroke length (S max), maximum	[mm]	400
Linear speed, maximum	[m/s]	1,5
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,02
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	2800[1]
Dynamic load (Fy), maximum	[N]	2000[2]
Dynamic load (Fz), maximum	[N]	2000[2]
Dynamic load torque (Mx), maximum	[Nm]	50[1]
Drive shaft force (Frd), maximum	[N]	500
Drive shaft torque (Mta), maximum	[Nm]	30
Ball screw diameter (d_0)	[mm]	20
Ball screw lead (p)	[mm]	5, 20, 50
Weight	[kg]	
of unit with zero stroke		4,5
of every 100 mm of stroke		0,77
of the rod with zero stroke		1,8
of every 100 mm of rod		0,26

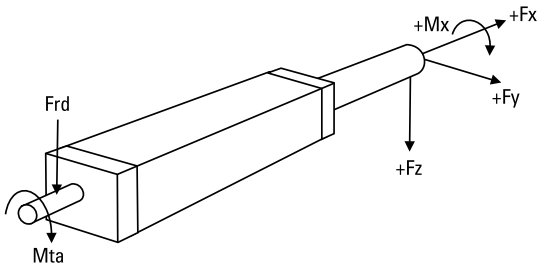
[1] Value for the complete unit
[2] See diagram Maximum Rod Side Forces (Fy, Fz)

Rod Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]		
	p = 5	p = 20	p = 50
150	0,7	1,0	1,4
1500	1,1	1,6	2,0
3000	1,5	1,8	2,2

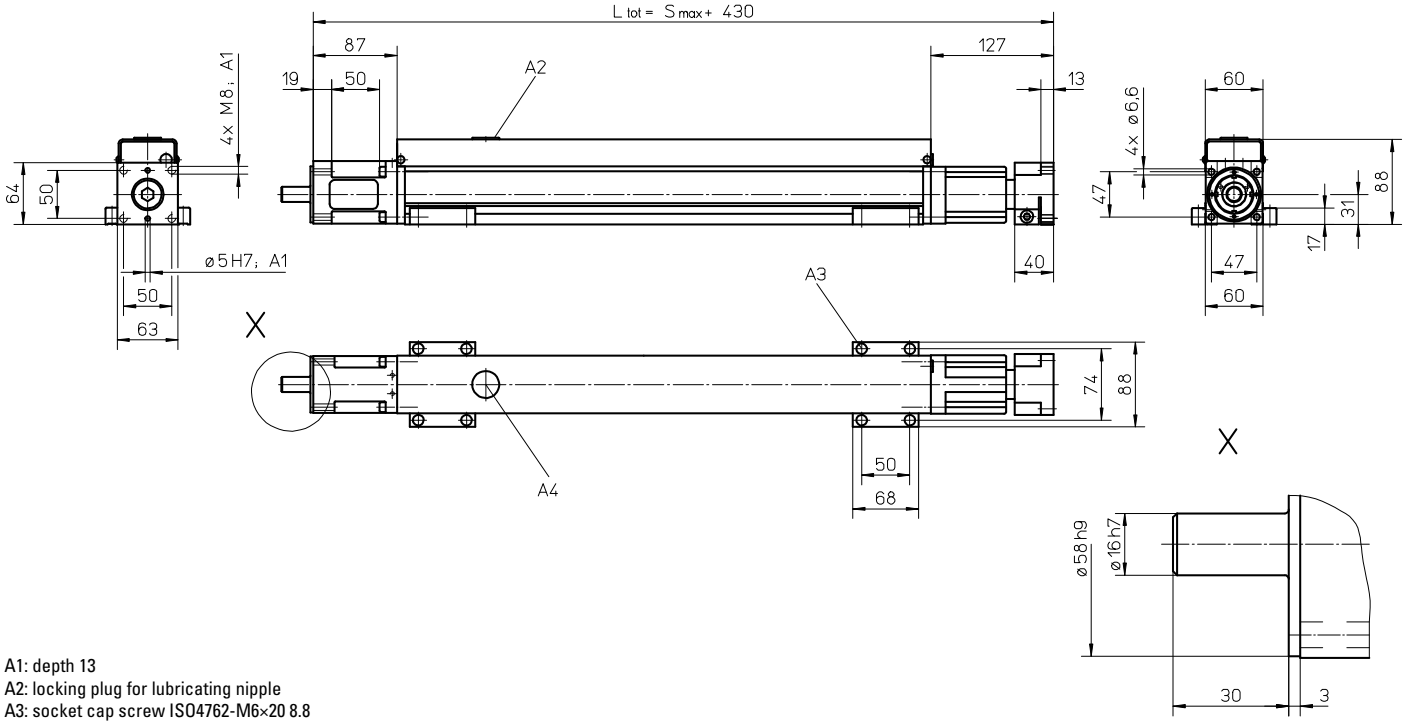
M idle = the input torque needed to move the rod with no load on it.

Definition of Forces



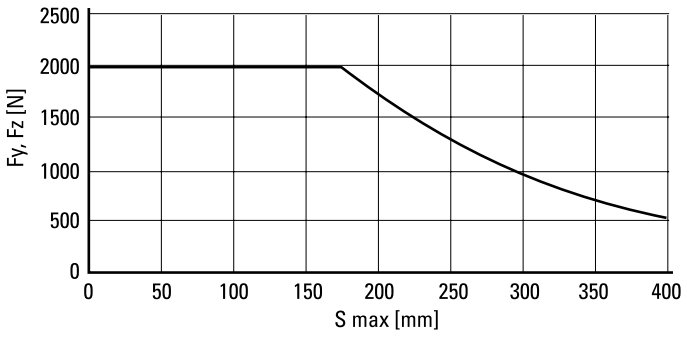
WZ60

Ball Screw Drive, Ball Guide

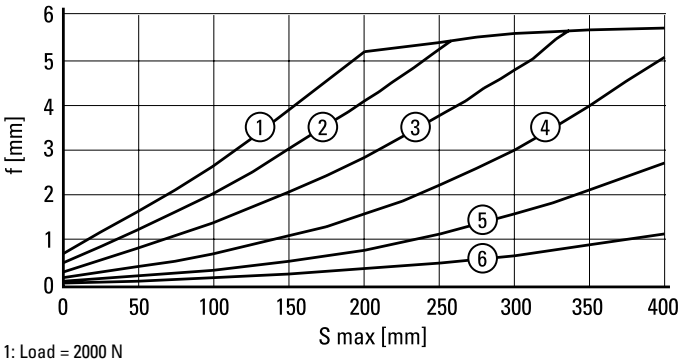


A1: depth 13
A2: locking plug for lubricating nipple
A3: socket cap screw ISO4762-M6×20 8.8
A4: tapered lubricating nipple to DIN71412 AM6 as standard feature

Maximum Rod Side Forces (Fy, Fz)

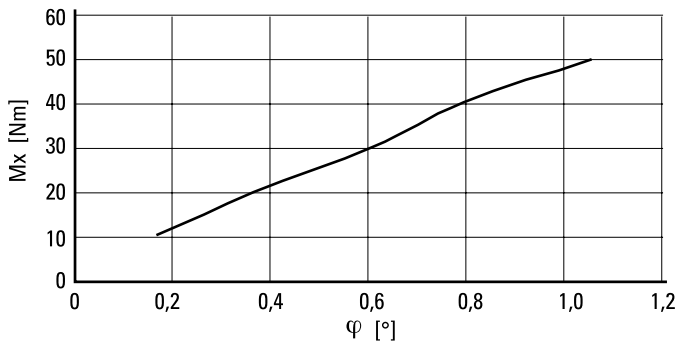


Deflection (f) of Rod due to Fy and Fz



1: Load = 2000 N
2: Load = 1500 N
3: Load = 1000 N
4: Load = 500 N
5: Load = 250 N
6: Load = 125 N

Torsion (φ) of Rod due to Mx



WZ80

Ball Screw Drive, Ball Guide

» Ordering key - see page 197
» Accessories - see page 125
» Additional data - see page 175

General Specifications

Parameter	WZ80
Profile size (w × h) [mm]	80 × 80
Type of screw	single nut ball screw
Lubrication	central lubrication of all parts that require lubrication
Included accessories	4 × mounting clamps

Performance Specifications

Parameter		WZ80
Stroke length (S max), maximum	[mm]	500
Linear speed, maximum	[m/s]	1,5
Acceleration, maximum	[m/s²]	20
Repeatability	[± mm]	0,02
Input speed, maximum	[rpm]	3000
Operation temperature limits	[°C]	0 – 80
Dynamic load (Fx), maximum	[N]	3500[1]
Dynamic load (Fy), maximum	[N]	3000[2]
Dynamic load (Fz), maximum	[N]	3000[2]
Dynamic load torque (Mx), maximum	[Nm]	150[1]
Drive shaft force (Frd), maximum	[N]	700
Drive shaft torque (Mta), maximum	[Nm]	55
Ball screw diameter (d_0)	[mm]	25
Ball screw lead (p)	[mm]	5, 10, 20, 50
Weight	[kg]	
of unit with zero stroke		7,5
of every 100 mm of stroke		1,35
of the rod with zero stroke		3,0
of every 100 mm of rod		0,5

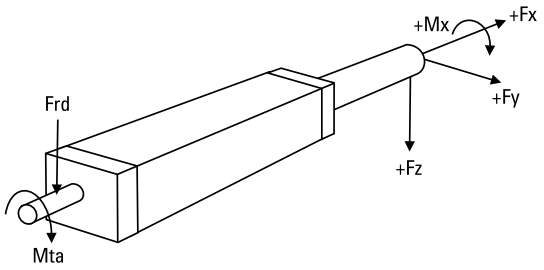
[1] Value for the complete unit
[2] See diagram Maximum Rod Side Forces (Fy, Fz)

Rod Idle Torque (M idle) [Nm]

Input speed [rpm]	Screw lead [mm]			
	p = 5	p = 10	p = 20	p = 50
150	0,6	1,1	1,3	1,8
1500	1,1	1,5	1,6	2,2
3000	1,4	1,8	1,8	2,7

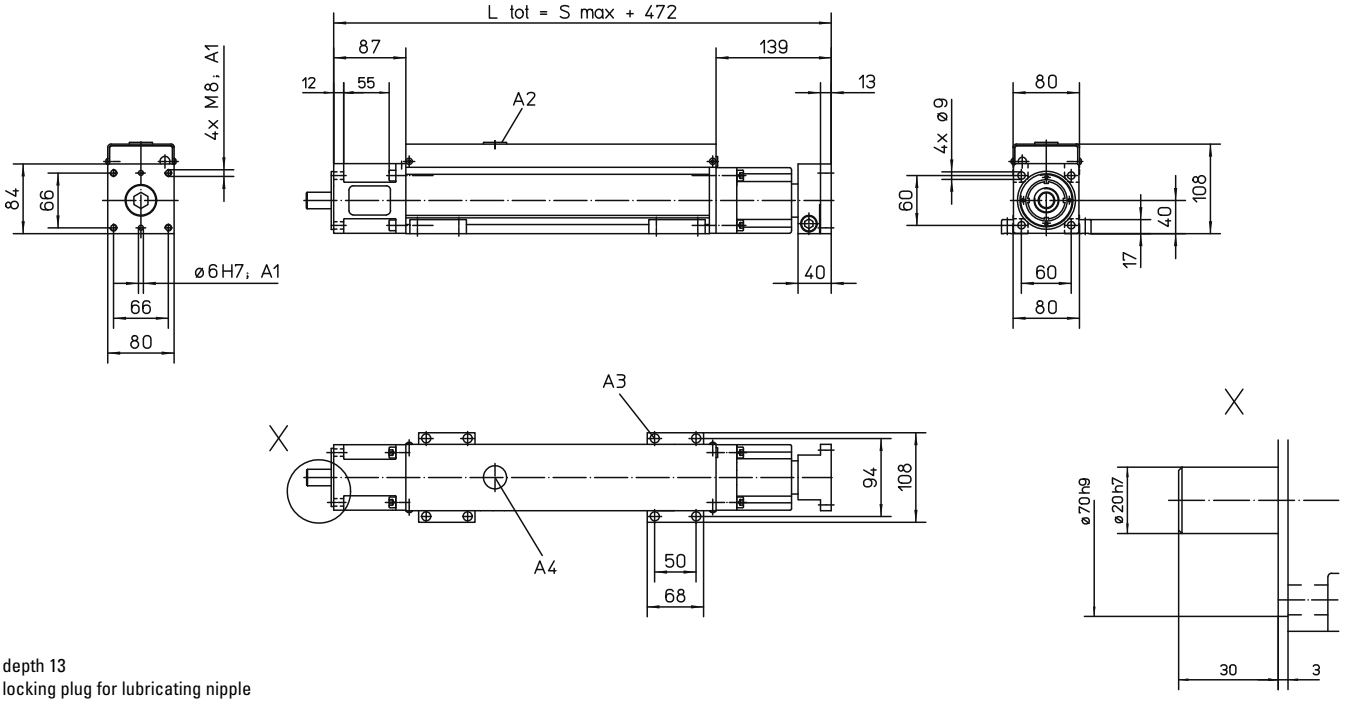
M idle = the input torque needed to move the rod with no load on it.

Definition of Forces



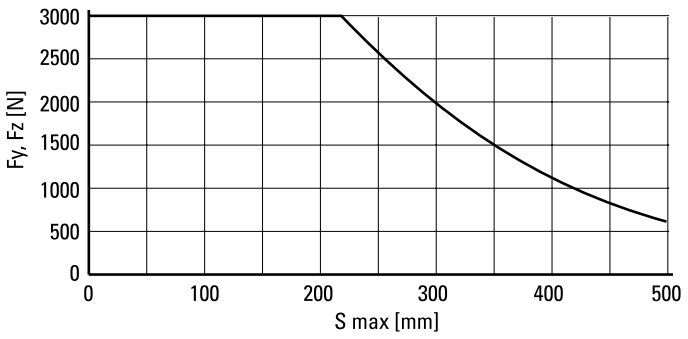
WZ80

Ball Screw Drive, Ball Guide

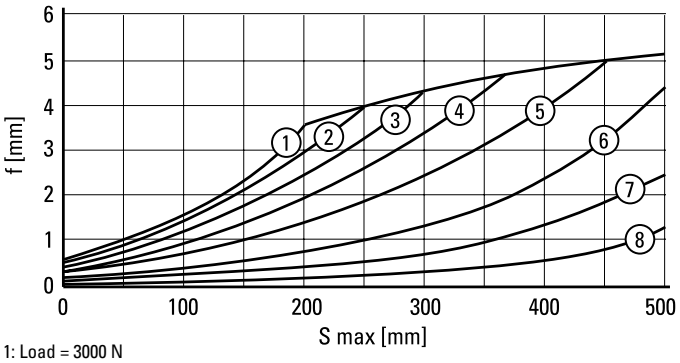


A1: depth 13
A2: locking plug for lubricating nipple
A3: socket cap screw ISO4762-M6×20 8.8
A4: tapered lubricating nipple to DIN71412 AM6 as standard feature

Maximum Rod Side Forces (Fy, Fz)

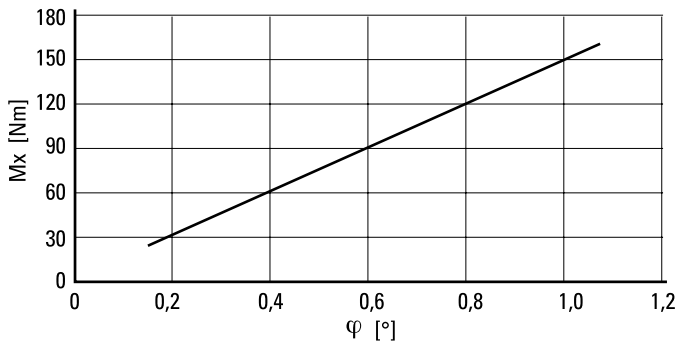


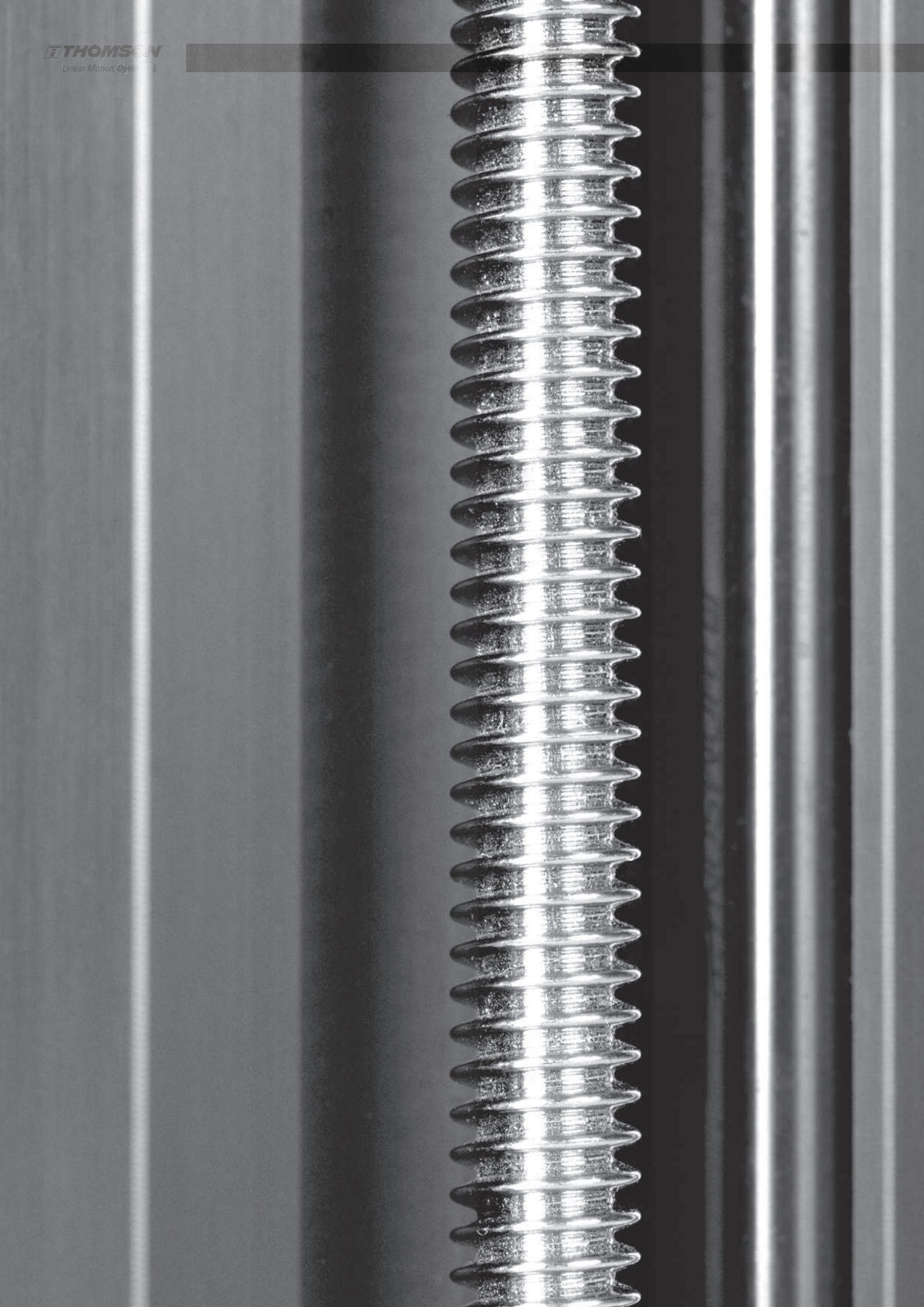
Deflection (f) of Rod due to Fy and Fz



1: Load = 3000 N
2: Load = 2500 N
3: Load = 2000 N
4: Load = 1500 N
5: Load = 1000 N
6: Load = 500 N
7: Load = 250 N
8: Load = 125 N

Torsion (φ) of Rod due to Mx





Accessories

Accessory Index

Accessories

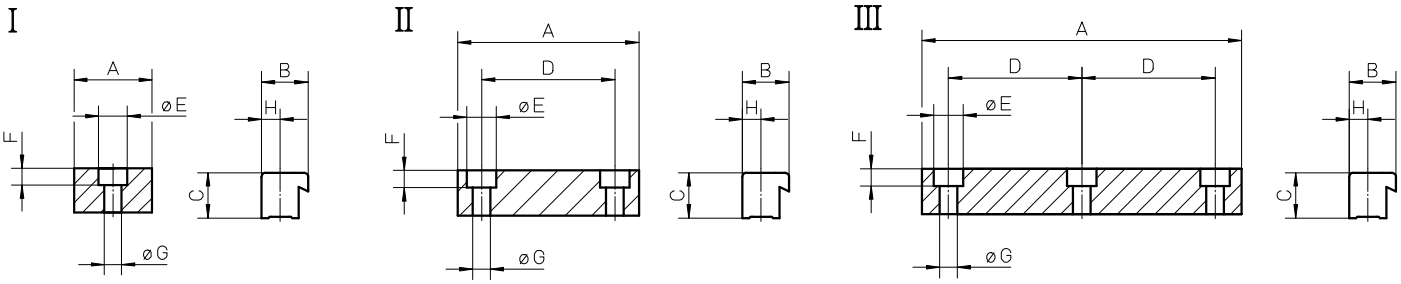
Mounting Kits

Mounting Clamps (single clamp)

Unit type	I	II	III	A	B	C	D	øE	F	øG	H	Screws	Ms [Nm]
WH40	–	890 885 0001	–	54	16	9,5	40	10	5,7	5,5	7	ISO4762-8.8	5,4
WH50	–	890 885 0001	–	54	16	9,5	40	10	5,7	5,5	7	ISO4762-8.8	5,4
WH80 / WB60	–	890 190 02	–	68	17,5	17	50	11	6,5	6,6	7	ISO4762-8.8	9
WH120	–	890 192 13	–	80	25	18	50	15	8,5	9	10	ISO4762-8.8	20
WM40 / WB40	–	890 885 001	–	54	16	9,5	40	10	5,7	5,5	7	ISO4762-8.8	5,4
WM60 / WV60 / WZ60	–	890 190 02	–	68	17,5	17	50	11	6,5	6,6	7	ISO4762-8.8	9
WM80 / WV80 / WZ80	–	890 190 02	–	68	17,5	17	50	11	6,5	6,6	7	ISO4762-8.8	9
WM60Z / WM80Z	–	890 190 02	–	68	17,5	17	50	11	6,5	6,6	7	ISO4762-8.8	9
WM120 / WV120	–	890 192 13	–	80	25	18	50	15	8,5	9	10	ISO4762-8.8	20
MLS60	–	890 190 02	890 192 26	68/120	17,5	17	50	11	6,5	6,6	7	ISO4762-8.8	9
MLS80	–	890 192 13	890 192 31	80/200	25	18	50	15	8,5	9	10	ISO4762-8.8	20
M50 [1]	D312 248	–	–	25	30	20	–	–	–	6,5	14	ISO4762-8.8	9,4
M55 [1]	D313 403	D313 402	–	25/56	25,5	10,7	41	9,5	5,3	5,5	10,2	ISO4762-8.8	5,5
M75 [1]	D312 747	D312 748	–	30/75	28,5	15	60	14	8,5	8,5	11	ISO4762-8.8	23
M100 [1]	D312 339	D312 334	–	45/92	46,5	22	60	17	10,5	10,5	20	ISO4762-8.8	45

[1] no screws included in the shipment of these clamps

Ms = tightening torque of screws



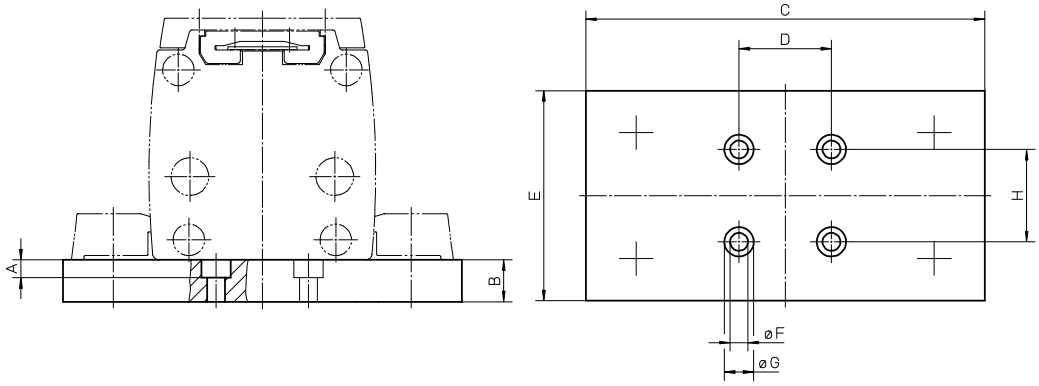
Accessories

Mounting Kits

Mounting Clamps with Plate[1]

Unit type	p/n	A	B	C	D	E	øF	øG	H
M50	D312 117	7	20	105	35	30	6,5	11	–
M55	D313 474	8,5	15	100	44	70	8,5	14	44
M75	D312 718	8,5	15	134	44	80	8,5	14	44
M100	D312 317	8,5	20	190	44	100	8,5	14	44

[1] two mounting clamps of version II (see page 138) and screws to connect these to the plate are included in shipment



Accessories

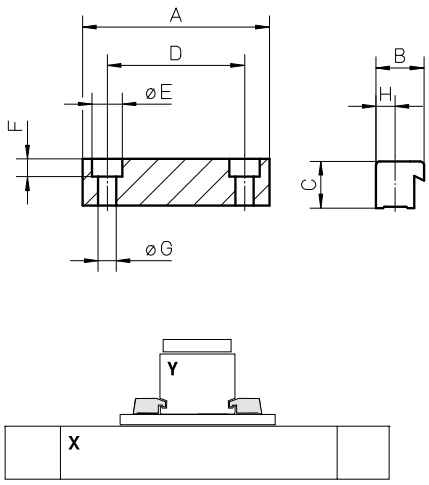
Mounting Kits

Mounting Clamps for Multi Axis Systems[1]

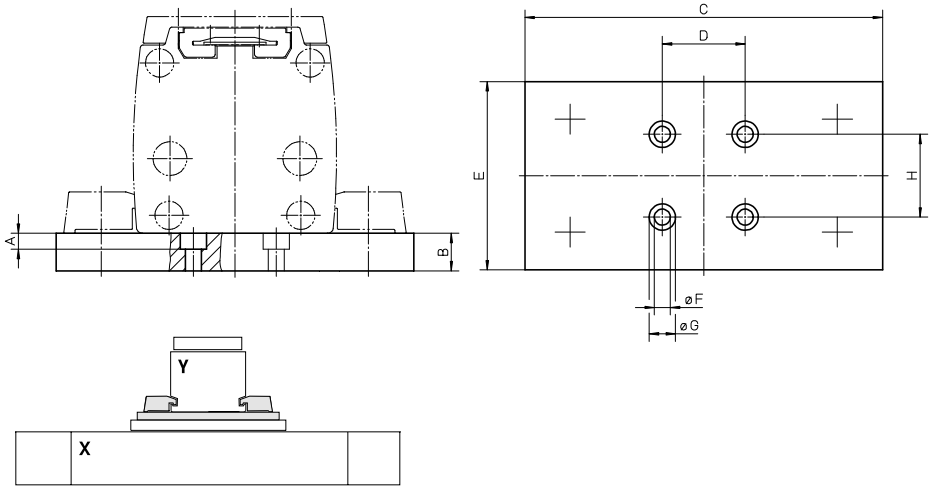
Unit type X-axis	Unit type Y-axis	I	I I	A	B	C	D	øE	F	øG	H
WM40 / WH40	WM40 / WH40	on request	–	–	–	–	–	–	–	–	–
WM60	WM60	890 191 94	–	58	17,5	17	40	11	6,5	6,6	7
M55	M55	D313 424	–	56	25,5	10,7	41	9,5	5,3	5,5	10,2
M55	M75	–	D313 470	5,5	15	134	76	80	5,5	9,5	41
M75	M55	–	D313 060	-	15	134	76	80	M5 × 7,5	-	41
M75	M75	D312 719	–	75	28,5	15	60	14	8,5	8,5	11
M75	M100	–	D313 062	8,5	20	190	106	100	8,5	14	60
M100	M75	–	D313 292	-	20	190	106,5	100	M8 × 12	-	60
M100	M100	D312 304	–	92	46,5	22	60	17	10,5	10,5	20

[1] all necessary screws are included in the shipment

I



II

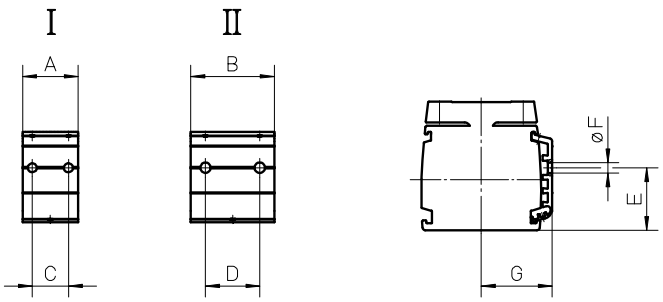


Accessories

Mounting Kits

Adapter Plates

Unit type	I	II	A	B	C	D	E	øF	G
M55	D313 422	D313 423	40	60	20	38	25,5	6,5	37
M75	D312 746	–	40	–	26	-	45	6,5	51
M75	–	D312 745	–	60	-	39	45	7,5	51
M100	D312 338	–	40	–	26	-	69	6,5	62
M100	–	D312 337	–	60	-	39	69	7,5	62



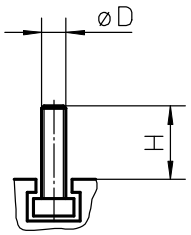
Adapter plates are fitted in the grooves along the profile and can be used to attach objects like sensors, swithes, cable ducts etc. to the unit.

Accessories

Mounting Kits

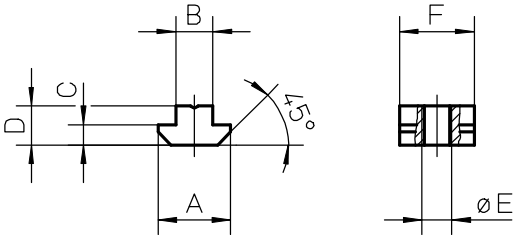
T-slot Bolts

Unit type	p/n	øD	H
M50	D312 221	M5	14
Z2	D800 089	M10	28
Z3	D800 089	M10	28



T-slot Nuts

Unit type	p/n	A	B	C	D	øE	F
ZB	D900 151	18	11	1,5	6,3	M6	25
ZB	D900 150	18	11	1,5	6,3	M8	25
MLS60	920 303 0037	16	8	4	6	M6	16
MLS80	920 303 0039	19,5	10	5,5	10,5	M8	20
WH120	911 044 19	15	10	6	12	M8	15
WM120	911 044 19	15	10	6	12	M8	15

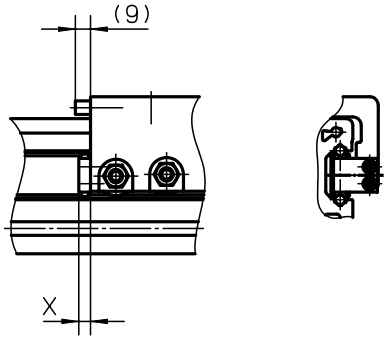


Accessories

Cover and Protection Kits

FA Felt Pad Wiper

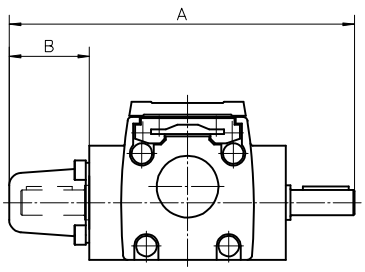
Unit type	Number of carriages on the unit	p/n	X
WH50	1	890 885 0064	6
WH50	2	2 × 890 885 0064	6
WH80	1	890 890 0069	7
WH80	2	2 × 890 890 0069	7
WH120	1	890 895 0058	8
WH120	2	2 × 890 895 0058	8
WHZ50	1	890 885 0064	6
WHZ50	2	2 × 890 885 0064	6
WHZ80	1	890 890 0069	7
WHZ80	2	2 × 890 890 0069	7



The felt pad wipers remove dust and dirt from the guides and are located on the carriage(s). They may increase the driving torque slightly but does not reduce the stroke of the unit. The felt pad wipers comes mounted from factory.

Shaft Protection Cover

Unit type	p/n	A	B
M50	D312 201	126	35
M55	D312 201	151	35
M75	D700 178	198	45
M100	D700 178	202	45



The shaft protection cover is used to cover shafts which is not being used. The cover is fitted by the customer.

Accessories

Cover and Protection Kits

Environment Protection Option Type S1 and S2, compatability table

Unit type	Drive type	Guide type	S1	S2	Ordering
M55	ball screw	slide	•		see ordering key of the unit for order
M55	belt drive	slide	•	•	see ordering key of the unit for order
		ball	•		see ordering key of the unit for order
M75	ball screw	slide	•		see ordering key of the unit for order
M75	belt drive	slide	•	•	see ordering key of the unit for order
		ball	•		see ordering key of the unit for order
M100	ball screw	slide	•		see ordering key of the unit for order
M100	belt drive	slide	•	•	see ordering key of the unit for order
		ball	•		see ordering key of the unit for order

The S1 and S2 environment protection option can be ordered to some units. All performance data and the life expectancy is the same as for standard units. S1 can be ordered for both ball screw and belt driven units with ball or slide guides while S2 only is possible for belt driven slide guided units.

S1 - Wash down protection
Typical places where S1 is used are in slaughter houses, dairy plants, food plants or in any other light wash down application.

S2 - Chemical protection
Typical applications where S2 is used are in wet areas in paper mills, galvanising equipment, chemical industry equipment or in any other application where water, acid and/or basic liquids are present.

Environment Protection Option Type S1 and S2, technical specification

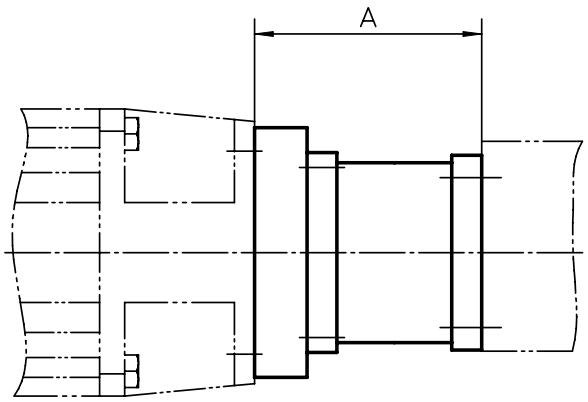
Item	S1	S2
External screws, bolts and nuts	stainless material class A2 or better	stainless material class A4 or better
Internal screws, bolts and nuts	standard material	stainless material class A2 or better
Drive shaft, ball screw driven units	standard material	-
Drive shaft, belt driven units	stainless material SS2333 or better	stainless material SS2343 or better
Tension wheel shaft	standard material	stainless material SS2333 or better
Bearings type	standard bearings	2RS
Bearing sealings, belt driven units	radial sealings	radial sealings
Surface treatment of machined extruded aluminum parts	none	anodising
Surface treatment of machined casted aluminum parts	none	anodising

Accessories

Motors, Gears and Transmission Kits

Bell House Flanges for IEC Motors

Unit type	IEC63 B14	A	IEC71 B14	A	IEC80 B14	A	IEC90 B14	A	IEC100/112 B14	A
M50	D390 820	64	D390 821	71	–	–	–	–	–	–
M55	D390 820	64	D390 821	71	–	–	–	–	–	–
M75	–	–	D390 823	83	D390 912	101	D390 916	101	–	–
M100 (MG10K)	–	–	D390 823	83	D390 913	101	D390 917	101	–	–
M100 (MG10B)	–	–	D390 823	83	D390 912	101	D390 916	101	–	–



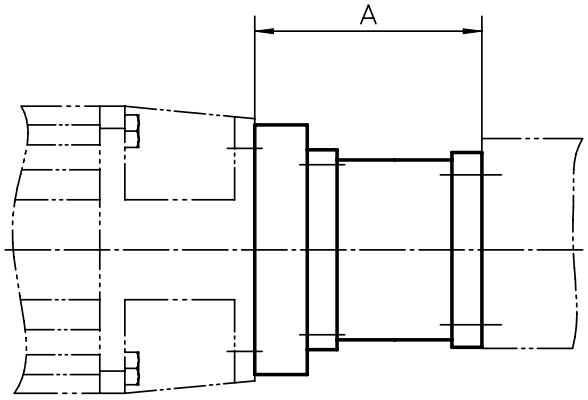
The bell house flange includes a matching coupling. Note! Keep in mind that heavy motors will need extra support in order not to break the flange or gear due to the load torque created.

Accessories

Motors, Gears and Transmission Kits

MGK Bell House Flanges for AKM Servo Motors

Unit type	AKM3 • D-AN	A	AKM4 • D-AN	A	AKM5 • D-AN	A	AKM6 • D-AN	A	AKM7 • D-AN	A
WM40	891 092 1264	71	–	–	–	–	–	–	–	–
WB40	891 092 1263	63	–	–	–	–	–	–	–	–
WB60	891 092 1265	75	–	–	–	–	–	–	–	–
WM60 / WV60 / WZ60	891 092 1109	79	891 092 1262	89	891 092 1261	103	–	–	–	–
WM80 / WV80 / WZ80	D321 553	79	–	–	891 092 1259	101	891 092 1258	117	–	–
WM120 / WV120	–	–	–	–	–	–	891 092 1257	121	891 092 1255	143
MLSM60	–	–	891 092 0909	88	891 092 1260	98	–	–	–	–
MLSM80	–	–	–	–	–	–	891 092 1256	111	891 092 1254	133
M55 (MG06K)	D390 930	73	D389 939	92	–	–	–	–	–	–
M75 (MG07K)	D390 966	83	D390 926	93	D390 909	107	–	–	–	–
M75 (MG07B)	D390 966	83	D390 926	93	D390 909	107	–	–	–	–
M100 (MG10K)	D390 966	83	D390 927	93	D390 910	107	–	–	–	–
M100 (MG10B)	D390 966	83	D390 926	93	D390 909	107	–	–	–	–



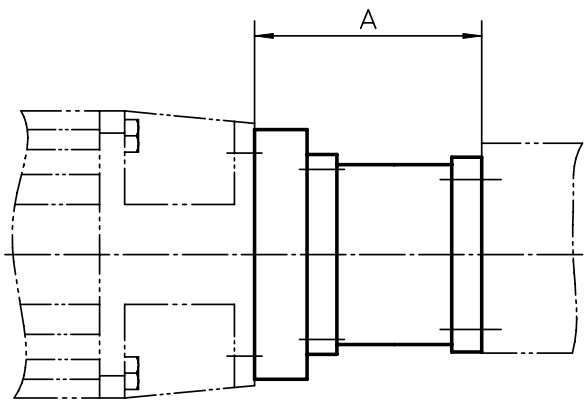
The bell house flange includes a matching coupling. Flanges for other units or motor sizes available on request, contact customer service. Note! Keep in mind that heavy motors will need extra support in order not to break the flange or gear due to the load torque created.

Accessories

Motors, Gears and Transmission Kits

MGK Bell House Flanges for DBL Servo Motors

Unit type	DBL2H	A	DBL3H/M	A	DBL3N	A	DBL4N	A	DBL5N	A	DBL6N	A
WH40	–	–	891 092 0441	61	–	–	891 092 0931	90	–	–	–	–
WH50	–	–	–	–	–	–	891 092 0081	81	–	–	–	–
WH80	–	–	–	–	–	–	891 092 0077	88	891 092 0076	98	891 092 0046	113
WH120	–	–	–	–	–	–	891 092 0929	100	891 092 0086	110	–	–
WM40	891 092 0562	64	891 092 0429	64	–	–	891 092 0932	87	–	–	–	–
WB40	–	–	891 092 0429	56	–	–	–	–	–	–	–	–
WB60	–	–	D390 964	75	–	–	–	–	–	–	–	–
WM60 / WV60 / WZ60	–	–	891 092 0878	78	891 092 0991	78	890 200 0135	89	891 092 0193	103	–	–
WM80 / WV80 / WZ80	–	–	–	–	891 092 0999	79	890 200 0136	91	891 092 0085	101	–	–
WM120 / WV120	–	–	–	–	–	–	891 092 0930	103	891 092 0085	113	891 092 0088	113
WM60Z	–	–	–	–	–	–	891 092 0926	81	–	–	–	–
WM80Z	–	–	–	–	–	–	891 092 0927	88	–	–	–	–
MLSH60	–	–	–	–	–	–	891 092 0928	91	–	–	–	–
MLSM60	–	–	–	–	891 092 0970	76	891 092 0893	88	891 092 0914	98	–	–
M75 (MG07K)	–	–	–	–	–	–	D390 919	101	–	–	–	–
M75 (MG07B)	–	–	–	–	–	–	D390 919	101	–	–	–	–
M100 (MG10K)	–	–	–	–	–	–	D390 920	101	–	–	–	–
M100 (MG10B)	–	–	–	–	–	–	D390 919	101	–	–	–	–



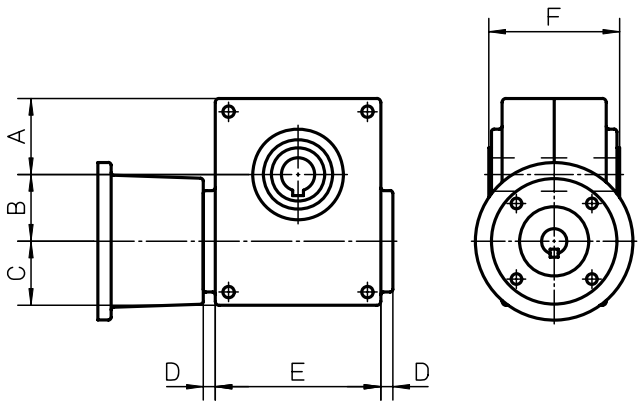
The bell house flange includes a matching coupling. Flanges for other units or motor sizes available on request, contact customer service. Note! Keep in mind that heavy motors will need extra support in order not to break the flange or gear due to the load torque created.

Accessories

Motors, Gears and Transmission Kits

BS40 Worm Gears, dimensions

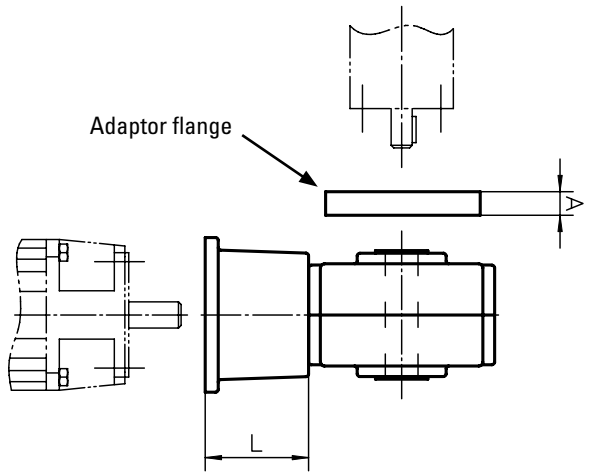
Gear	A	B	C	D	E	F
BS40	54	40	46	10	100	92



The worm gear includes the gear, the bell house and a matching coupling.

BS40 Worm Gears, compatability table

Unit	BS40	IEC71B14	IEC80B14	IEC90B14	A	L
Z2 (MGZ2K32)	•	•			17	58
Z2 (MGZ2K32)	•		•		17	68



To be able to install the gear to the unit an adaptor flange must be used between the gear and the unit. The adaptor flange is ordered separately.

Accessories

Motors, Gears and Transmission Kits

BS40 Worm Gears, ordering key

	1	2	3
Example	**BS40**	**-10**	**-71**

1. Type and size of worm gear	**2. Gear ratio**	**6. Motor size**
BS40 = BS40 worm gear	-3 = 3:1 -5,5 = 5,5:1 -7,5 = 7,5:1 -10 = 10:1 -15 = 15:1 -20 = 20:1 -24 = 24:1 -30 = 30:1 -40 = 40:1 -48 = 48:1 -60 = 60:1	-71 = IEC71B14 -80 = IEC80B14

Adaptor flanges for BS40 Worm Gears, part numbers

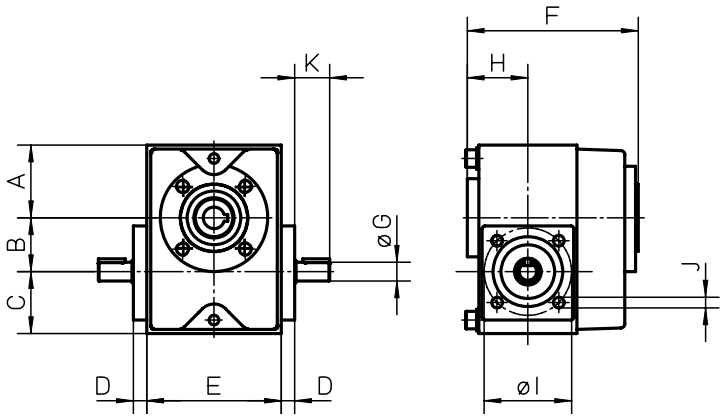
Unit	**p/n**
Z2 (MGZ2K32)	D606 250

Accessories

Motors, Gears and Transmission Kits

TBS40 Worm Gears, dimensions

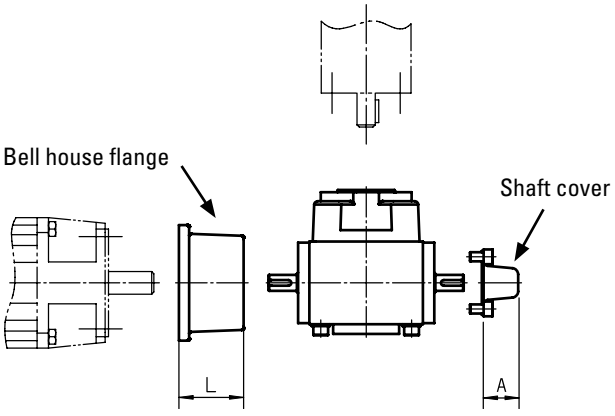
Gear	A	B	C	D	E	F	øG	H	øI	J	K
TBS40	54	40	46	10	100	125	14j6	45	65	M8 (4×)	25



The worm gear is installed directly to the unit and require no intermediate coupling between the two.

TBS40 Worm Gears, compatability table

Unit	TBS40	IEC71B14	IEC80B14	A	L
Z2 (MGZ2K25)	•	•		32	58
Z2 (MGZ2K25)	•		•	32	68
Z3 (MGZ3K25)	•	•		32	58
Z3 (MGZ3K25)	•		•	32	68
M75	•	•		32	58
M75	•		•	32	68
M100	•	•		32	58
M100	•		•	32	68



To be able to install the gear to the motor a bell house flange must be used between the gear and the motor. The bell house flange, which includes a matching coupling, is ordered separately. A shaft cover can be ordered to cover the second primary shaft on the gear in cases it is not being used.

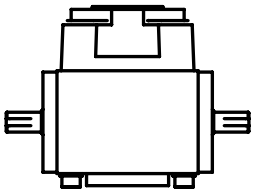
Accessories

Motors, Gears and Transmission Kits

TBS40 Worm Gears, ordering key

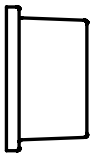
	1	2	3
Example	**TBS40**	**-3**	**-216**

1. Type and size of worm gear	**2. Gear ratio**	**3. Fixed code**
TBS40 = TBS40 worm gear	-3 = 3:1 -5,5 = 5,5:1 -7,5 = 7,5:1 -10 = 10:1 -15 = 15:1 -20 = 20:1 -24 = 24:1 -30 = 30:1 -40 = 40:1 -48 = 48:1 -60 = 60:1	-216



Bell house flanges for TBS40 Worm Gears, part numbers

Motor size	p/n
IEC71B14	D701 011
IEC80B14	D701 015



Shaft Cover for TBS40 Worm Gears, part numbers

Gear type	p/n
TBS40	D701 020

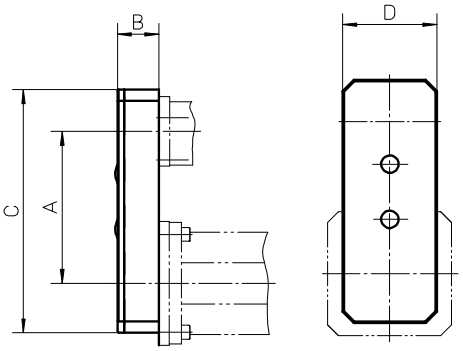
Accessories

Motors, Gears and Transmission Kits

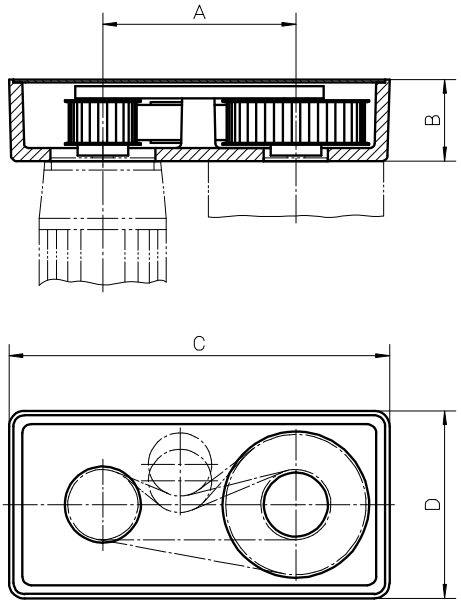
RT Belt Gears, dimensions

Gear	A	B	C	D
RT40	110	30	176	68
RT60	175	74	345	170
RT80	175	74	345	170

RT40



RT60/80



RT Belt Gears, data

Gear	i	nmax [rpm]	Mmax [Nm]	M idle [Nm]	η	J [kgm²]	Weight [kg}
RT40	1:1	3000	1,75	0,3	0,80	0,000025	0,62
RT60	1:1	3000	15	0,7	0,85	0,000438	5,6
RT60	2:1	3000	15	0,7	0,85	0,001011	7,1
RT80	1:1	3000	30	0,7	0,85	0,000465	5,5
RT80	2:1	3000	30	0,7	0,85	0,001038	7

i = gear ratio
nmax = max. input speed
Mmax = max. input torque
M idle = idle torque
η = efficiency factor
J = inertia

Accessories

Motors, Gears and Transmission Kits

RT Belt Gears, compatability table

Gear	WH40 / WM40	WM60 / WV60 / WZ60 / MLSM60D	WH80 / WM80 / WV80 / WM120 / WV120 / MLSM60D / MLSM80D
RT40	•		
RT60		•	
RT80			•

RT Belt Gears, ordering key

	1	2	3	4	5
Example	RT80	-2	-•••	-P-N	-05

1. Type and size of belt gear
RT40 = RT belt gear size 40
RT60 = RT belt gear size 60
RT80 = RT belt gear size 80

2. Gear ratio
-1 = 1:1
-2 = 2:1

3. Motor code
-••• = alphanumeric motor code (e.g. -AK5). There are several motors that fits each gear and the list of suitable motors is continiously being updated. Please contact customer support for help to see which motors currently are on the list or if your prefered motor can be added to the list.

4. Type of mounting
-P-M = gear supplied mounted to the unit
-P-N = gear supplied unmounted

5. Compatable unit type
-01 = WH40
-02 = WH50
-03 = WH80
-04 = WH120
-05 = WM40
-06 = WM60
-07 = WM80
-08 = WM120
-09 = WV60
-10 = WV80
-11 = WV120
-12 = WHZ50
-13 = WHZ80
-14 = WZ60
-15 = WZ80
-16 = MLSH60Z
-17 = MLSH80Z
-18 = MLSM80Z
-19 = MLSM60D
-20 = MLSM80D

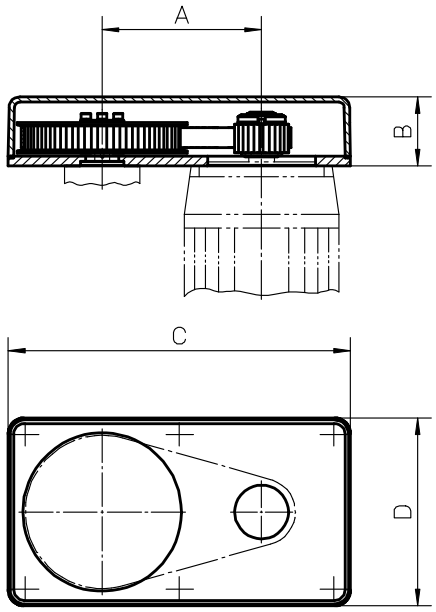
Accessories

Motors, Gears and Transmission Kits

BGM Belt Gears, dimensions

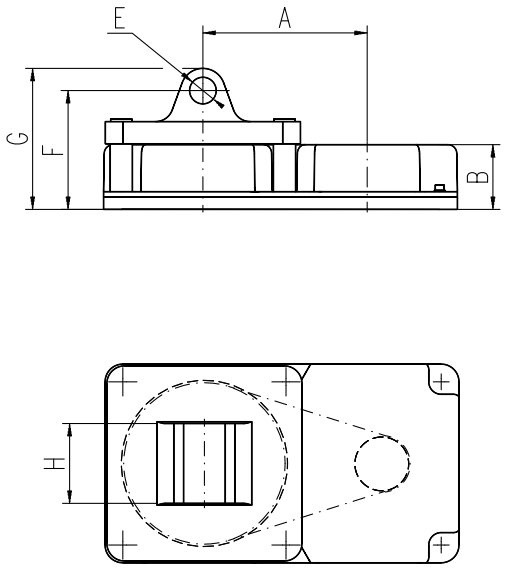
Gear	A	B	C	D	øE	F	G	H	I	J
BGM09	118,7	52	255	140	20 H9	95	115	60	–	–
BGM41	155,2	70	305	165	25 H9	122	147	70	–	–
BGM81	200	73	399	224	30 H9	134	159	90	90H14	170

BGM09/41/81 - WITHOUT CLEVIS OPTION

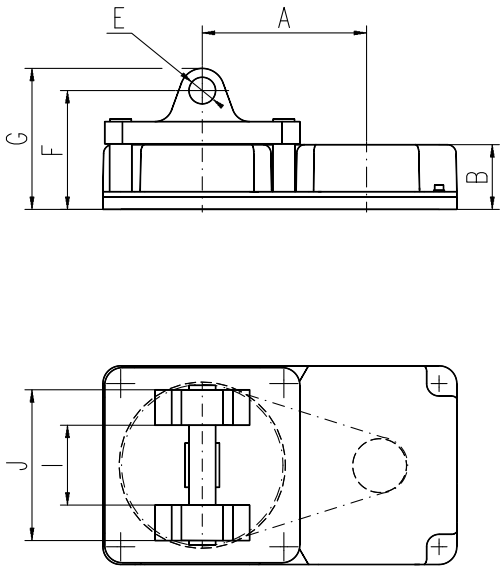


The belt gear comes in parts and is assembled to the unit and motor by the customer.

BGM09/41/81 - WITH CLEVIS OPTION TYPE S



BGM81 - WITH CLEVIS OPTION TYPE R



Accessories

Motors, Gears and Transmission Kits

BGM Belt Gears, data

Gear	i	nmax [rpm]	Mmax [Nm]	η	J [kgm²]	Weight [kg}
BGM09	1,04:1	4000	3,3	0,85	0,000102	2
BGM09	1,85:1	4000	3,3	0,85	0,000112	2,1
BGM09	2,85:1	4000	3,3	0,85	0,000213	2,5
BGM41	1:1	4000	16,6	0,85	0,000438	3,4
BGM41	2:1	4000	9,7	0,85	0,000342	3,7
BGM41	3:1	4000	9,7	0,85	0,000583	4,6
BGM81	1:1	4000	32	0,85	0,000836	12,1
BGM81	2,25:1	4000	30	0,85	0,001051	12,9
BGM81	3,13:1	4000	28	0,85	0,001439	14

i = gear ratio
nmax = max. input speed
Mmax = max. input torque
η = efficiency factor
J = inertia

BGM Belt Gears, compatability table

Gear	WM/V/Z60	WM/V80	WM/V120	MLSM60D/80D	MLSH80Z	WB60	M50	M55	M75	M100	Z2
BGM09	•					•	•	•	•		
BGM41	•	•							•	•	•
BGM81			•	•	•						

BGM Belt Gears, ordering keys

See next page for ordering keys.

Accessories

Motors, Gears and Transmission Kits

BGM 09 Belt Gears, ordering key

	1	2	3	4	5	6	7
Example	BGM09	-2	-CC	063	P	050	X

1. Type and size of belt gear
BGM09 = BGM belt gear size 09

2. Gear ratio
-1 = 1,04:1
-2 = 1,85:1
-3 = 2,85:1

3. Type of couplings
-CC = conical couplings

4. Motor size[1]
063 = IEC 63 B14
071 = IEC 71 B14
S80 = servo motor size 80
AK4 = servo motor type AKM 4

5. Type of mounting
P = standard

6. Compatable unit type
W06 = WM60, WV60, WZ60
WB6 = WB60
050 = M50
060 = M55
070 = M75

7. Clevis option
X = no clevis option
S = clevis option type S

[1]This is only a selection of all motors that fits this gear. Please contact customer support to see if your prefered motor fits the gear.

BGM 41 Belt Gears, ordering key

	1	2	3	4	5	6	7
Example	BGM41	-1	-CC	071	P	070	X

1. Type and size of belt gear
BGM41 = BGM belt gear size 41

2. Gear ratio
-1 = 1:1
-2 = 2:1
-3 = 3:1

3. Type of couplings
-CC = conical couplings

4. Motor size[1]
071 = IEC 71 B14
080 = IEC 80 B14
S80 = servo motor size 80
S95 = servo motor size 95
AK5 = servo motor type AKM 5

5. Type of mounting
P = standard

6. Compatable unit type
W06 = WM60, WV60, WZ60
W08 = WM80, WV80
070 = M75
10B = M100 (MF/G10B)
10K = M100 (MF/G10K/C/D)

7. Clevis option
X = no clevis option
S = clevis option type S

[1]This is only a selection of all motors that fits this gear. Please contact customer support to see if your prefered motor fits the gear.

Accessories

Motors, Gears and Transmission Kits

BGM 81 Belt Gears, ordering key

	1	2	3	4	5	6	7
Example	BGM81	-1	-CC	090	P	M6D	X

1. Type and size of belt gear
BGM81 = BGM belt gear size 81

2. Gear ratio
-1 = 1:1
-2 = 2,25:1
-3 = 3,13:1

3. Type of couplings
-CC = conical couplings

4. Motor size[1]
090 = IEC 90 B14
100 = IEC 100/121 B14
A20 = servo motor size A200
AK6 = servo motor type AKM 6

5. Type of mounting
P = standard

6. Compatable unit type
W12 = WM120, WV120
M6D = MLSM60D
M8D = MLSM80D
M8Z = MLSH80Z

7. Clevis option
X = no clevis option
S = clevis option type S
R = clevis option type R

[1]This is only a selection of all motors that fits this gear. Please contact customer support to see if your prefered motor fits the gear.

Accessories

Motors, Gears and Transmission Kits

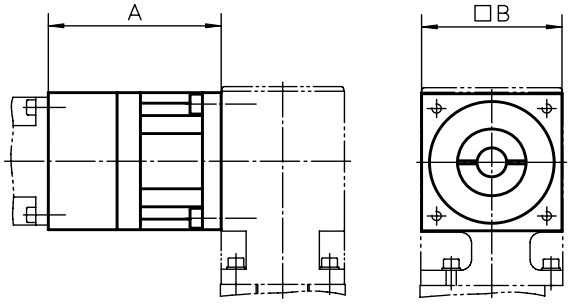
Micron DT, DTR Planetary Gears, compatability and dimensions

Unit	Gear	i	□A	B	C	□D	E	Weight [kg]	Backlash [arc min]	Efficiency [%]
WH50	DT60-SS	3:1 - 10:1	89,7	60	–	–	–	1	8	90
	DT60-DS	15:1 - 100:1	106,9	60	–	–	–	1,2	9	85
	DTR60-SS	5:1 - 50:1	–	–	110,2	104,1	60	2,5	9	90
	DTR60-DS	60:1 - 500:1	–	–	127,3	104,1	60	2,7	9	85
WH80	DT90-SS	3:1 - 10:1	110,9	90	–	–	–	3	9	90
	DT90-DS	15:1 - 100:1	133,5	90	–	–	–	3,7	9	85
	DTR90-SS	5:1 - 50:1	–	–	145,4	138,2	90	4,8	9	90
	DTR90-DS	60:1 - 500:1	–	–	168,0	138,2	90	5,5	9	85
WH120	DT115-SS	3:1 - 10:1	136,4	110	–	–	–	12,7	8	90
	DT115-DS	15:1 - 100:1	167,4	110	–	–	–	16,2	9	85
	DTR115-SS	5:1 - 50:1	–	–	185,7	173,5	115	11	8	90
	DTR115-DS	60:1 - 500:1	–	–	216,7	173,5	115	12	9	85
WM60Z	DT60-SS	3:1 - 10:1	89,7	60	–	–	–	1	8	90
	DT60-DS	15:1 - 100:1	106,9	60	–	–	–	1,2	9	85
	DTR60-SS	5:1 - 50:1	–	–	110,2	104,1	60	2,5	9	90
	DTR60-DS	60:1 - 500:1	–	–	127,3	104,1	60	2,7	9	85
WM80Z	DT90-SS	3:1 - 10:1	110,9	90	–	–	–	3	9	90
	DT90-DS	15:1 - 100:1	133,5	90	–	–	–	3,7	9	85
	DTR90-SS	5:1 - 50:1	–	–	145,4	138,2	90	4,8	9	90
	DTR90-DS	60:1 - 500:1	–	–	168,0	138,2	90	5,5	9	85

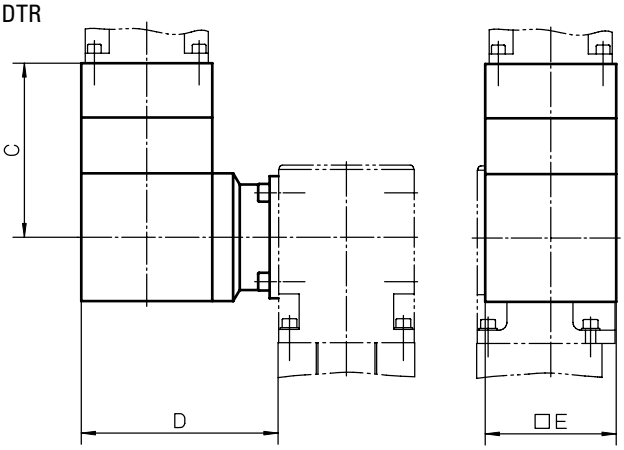
i = gear ratio

Micron DT and DTR planetary gears comes mounted on the unit from factory.

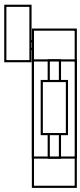
DT



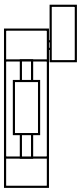
DTR



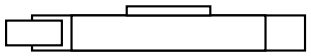
Left side



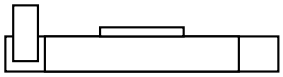
Right side



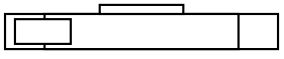
Position 1



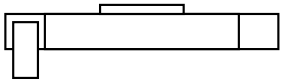
Position 2



Position 3



Position 4



Accessories

Motors, Gears and Transmission Kits

Micron DT, DTR Planetary Gears, how to order

When ordering a DT or DTR planetary gear you need to state the size and type of gear, which side of the unit the gear shall be installed, the gear ratio and which motor that you wish to use. For DTR you also must state the prefered mounting position of the gear. With this information we can check if your choice of motor is possible or not and give you the correct ordering code for the gear.

Micron DT, ordering data

1. Size of planetary gear
DT60
DT90
DT115

2. Type of gear
-SS
-DS

3. Mounting side of the unit
Left
Right

4. Gear ratio
3:1 (only for -SS models)
5:1 (only for -SS models)
10:1 (only for -SS models)
15:1 (only for -DS models)
25:1 (only for -DS models)
30:1 (only for -DS models)
50:1 (only for -DS models)
100:1 (only for -DS models)

5. Motor
Specify your choice of motor.

Micron DTR, ordering data

1. Type and size of planetary gear
DTR60
DTR90
DTR115

2. Type of gear
-SS
-DS

3. Mounting position of the gear
Position 1
Position 2
Position 3
Position 4

4. Mounting side of the unitl
Left
Right

5. Gear ratio
5:1 (only for -SS models)
6:1 (only for -SS models)
9:1 (only for -SS models)
10:1 (only for -SS models)
12:1 (only for -SS models)
15:1 (only for -SS models)
20:1 (only for -SS models)
25:1 (only for -SS models)
30:1 (only for -SS models)
40:1 (only for -SS models)
50:1 (only for -SS models)
60:1 (only for -DS models)
75:1 (only for -DS models)
90:1 (only for -DS models)
100:1 (only for -DS models)
120:1 (only for -DS models)
125:1 (only for -DS models)
150:1 (only for -DS models)
200:1 (only for -DS models)
250:1 (only for -DS models)
300:1 (only for -DS models)
400:1 (only for -DS models)
500:1 (only for -DS models)

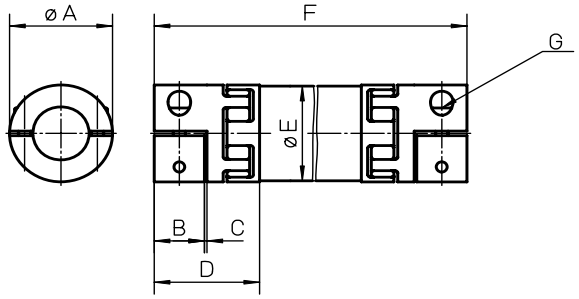
6. Motor
Specify your choice of motor.

Accessories

Motors, Gears and Transmission Kits

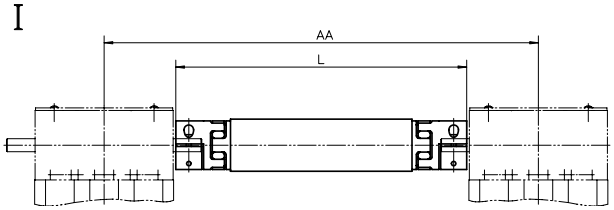
VWZ Intermediate Shafts, dimensions

Shaft	øA	B	C	D	øE	F min.	G
VWZ-30	32	15	1,5	34	30	99	M4
VWZ-40	42	17	1,5	46	40	133	M5
VWZ-60	56	30	2	63	60	177	M6
VWZ-60V	67	35	2	73	60	205	M8
VWZ-80	82	40	2	84	80	249	M10
VWZ-100	102	50	2	97	100	283	M12

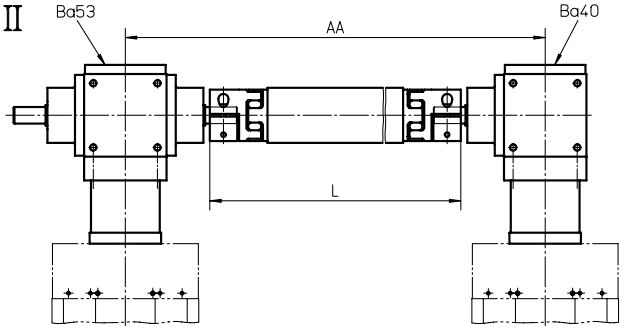


The VWZ intermediate shafts can be installed in two ways. Either directly to belt driven units (I) or to screw driven units using KRG bevel gears (II) of type VL0, VL1 or VL2. The intermediate shaft includes tube and couplings.

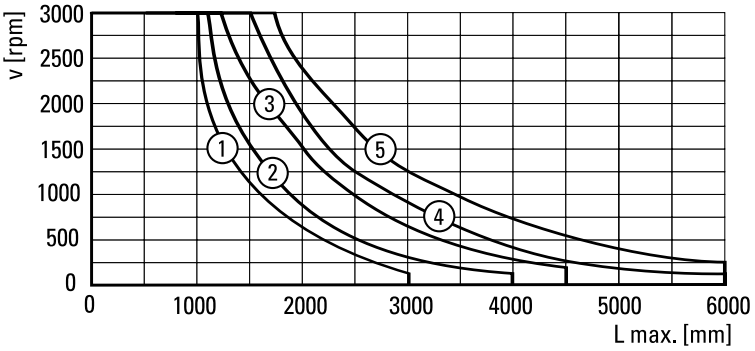
I



II



Critical Speed of Shaft



1: VWZ-30
2: VWZ-40
3: VWZ-60 and VWZ-60V
4: VWZ-80
5: VWZ-100

VWZ Intermediate Shafts, data

Shaft	Mmax [Nm]	Gs [kg/m]	Gc [kg]	Js [kgm²/m]	Jc [kgm²]	Ms [Nm]
VWZ-30	4,8	0,58	0,14	0,00011	0,00001	4
VWZ-40	6,4	0,76	0,36	0,00020	0,00008	8
VWZ-60	22,7	0,97	0,94	0,00080	0,00024	15
VWZ-60V	60,6	0,97	1,42	0,00080	0,00046	35
VWZ-80	122,7	2,00	2,98	0,00300	0,00240	70
VWZ-100	169,7	2,47	4,62	0,00580	0,00600	120

Mmax = max. shaft torque
Gc = weight of coupling
Jc = inertia of coupling
Gs = weight of shaft
Js = inertia of shaft
Ms = tightening torque

Accessories

Motors, Gears and Transmission Kits

VWZ Intermediate Shafts, compatability table

Unit	I	I I	VWZ-30	VWZ-40	VWZ-60	VWZ-60V	VWZ-80	VWZ-100	AA [mm]
WH40	•			•					AA = L + 56
WH50 / WHZ50	•				•				AA = L + 54
WM60Z	•				•				AA = L + 64
WH80 / WHZ80	•					•			AA = L + 84
WH120	•							•	AA = L + 124
WM80Z	•					•			AA = L + 84
MLSH60Z	•					•			AA = L + 164
WB40 / WM40		VL0	•						AA = L + 170
WB60		VL1			•				AA = L + 184
WM60 / WV60 / WZ60		VL1			•				AA = L + 184
WM80 / WV80 / MLSM60D		VL1				•			AA = L + 176
MLSH80Z / MLSM80Z	•						•		AA = L + 244
WM120 / WV120 / MLSM60D / MLSM80D		VL2					•		AA = L + 244

AA = C/C distance between units
L = total length of shaft and coupling assembly

VWZ Intermediate Shafts, ordering key

	1	2	3
Example	VWZ-060	-02	-0700

1. Intermediate shaft size
VWZ-030 = VWZ-30
VWZ-040 = VWZ-40
VWZ-060 = VWZ-60
VWZ-06V = VWZ-60V
VWZ-080 = VWZ-80
VWZ-100 = VWZ-100

2. Type of unit and type of mounting
-01 = WH40 for type I mounting
-02 = WH50 / WHZ50 for type I mounting
-03 = WM80Z for type I mounting
-04 = WH80 / WHZ80 for type I mounting
-05 = WH120 for type I mounting
-06 = WM60Z for type I mounting
-07 = MLSH60Z for type I mounting
-08 = WB40 / WM40 for type II mounting on VLO gears
-09 = WB60 for type II mounting on VL1 gears
-10 = WM60 / WV60 / WZ60 for type II mounting on VL1 gears
-11 = WM80 / WV80 / MLSM60D for type II mounting on VL1 gears
-12 = MLSH80Z / MLSM80Z for type I mounting
-13 = WM120 / WV120 / MLSM60D / MLSM80D for type II mounting on VL2 gears

3. C/C distance between units (AA)

Accessories

Motors, Gears and Transmission Kits

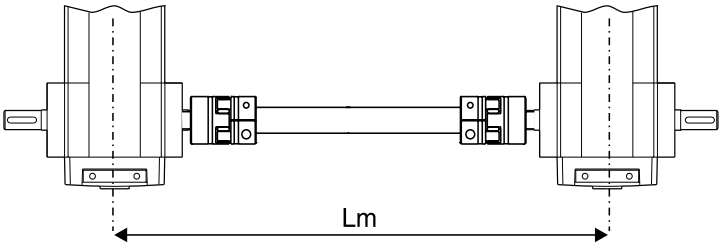
DSP Intermediate Shafts, data

Shaft	Weight of shaft [kg]	Max. speed [rpm]	Shaft diameter [mm]
DSP-05B	0,3 + 1,3 × Lm	1500	20
DSP-06B	0,3 + 1,3 × Lm	1500	20
DSP-07B	0,6 + 2,6 × Lm	1500	30
DSP-10B	0,6 + 2,6 × Lm	1500	30
DSB--ZB	0,6 + 2,6 × Lm	1500	30
DSP-TBS	0,6 + 2,6 × Lm	1500	30

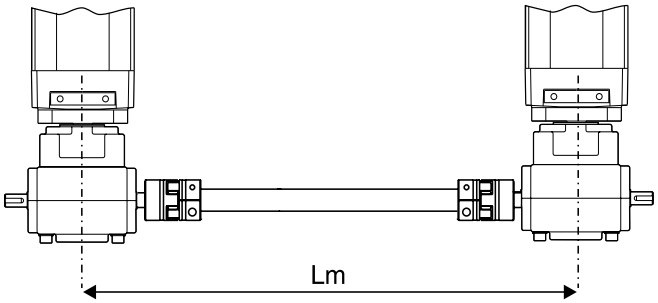
Lm = C/C distance between units in cm

The DSP intermediate shaft can be installed directly between two belt driven units or between two screw driven units using a TBS worm gear. Couplings and tube is included in the shipment. Support bearings may need to be installed if the critical speed of the shaft is exceeded. See diagram. Support bearings can be ordered from your local bearing supplier.

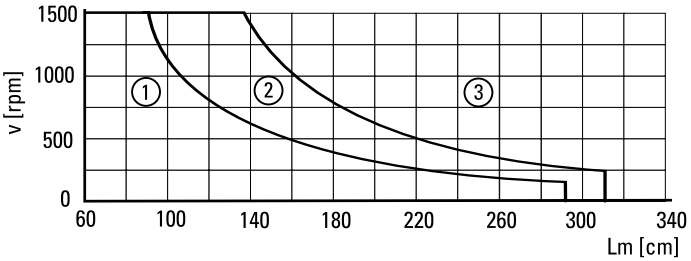
DSP-05B/06B/07B/10B/-ZB



DSP-TBS



Critical Speed of Shaft



1: No support bearing required
2: Support bearing required for DSP-05B and DSP-06B
3: Support bearing always required

Accessories

Motors, Gears and Transmission Kits

DSP Intermediate Shafts, compatability table

Unit	Drive type	DSP-05B	DSP-06B	DSP-07B	DSP-10B	DSP--ZB	DSP-TBS
M50	belt	•					
M55	belt		•				
M75	belt			•			
M100	belt				•		
ZB	belt					•	
M55	screw						•
M75	screw						•
M100	screw						•

DSP Intermediate Shafts, ordering key

	1	2
Example	DSP-06B	-305

1. Intermediate shaft size and type
DSP-05B = for belt driven M50 units
DSP-06B = for belt driven M55 units
DSP-07B = for belt driven M75 units
DSP-10B = for belt driven M100 units
DSP--ZB = for belt driven ZB units
DSP-TBS = for screw driven M55, M75 or M100 units with TBS worm gear

2. C/C distance between units in cm (Lm)
-• • • = length in cm

Accessories

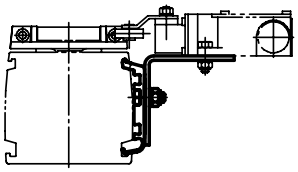
Electrical Feedback Devices

Limit Switch Brackets[1]

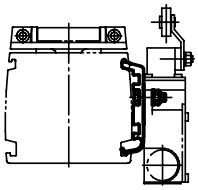
Unit type	I	For limit switch type	II	For limit switch type
M50	D393 035	ZCM-D21	–	–
M55	D313 427	ZCM-D21	D313 428	ZCM-D21
M75	D312 860	XCK-M115	D312 861	XCK-M115
M100	D312 330	XCK-M115	D312 331	XCK-M115

[1] no limit switches included in the shipment.

I

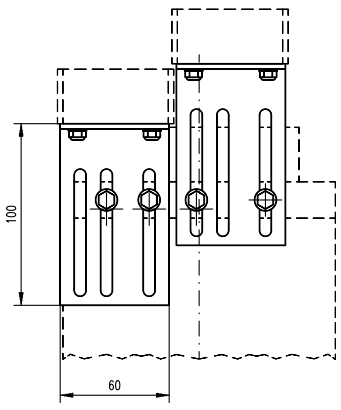


II



Limit Switch Brackets for Z3

Unit type	p/n	For limit switch type
Z3	D800 042	XCK-M115



The limit switch brackets are adjustable in height. The limit switches on the brackets are operated by the maximum extended and maximum retracted end of stroke bars on top of the Z3 units. Two brackets are required.

Limit Switches

Switch type	p/n	Protection degree	Contacts	Cable
XCK-M115	D535 107	IP67	NO + NC	–
ZCM-D21	D535 102	IP67	NO + NC	1 meter

Accessories

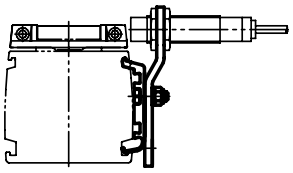
Electrical Feedback Devices

Sensor Brackets for Cylindrical Sensors[1]

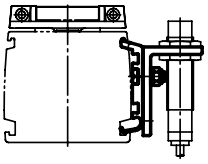
Unit type	I	For sensor diameter	I I	For sensor diameter
M55	D313 429	M12	D313 430	M12
M75	D312 862	M18	D312 863	M18
M100	D312 332	M18	D312 333	M18

[1] no sensors included in the shipment

I



II



Cylindrical Inductive Sensors

Sensor type	p/n	Diameter	Input voltage	Max. current	Protection degree	Contacts	Cable
PNP	D535 085	M12	12 - 48 Vdc	0,2 A	IP67	NO	connector
PNP	D535 089	M18	12 - 48 Vdc	0,2 A	IP67	NO	connector

Cylindrical Inductive Sensor Connectors

For sensor diameter	p/n
M12	D535 092
M18	D535 091

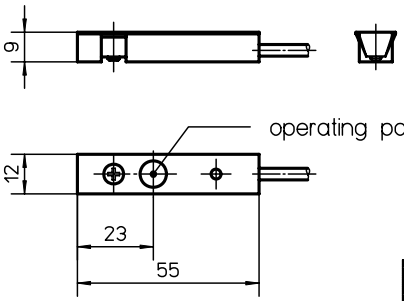
Accessories

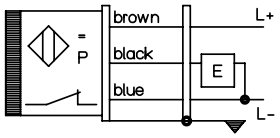
Electrical Feedback Devices

EN2 Inductive Sensors, part numbers

Sensor type	Cable length [m]	p/n
Normally closed	2	671 545 0305
Normally open	2	671 545 0304
Normally closed	10	671 545 0307
Normally open	10	671 545 0306

To be able to mount the EN2 inductive sensors on a unit the ENT14x16 sensor rail is required (see page 178) except for units WM120 and WV120 where they can be fitted directly to the profile of the unit.



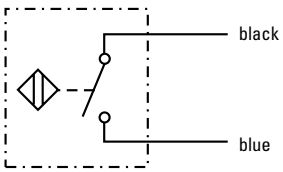


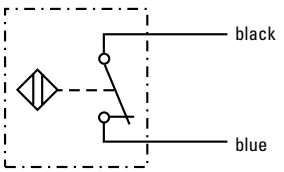
EN2 Inductive Sensors, data

Parameter		EN2
Supply voltage	[Vdc]	10 – 30
Max. load current	[A]	0,2
Operating distance	[mm]	2
LED indicator for switch		yes
Protection class		IP67
Cable type		screened
Weight with cable L = 2 m with cable L= 10 m	[kg]	 0,04 0,19

Magnetic Sensors, data

Parameter		
Max. power	[W]	10
Max. voltage	[Vdc]	100
Max. current	[A]	0,5
LED indicator for switch		no
Protection class		IP67
Cable length	[m]	3
Cable cross section	[mm²]	2 × 0,15
Operating temperature limits	[°C]	-25 – 65
Weight	[kg]	0,050

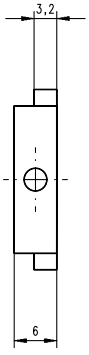


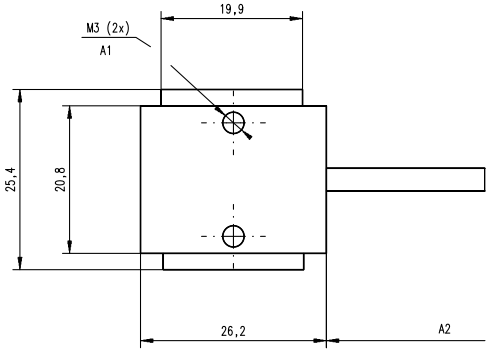


Magnetic Sensors, part numbers

Sensor type	suitable units	p/n
Normally closed	M50, Z2, Z3	D535 071
Normally open	M50, Z2, Z3	D535 070

On M50 the magnetic sensors are mounted directly in the sensor slot of the profiles of the units and require no mounting bracket while Z2 and Z3 require magnetic sensor mounting brackets. The sensor is fixed in position by two M3 size locking screws (A1). The cable (A2) is molded into the sensor.





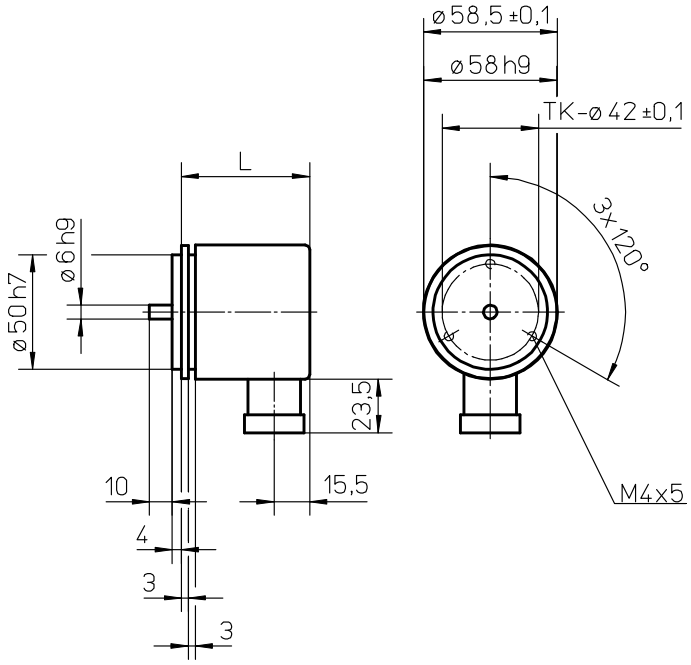
Accessories

Electrical Feedback Devices

IG602 Encoders, data

Parameter		IG602
Supply voltage Type 1 Type 2	[Vdc]	 5 ±10% 10 – 30
Output type Type 1 Type 2		 line driver push-pull
Pulses per revolution Type 1 Type 2	[ppr]	 100 – 2500 100 – 600
Length (L) Type 1 Type 2	[mm]	 51,5 56,0
Weight Type 1 Type 2	[kg]	 0,36 0,36

The IG602 encoders comes with mounting screws but no coupling or connector. To be able to mount the encoder to the unit the unit must have a shaft for encoders. See the ordering keys of the units. The encoders can also be ordered mounted to the unit from factory. See ADG encoder option kit on page 180.



IG602 Encoders, part numbers

Encoder type	Supply voltage [Vdc]	Pulses per revolution	p/n
Type 1	5	100	671 521 0194
Type 1	5	200	671 521 0195
Type 1	5	500	671 521 0196
Type 1	5	600	671 521 0197
Type 1	5	1000	671 521 0198
Type 1	5	1250	671 521 0199
Type 1	5	1500	671 521 0200
Type 1	5	2000	671 521 0192
Type 1	5	2500	671 521 0201
Type 2	10 – 30	100	671 521 0193
Type 2	10 – 30	200	671 521 0202
Type 2	10 – 30	500	671 521 0203
Type 2	10 – 30	600	671 521 0204

STE001 Encoder Connector, data

Parameter		STE001
Number of poles		12
Protection class		IP67
Execution		jack
Cable entrance		straight
Weight	[kg]	0,04
Part number		6715600153

Encoder Cable, data

Parameter	p/n
5 m cable length	671 555 0068
10 m cable length	671 555 0069

The encoder cables come fitted with a STE001 encoder connector in one of the ends.

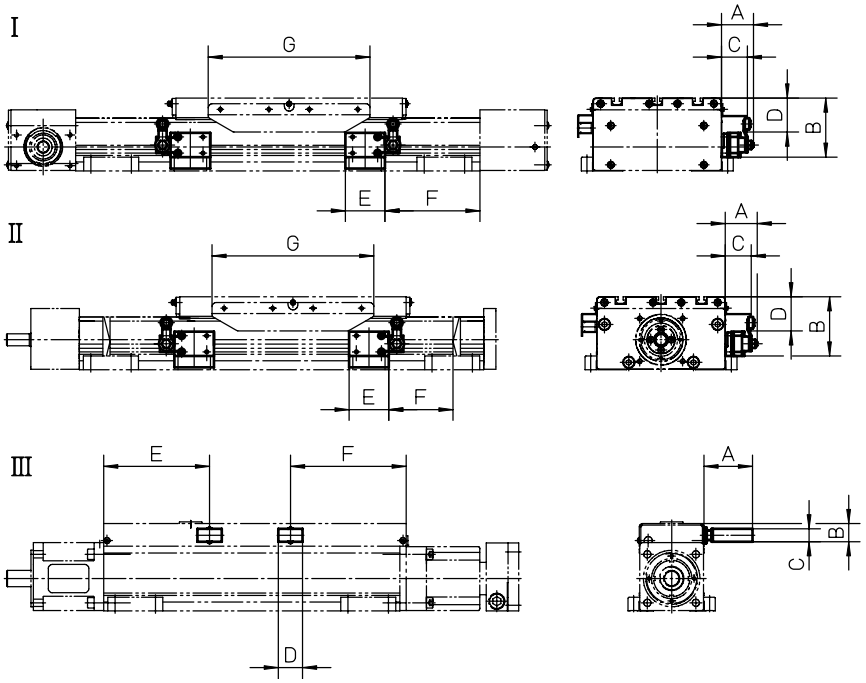
Accessories

Electrical Feedback Devices

ES Limit Switch Option Kit

Unit type	I	II	III	A	B	C	D	E	F	G
WH50 [1]	•			34	60,5	10	26	49	58,5	196
WH80	•			31	76	10	39	49	78,5	196
WH120	•			34	88	10	51	49	78,5	196
WHZ50	•			34	61	10	26	49	58,5	196
WHZ80	•			31	76	10	39	49	78,5	196
WM60		•		40	69	32	38	50	63	200
WM80		•		40	73	32	42	50	79	200
WM120		•		40	89	32	58	50	94	200
WM60Z	•			40	69	32	38	50	73	200
WM80Z [2]	•			40	73	32	42	50	99 (89)	200
WV60		•		40	69	32	38	50	33	200
WV80		•		40	73	32	42	50	39	200
WV120		•		40	89	32	58	50	59	200
MLSM60D		•		40	73	32	32	50	79	200
MLSH60Z	•			40	73	32	42	50	79	200
MLSM80D		•		40	85	32	54	50	101	200
MLSH80Z	•			40	85	32	54	50	101	200
MLSM80Z		•		40	85	32	54	50	101	200
WZ60 [1]			•	60	22,5	16	30	113	53	–
WZ80 [1]			•	60	22,5	16	30	112	84	–

[1] limit switches for these units can not be moved. On all other units the switches can be re-positioned by the customer. [2] Value in brackets = for short carriage.



The ES limit switch assembly is an option that is mounted at the factory. The limit switches are placed 10 mm from the mechanical ends of the unit. Each limit switch has one NO and one NC contact with positive opening action. Protection degree is IP67. Type I and II switches can be repositioned along the profile by the customer. Note! the ES limit switch option and any of the sensor rail options ENT14x16, ENF14x16 or ENK can not be mounted on the same side of the unit.

Accessories

Electrical Feedback Devices

ES Limit Switch Option Kit, ordering key

	1	2	3	4
Example	ESK07	-L	-01	-10

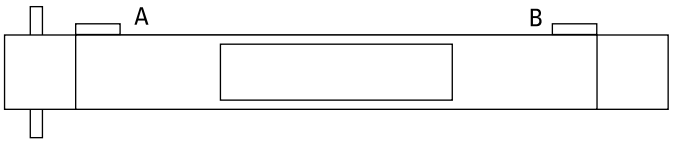
1. Compatable unit
ESK02 = WH50
ESK03 = WH80
ESK04 = WH120
ESK05 = WM40
ESK06 = WM60 / WM60Z
ESK07 = WM80 / WM80Z
ESK08 = WM120
ESK09 = WV60
ESK10 = WV80
ESK11 = WV120
ESK12 = WHZ50
ESK13 = WHZ80
ESK14 = WZ60
ESK15 = WZ80
ESK16 = MLSH60Z
ESK17 = MLSH80Z
ESK18 = MLSM80Z
ESK19 = MLSM60D
ESK20 = MLSM80D

2. Mounting side of the unit
-L = left side
-R = right side

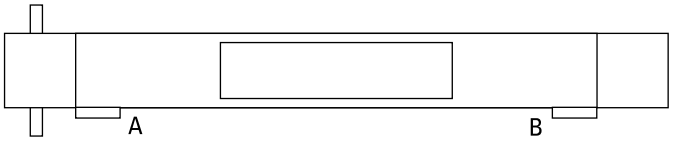
3. Switch configuration on side A
-00 = no switch on side A
-01 = switch with 1 m cable
-05 = switch with 5 m cable
-10 = switch with 10 m cable

4. Switch configuration on side B
-00 = no switch on side B
-01 = switch with 1 m cable
-05 = switch with 5 m cable
-10 = switch with 10 m cable

ES-••-R-••-••



ES-••-L-••-••

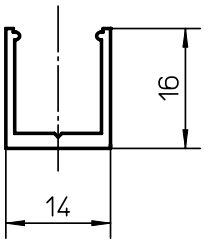


Accessories

Electrical Feedback Devices

ENT14x16 Inductive Sensor Rail

Unit type	p/n
WH40 / WH50 / WH80 / WH120 / WHZ50 / WHZ80 / WM40 / WM60 / WM80 / WM60Z / WM80Z / WV60 / WV80 / MLSM60D / MLSM80D / MLSH60Z / MLSH80Z / MLSM80Z / WZ60 / WZ80 / WB40 / WB60	671 545 0283

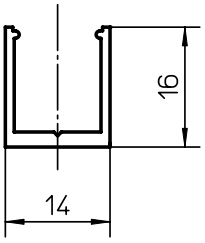


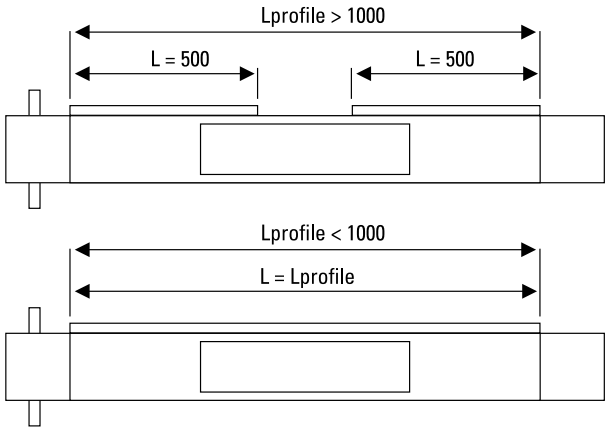
The ENT14x16 inductive sensor rail is mounted to the side of an unit or along any type of beam or profile. In the rail inductive sensors of type EN2 can be mounted. The rail can also serve as a cable duct for the sensor cables. The rail is sealed with a cover which comes with the rail. The rail comes in lengths of max. 3000 mm. Drilling in the profile of the unit is required when mounting the rail. When ordering, specify part number and length of the rail. Note1! WM120 and WV120 units do not require any rail as the EN2 sensors can be fitted directly to the profile of the units. Note2! ES limit switch option and ENT14x16 rail can not be mounted on the same side of the unit.

ENF and ENK Inductive Sensor Rail Option Kit, compatability table

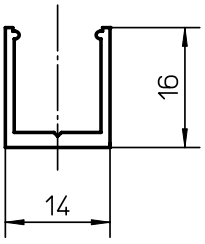
Unit type	ENF / ENK
WH40 / WH50 / WH80 / WH120 / WHZ50 / WHZ80 / WM40 / WM60 / WM80 / WM60Z / WM80Z / WV60 / WV80 / MLSM60D / MLSM80D / MLSH60Z / MLSH80Z / MLSM80Z / WZ60 / WZ80 / WB40 / WB60	•

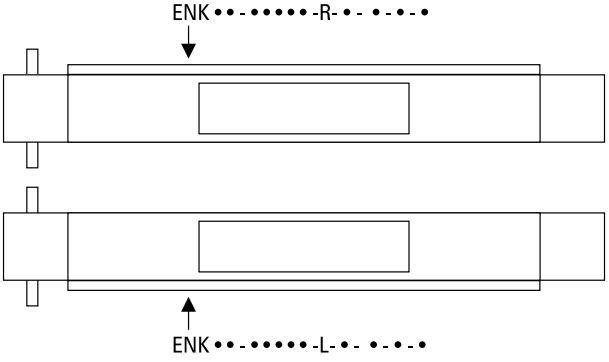
ENF





ENK





The ENF and ENK inductive sensor rail option kits are mounted at the factory. The ENF option consists of two 500 mm long ENT14x16 sensor rails mounted on in each end of the unit on the left or right side of the profile. In cases where the unit is to short to allow two 500 mm sensor rails to be mounted, then one rail is mounted along the entire profile of the unit. The ENK option also consists of ENT14 x16 sensor rails but the ENK option has sensor profiles that runs along the entire profile of the unit. In the shipment of both ENF and ENK the specified amount and type of EN2 sensors are included. The sensors are fitted to the sensor rail by the customer at the desired positions. Note1! WM120 and WV120 units do not require any ENF or ENF option as the EN2 sensors can be fitted directly to the profile of the units. Note2! ES limit switch option and ENF rail can not be mounted on the same side of the unit.

Accessories

Electrical Feedback Devices

ENK and ENF Inductive Sensor Rail Option Kit, ordering key

	1	2	3	4	5	6	7	8
Example	ENK16	-S	-04000	-R	-2	-0	-1	-6

1. Type of rail and compatable unit

ENK01 = ENK rail for WH40	ENF01 = ENF rail for WH40
ENK02 = ENK rail for WH50	ENF02 = ENF rail for WH50
ENK03 = ENK rail for WH80	ENF03 = ENF rail for WH80
ENK04 = ENK rail for WH120	ENF04 = ENF rail for WH120
ENK05 = ENK rail for WM40	ENF05 = ENF rail for WM40
ENK06 = ENK rail for WM60 / WV60	ENF06 = ENF rail for WM60 / WV60
ENK07 = ENK rail for WM80 / WV80	ENF07 = ENF rail for WM80 / WV80
ENK08 = ENK rail for WM120 / WV120	ENF08 = ENF rail for WM120 / WV120
ENK09 = ENK rail for WM60Z	ENF09 = ENF rail for WM60Z
ENK10 = ENK rail for WM80Z	ENF10 = ENF rail for WM80Z
ENK11 = ENK rail for WHZ50	ENF11 = ENF rail for WHZ50
ENK12 = ENK rail for WHZ80	ENF12= ENF rail for WHZ80
ENK13 = ENK rail for WZ60	ENF13 = ENF rail for WZ60
ENK14 = ENK rail for WZ80	ENF14 = ENF rail for WZ80
ENK15 = ENK rail for MLSH60Z	ENF15 = ENF rail for MLSH60Z
ENK16 = ENK rail for MLSH80Z	ENF16 = ENF rail for MLSH80Z
ENK17 = ENK rail for MLSM80Z	ENF17 = ENF rail for MLSM80Z
ENK18 = ENK rail for MLSM60D	ENF18 = ENF rail for MLSM60D
ENK19 = ENK rail for MLSM80D	ENF19 = ENF rail for MLSM80D
ENK20 = ENK rail for WB40	ENF20 = ENF rail for WB40
ENK21 = ENK rail for WB60	ENF21 = ENF rail for WB60

2. Number of carriages

-S = singel carriage

-D = double carriages

3. Total length of unit (L tot)

- ••••• = distance in mm

4. Mounting side of the unit

-L = left side

-R = right side

5. Number of EN2 sensors with NC contact and 2 m cable

- • = 0 – 9 sensors / normally closed / 2 m cable

6. Number of EN2 sensors with NO contact and 2 m cable

- • = 0 – 9 sensors / normally open / 2 m cable

7. **Number of EN2 sensors with NC contact and 10 m cable**

- • = 0 – 9 sensors / normally closed / 10 m cable

8. **Number of EN2 sensors with NO contact and 10 m cable**

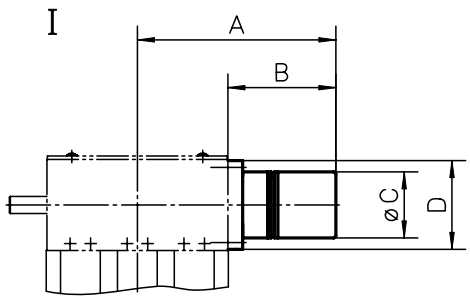
- • = 0 – 9 sensors / normally open / 10 m cable

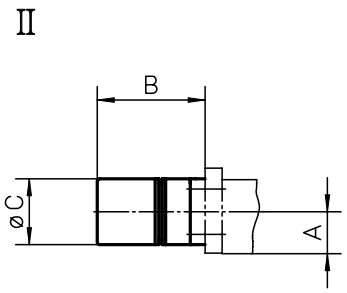
Accessories

Electrical Feedback Devices

ADG Encoder Option Kit

Unit type	Mounting type I	Mounting type II	A	B	øC	D
WH40	•		115	95	58,5	ø60
WH50 / WHZ50	•		120	96	58,5	50 × 50
WH80 / WHZ80	•		139	100	58,5	90 × 90
WH120	•		153	93	58,5	100 × 100
WM40		•	25	95	58,5	–
WM60		•	31	95	58,5	–
WM80		•	40	95	58,5	–
WM120		•	74	95	58,5	–
WM60Z	•		124	94	58,5	60 × 60
WM80Z	•		138	98	58,5	65 × 65
WB40		•	20,8	95	58,5	–
WB60		•	32,5	95	58,5	–
MLSM60D		•	37	95	58,5	–
MLSM80D		•	46	95	58,5	–
MLSH60Z	•		174,5	95	58,5	78 × 59
MLSH80Z	•		214,5	95	58,5	100 × 80
MLSM80Z	•		214,5	95	58,5	100 × 80





The ADG encoder option kit is an option that is mounted to the unit at the factory. It includes an IG602 encoder, a STE001 encoder connector and an encoder mounting flange with coupling. Cable can also be supplied in 5 or 10 meter length.

Accessories

Electrical Feedback Devices

ADG Encoder Option Kit, ordering key

	1	2	3
Example	ADG-08	-05-0600	-00

1. Compatable unit
ADG-01 = WH40
ADG-02 = WH50 / WHZ50
ADG-03 = WH80 / WHZ80
ADG-04 = WH120
ADG-05 = WM40
ADG-06 = WM60 / WV60
ADG-07 = WM80 / WV80
ADG-08 = WM120 / WV120
ADG-09 = WM60Z
ADG-10 = WM80Z
ADG-11 = MLSH60Z
ADG-12 = MLSH80Z
ADG-13 = MLSM80Z
ADG-14 = MLSM60D
ADG-15 = MLSM80D
ADG-16 = WB40
ADG-17 = WB60

2. Supply voltage and number of pulses
-05-0100 = 5 volts, 100 pulses per revolution
-05-0200 = 5 volts, 200 pulses per revolution
-05-0500 = 5 volts, 500 pulses per revolution
-05-0600 = 5 volts, 600 pulses per revolution
-05-1000 = 5 volts, 1000 pulses per revolution
-05-1250 = 5 volts, 1250 pulses per revolution
-05-2000 = 5 volts, 2000 pulses per revolution
-05-2500 = 5 volts, 2500 pulses per revolution
-24-0100 = 10 - 30 volts, 100 pulses per revolution
-24-0200 = 10 - 30 volts, 200 pulses per revolution
-24-0500 = 10 - 30 volts, 500 pulses per revolution
-24-0600 = 10 - 30 volts, 600 pulses per revolution

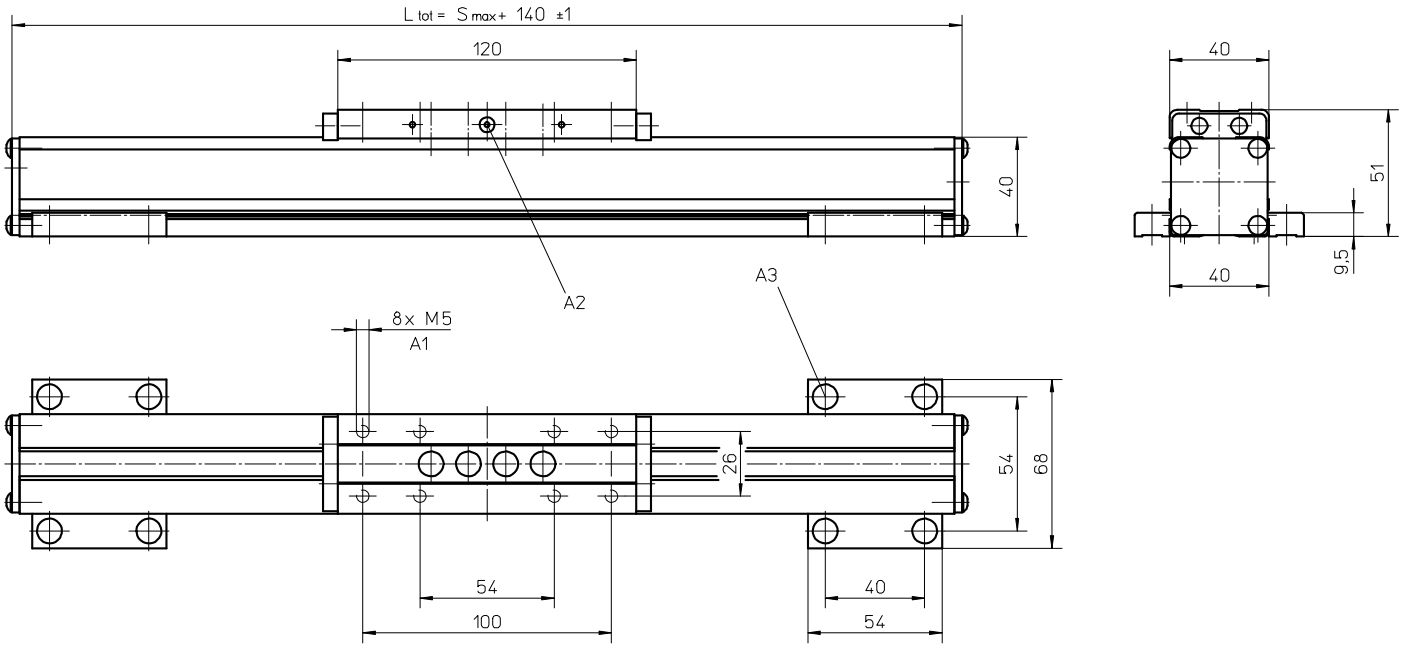
3. Cable and connector configuation
-00 = no cable only STE001 encoder connector
-05 = 5 m cable with STE001 encoder connector in one of the ends
-10 = 10 m cable with STE001 encoder connector in one of the ends

Accessories

Non Driven Linear Motion Systems

WH40N

» Ordering key - see page 198
» Technical data - see page 60

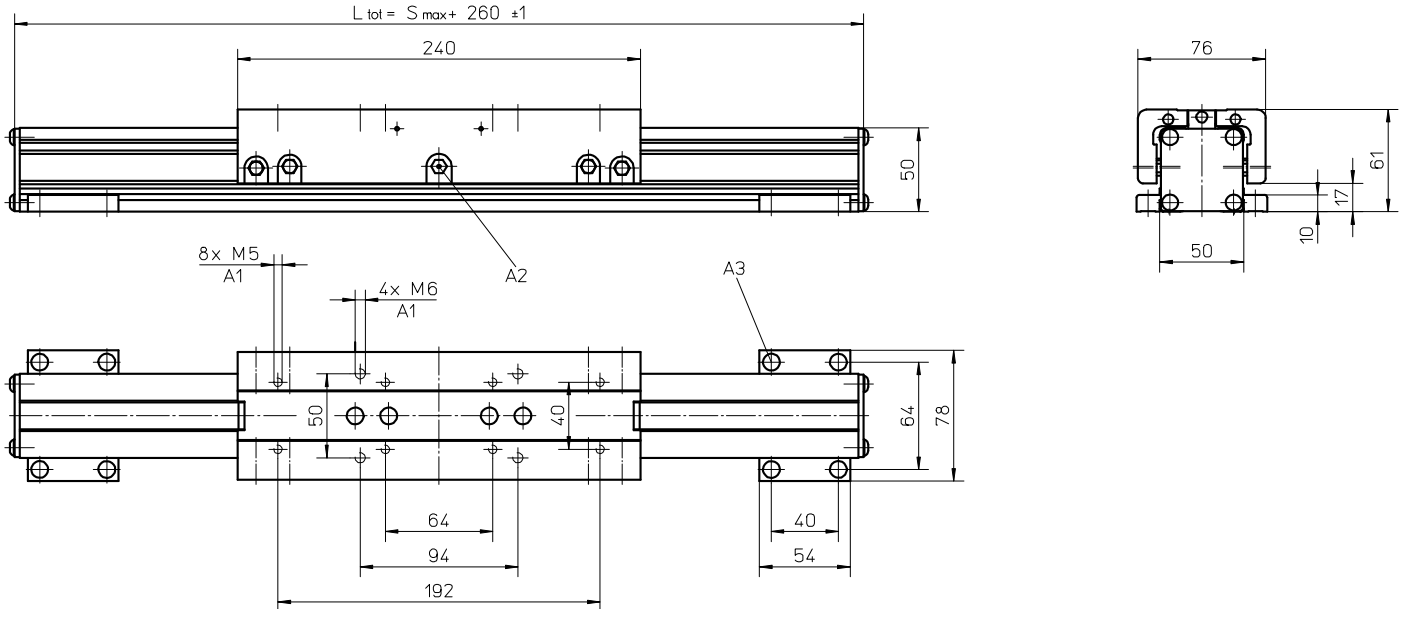


A1: depth 10
A2: lubricating nipple on both sides DIN3405 D 1/A

A3: socket cap screw ISO4762-M5×12 8.8

WH50N

» Ordering key - see page 198
» Technical data - see page 92



A1: depth 10
A2: funnel type lubricating nipple DIN3405-M6×1-D1

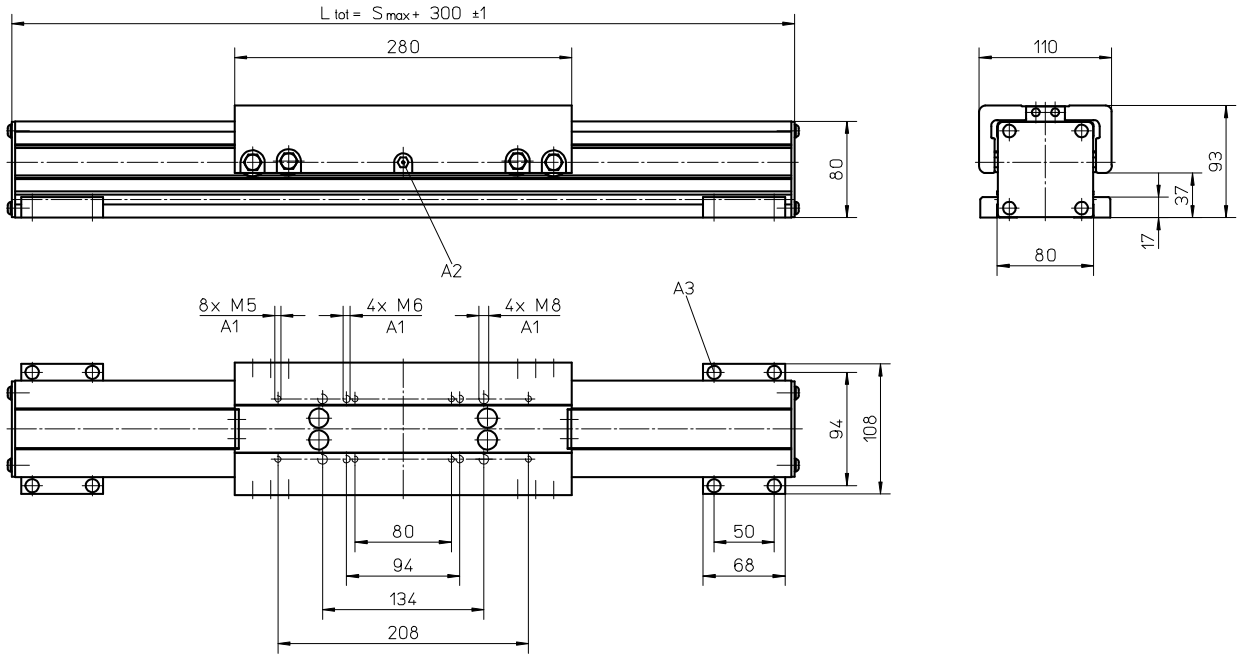
A3: socket cap screw ISO4762-M5×12 8.8

Accessories

Non Driven Linear Motion Systems

WH80N

» Ordering key - see page 198
» Technical data - see page 94

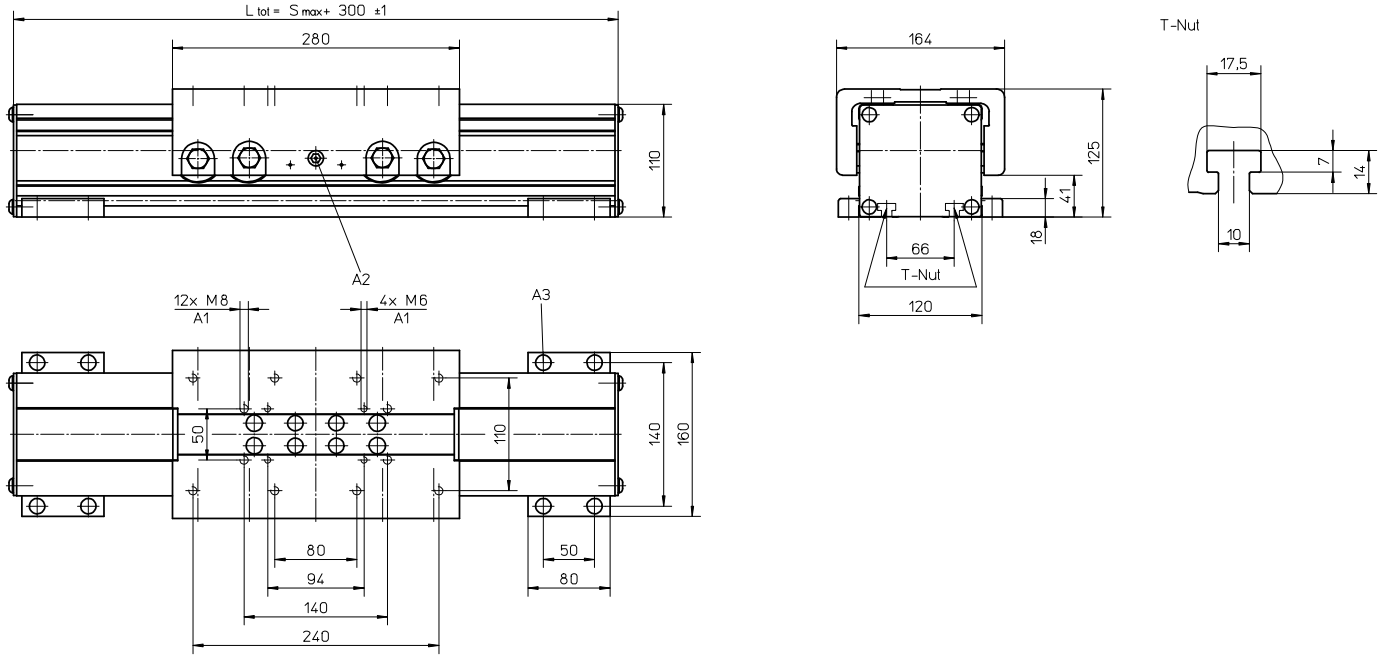


A1: depth 12
A2: funnel type lubricating nipple DIN3405-M6×1-D1

A3: socket cap screw ISO4762-M6×20 8.8

WH120N

» Ordering key - see page 198
» Technical data - see page 96



A1: depth 12
A2: funnel type lubricating nipple DIN3405-M6×1-D1

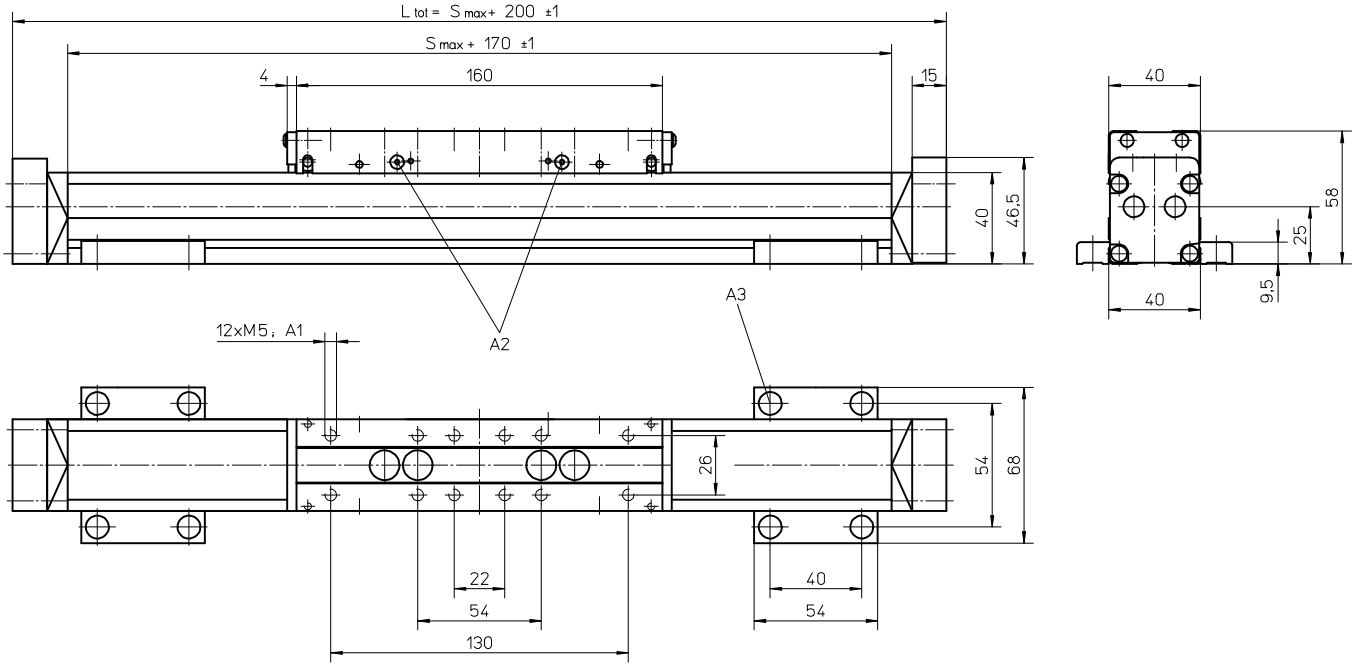
A3: socket cap screw ISO4762-M8×20 8.8

Accessories

Non Driven Linear Motion Systems

WM40N

» Ordering key - see page 198
» Technical data - see page 14

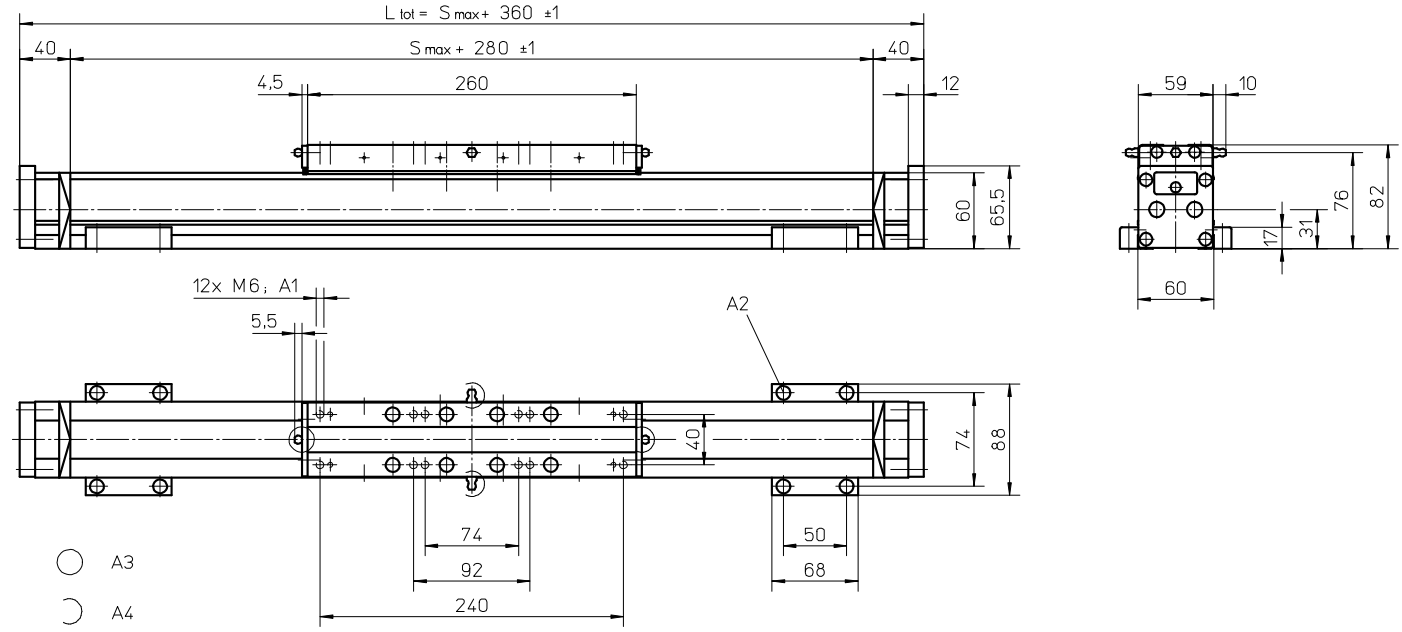


A1: depth 7
A2: lubricating nipple on both sides DIN3405 D 1/A

A3: socket cap screw ISO4762-M5×12 8.8

WM60N

» Ordering key - see page 198
» Technical data - see page 16



A1: depth 11
A2: socket cap screw ISO4762-M6×20 8.8

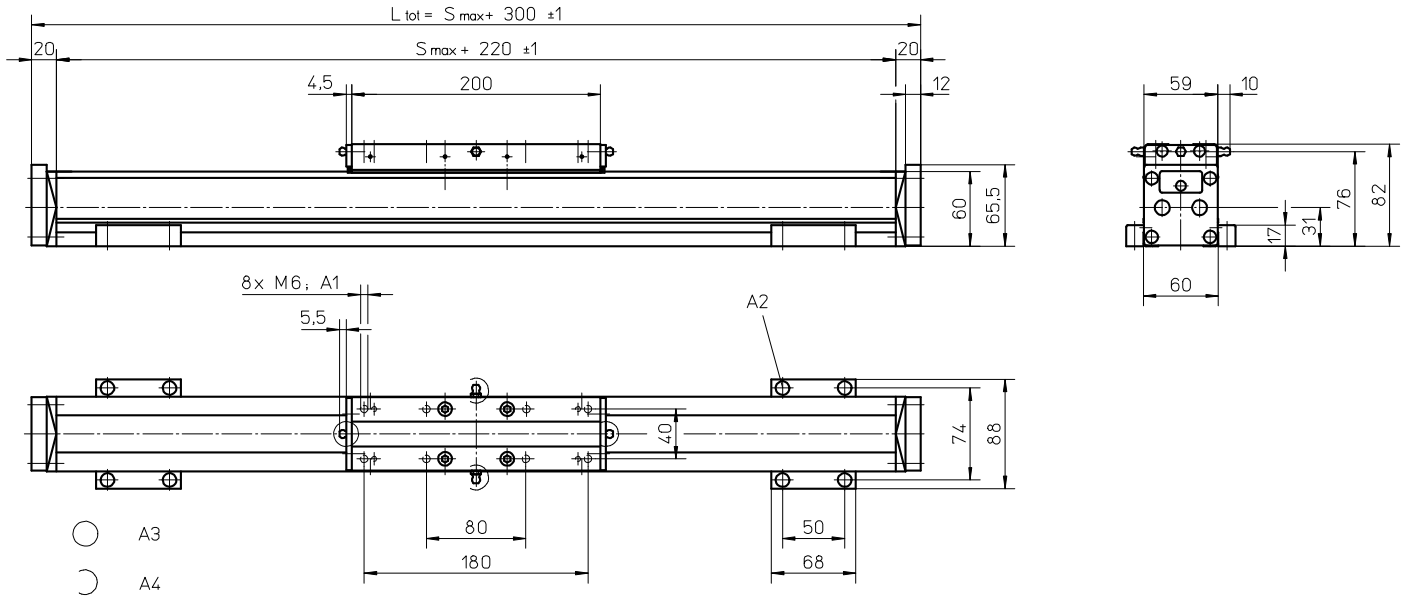
A3: tapered lubricating nipple to DIN71412 AM6
A4: can be changed over to one of the three alternative lubricating points by the customer

Accessories

Non Driven Linear Motion Systems

WM60N with Single Short Carriage

» Ordering key - see page 198
» Technical data - see page 18

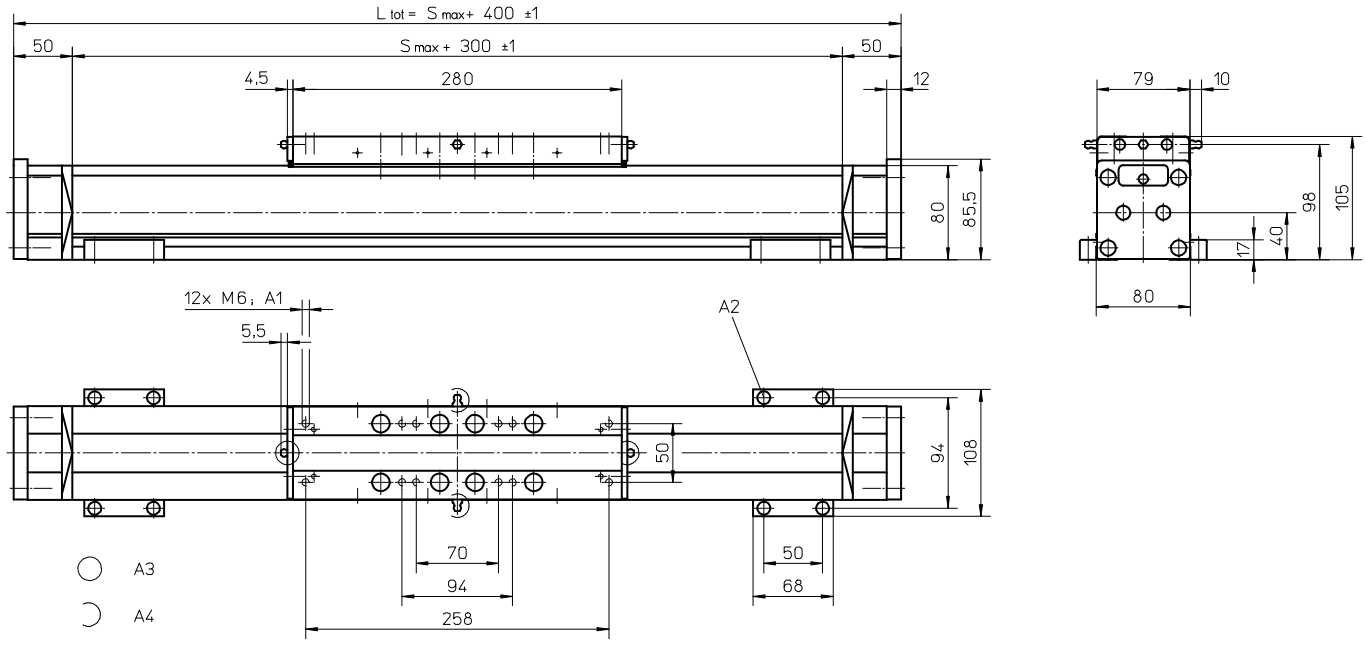


A1: depth 11
A2: socket cap screw ISO4762-M6×20 8.8

A3: tapered lubricating nipple to DIN71412 AM6
A4: can be changed over to one of the three alternative lubricating points by the customer

WM80N

» Ordering key - see page 198
» Technical data - see page 22



A1: depth 12
A2: socket cap screw ISO4762-M6×20 8.8

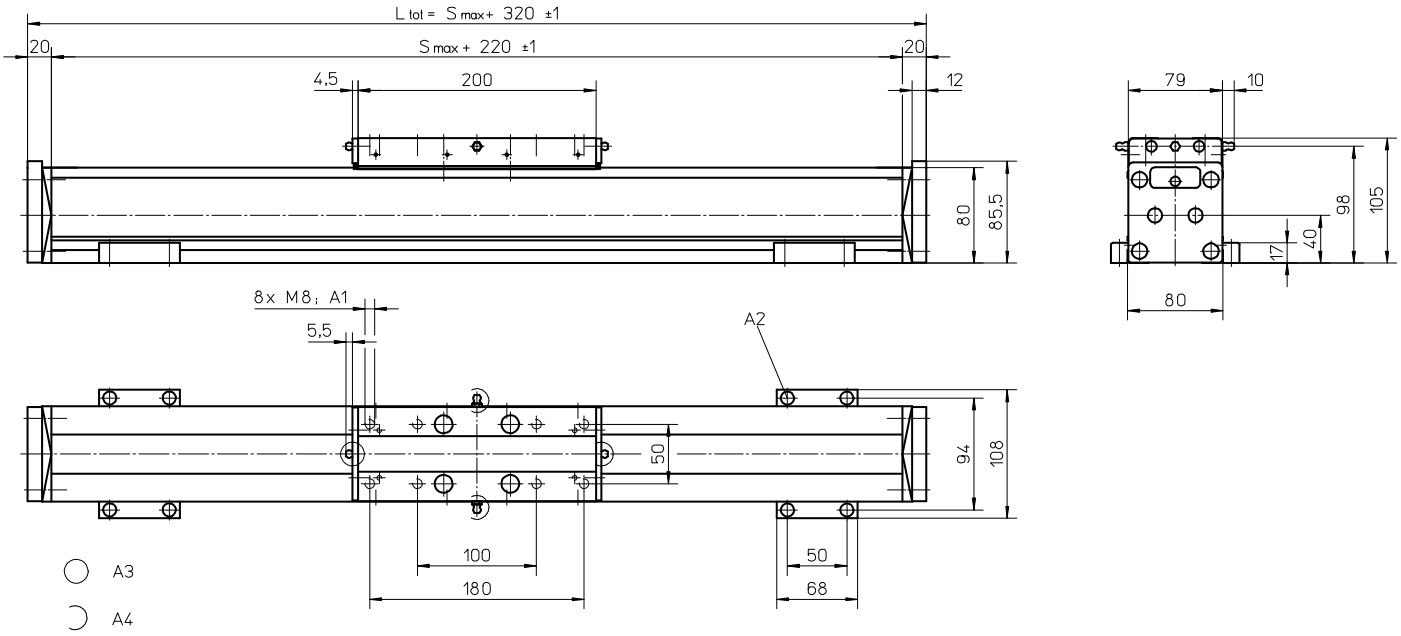
A3: tapered lubricating nipple to DIN71412 AM6
A4: can be changed over to one of the three alternative lubricating points by the customer

Accessories

Non Driven Linear Motion Systems

WM80N with Single Short Carriage

» Ordering key - see page 198
» Technical data - see page 24

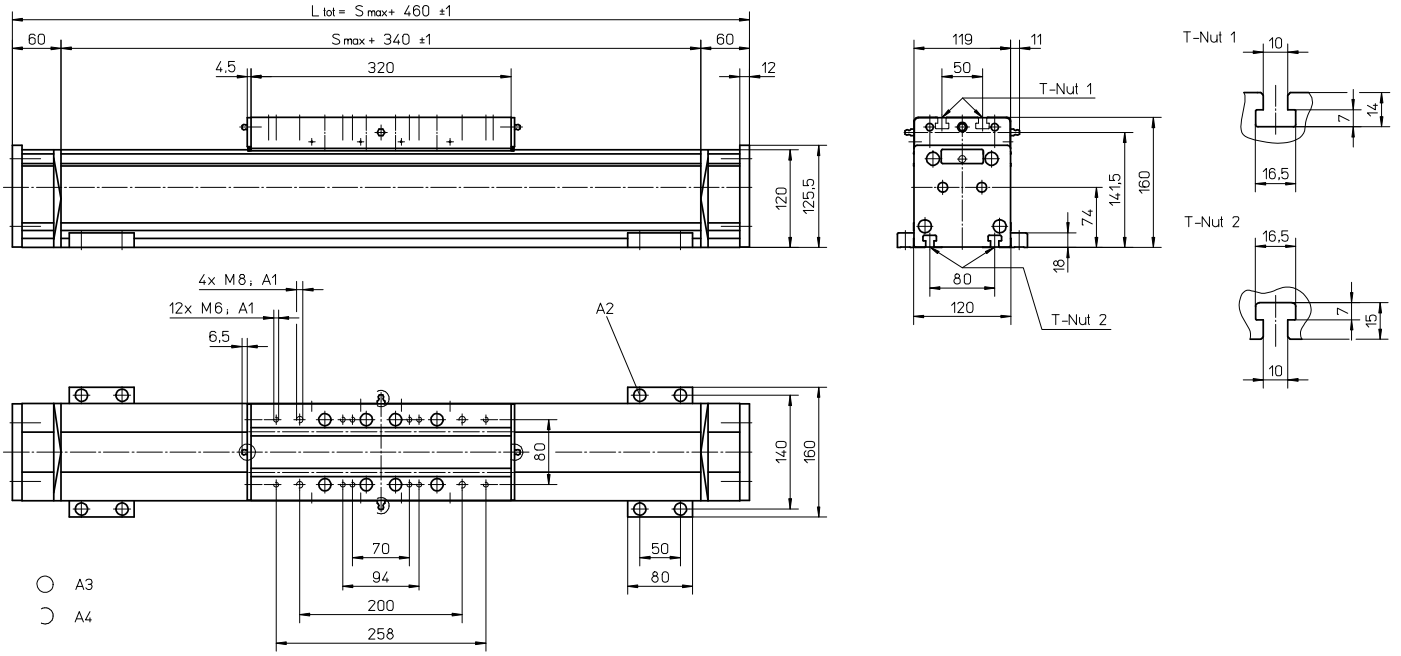


A1: depth 12
A2: socket cap screw ISO4762-M6×20 8.8

A3: tapered lubricating nipple to DIN71412 AM6
A4: can be changed over to one of the three alternative lubricating points by the customer

WM120N

» Ordering key - see page 198
» Technical data - see page 26



A1: depth 22
A2: socket cap screw ISO4762-M8×20 8.8

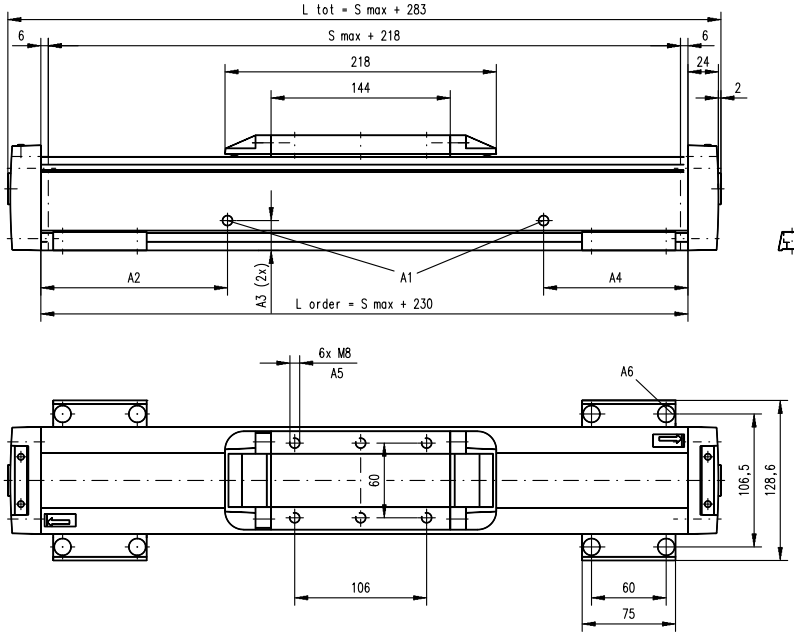
A3: tapered lubricating nipple to DIN71412 M8×1
A4: can be changed over to one of the three alternative lubricating points by the customer

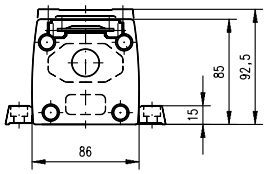
Accessories

Non Driven Linear Motion Systems

M75N

» Ordering key - see page 199
» Technical data - see page 48

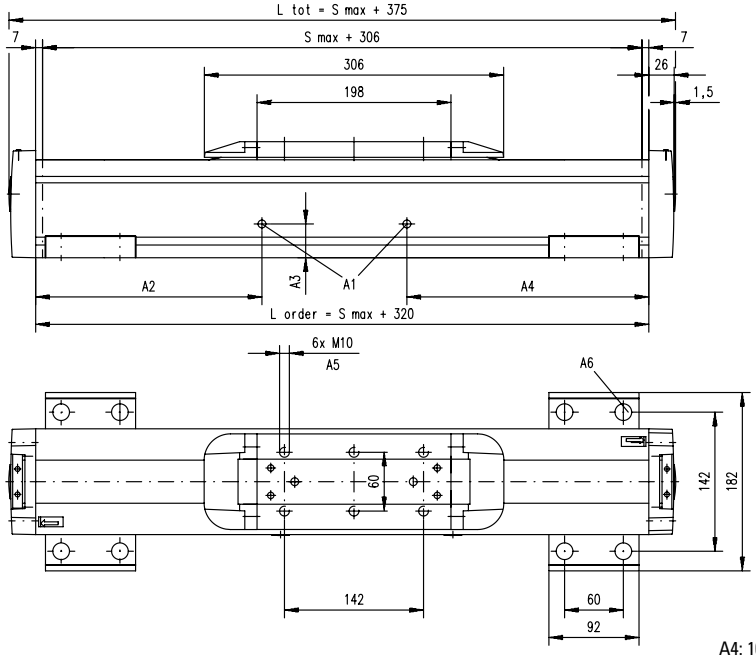


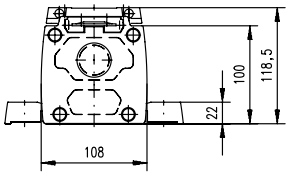


A1: lubrication holes ø6 (MG07N), ø10 (MF07N)
A2: 150 (MG07N), 100 (MF07N)
A3: 24 (MG07N), 43 (MF07N)
A4: 300 (MG07N), 320 (MF07N)
A5: depth 8 Heli coil
A6: ø13,5 / ø 8,5 for socket head cap screw M8

M100N

» Ordering key - see page 199
» Technical data - see page 50





A1: lubrication holes ø6 (MG10N), ø10 (MF10N)
A2: 100 if L order is equal or < 1 m, 200 if L order > 1 m (MG10N), 265 (MF10N)
A3: 34,5 (MG10N), 56,5 (MF10N)
A4: 100 if L order is equal or < 1 m, 350 if L order > 1 m (MG10N)
265 if L order is equal or > 0,7 m, no hole if L order < 0,7 m (MF10N)
A5: depth 10 Heli coil
A6: ø17 / ø 10,5 for socket head cap screw M10

Accessories

Packaged Linear Motion Systems

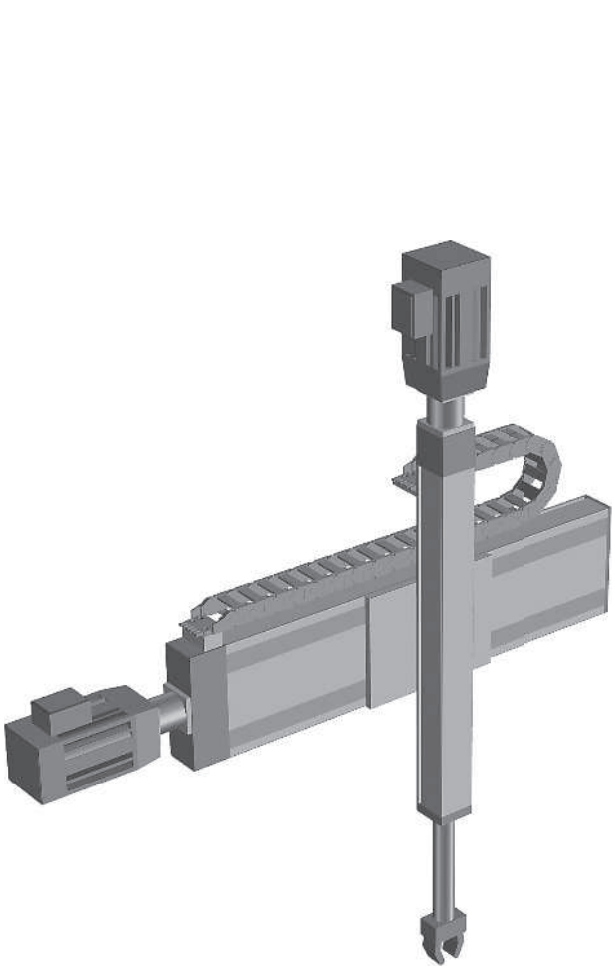
Thomson offers a range of “ready-to-run” linear actuators. One part number will include everything: a linear actuator, a gear, a flange, necessary couplings, a servo motor and a servo drive. All necessary cables, a set of limit switches and a mounting kit are also included. This will significantly reduce the time spent on engineering, component selection and comissioning for an application. A free user friendly sizing and selection software is available to assist you in the process of getting the ultimate package for your specific application.

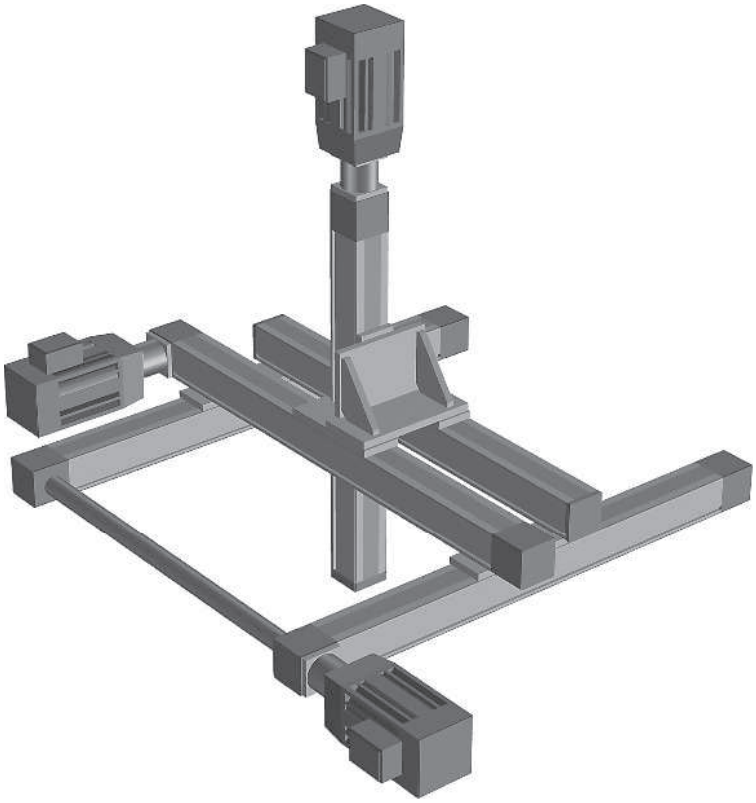
Accessories

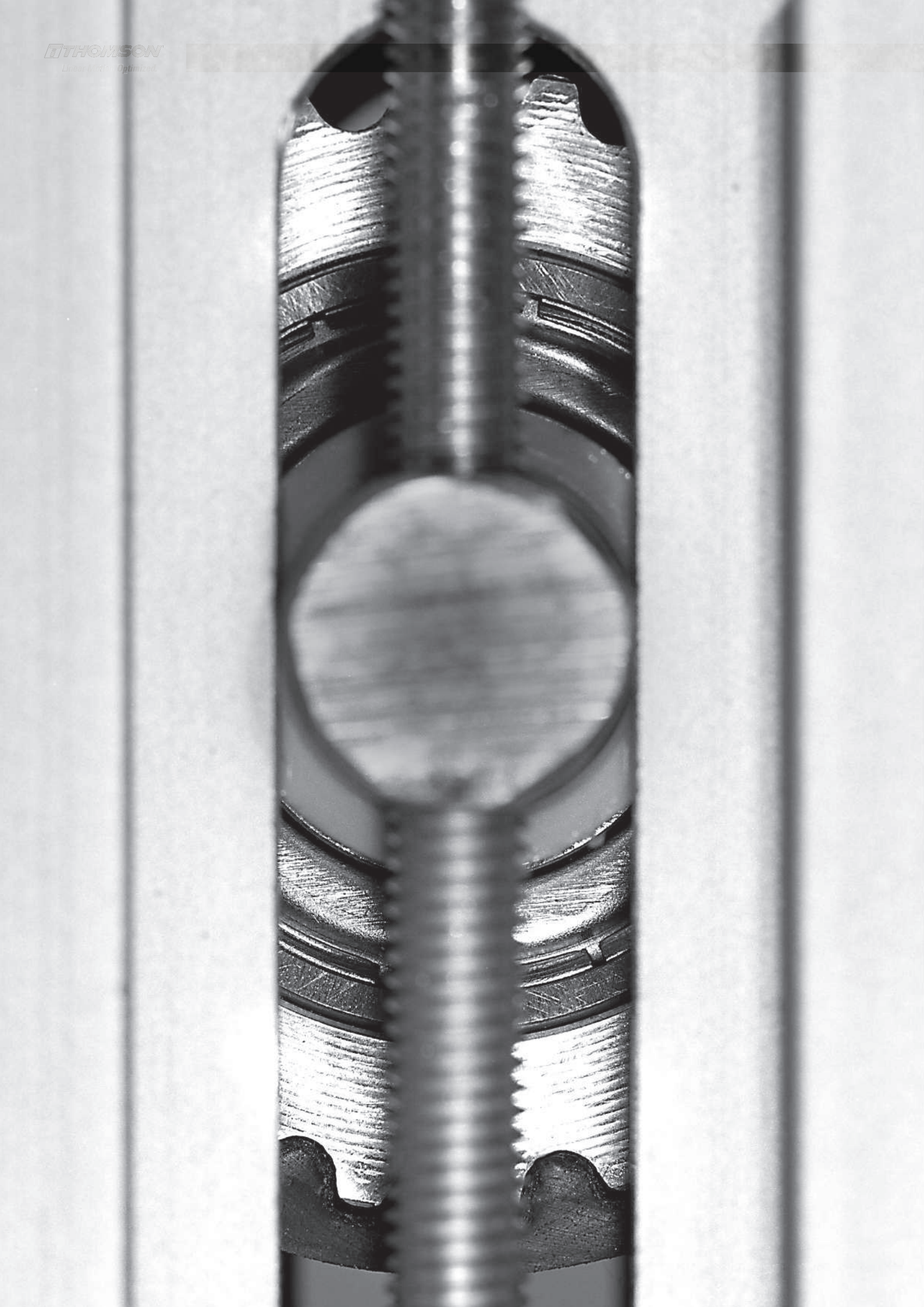
Multi Axis System Kits

Using the wide range of Thomson linear motion systems it is easy to create complex robots or manipulators regardless of the application. We can offer solutions for most applications, whether it is a high-speed short cycle application, a high precision pick and place equipment, hydraulics replacement or a heavy load and long movements application in a harsh environment.

Thomson offer a wide range of brackets and mounting components that enables you to design a complete linear unit motion system. And together with our motor and drive packages we can supply you a complete solution. For sizing and selection of a system please contact us for more detailed information.







Additional Technical Data

Linear Motion Systems with Ball Screw Drive and Ball Guides

Technical Data

Parameter		WM40S	WM40D	WM60D	WM60S	WM60X	WM80D	WM80S	WM120D
Geometrical moment of inertia of the profile (Iy)	[mm^4]	$10,8 \times 10^4$	$10,8 \times 10^4$	$5,8 \times 10^5$	$5,8 \times 10^5$	$5,8 \times 10^5$	$1,85 \times 10^6$	$1,85 \times 10^6$	$7,7 \times 10^6$
Geometrical moment of inertia of the profile (Iz)	[mm^4]	$13,4 \times 10^4$	$13,4 \times 10^4$	$5,9 \times 10^5$	$5,9 \times 10^5$	$5,9 \times 10^5$	$1,94 \times 10^6$	$1,94 \times 10^6$	$9,4 \times 10^6$
Friction factor of the guide system (μ)		0,05	0,05	0,1	0,1	0,1	0,1	0,1	0,1
Effiency of the unit		0,8	0,8	0,8	0,8	0,8	0,8	0,8	0,8
Bending factor (b)		0,0003	0,0003	0,0003	0,0003	0,0003	0,0003	0,0003	0,0003
Inertia of ball screw (jsp)	[kgm^2/m]	$1,13 \times 10^{-5}$	$1,13 \times 10^{-5}$	$8,46 \times 10^{-5}$	$8,46 \times 10^{-5}$	$8,46 \times 10^{-5}$	$2,25 \times 10^{-4}$	$2,25 \times 10^{-4}$	$6,34 \times 10^{-4}$
Dynamic load rating of ball screw (Cx) 05 mm lead 10 mm lead 20 mm lead 40 mm lead 50 mm lead	[N]	 4400 - - - -	 4400 - - - -	 10500 - 11600 - 8400	 10500 - 11600 - 8400	 10500 - - - -	 12300 13200 13000 - 15400	 12300 13200 13000 - 15400	 21500 33400 29700 14900 -
Dynamic load rating of ball guide (Cy)	[N]	2 × 2650	2 × 2650	4 × 11495	2 × 12964	4 × 11495	4 × 14356	2 × 18723	4 × 18723
Dynamic load rating of ball guide (Cz)	[N]	2 × 3397	2 × 3397	4 × 10581	2 × 11934	4 × 10581	4 × 13739	2 × 17919	4 × 17919
Distance between ball guide carriages (Lx)	[mm]	87	136	141,7	-	141,7	154	-	186
Distance between ball guide carriages (Ly)	[mm]	-	-	35	35	35	49,75	49,75	80,75

Parameter		WV60	WV80	WV120	MLSM60D	MLSM80D
Geometrical moment of inertia of the profile (Iy)	[mm^4]	$5,8 \times 10^5$	$1,85 \times 10^6$	$7,7 \times 10^6$	$1,19 \times 10^6$	$3,77 \times 10^6$
Geometrical moment of inertia of the profile (Iz)	[mm^4]	$5,9 \times 10^5$	$1,94 \times 10^6$	$9,4 \times 10^6$	$1,08 \times 10^7$	$4,71 \times 10^7$
Friction factor of the guide system (μ)		no guides	no guides	no guides	0,1	0,1
Effiency of the unit		0,8	0,8	0,8	0,8	0,8
Bending factor (b)		0,0003	0,0003	0,0003	0,0003	0,0003
Inertia of ball screw (jsp)	[kgm^2/m]	$8,46 \times 10^{-5}$	$2,25 \times 10^{-4}$	$6,34 \times 10^{-4}$	$2,25 \times 10^{-4}$	$6,34 \times 10^{-4}$
Dynamic load rating of ball screw (Cx) 05 mm lead 10 mm lead 20 mm lead 25 mm lead 40 mm lead 50 mm lead	[N]	 10500 - 11600 - 8400	 12300 13200 13000 - 15400	 21500 33400 29700 14900 -	 12300 13200 13000 - - 15400	 21500 33400 29700 - 14900 -
Dynamic load rating of ball guide (Cy)	[N]	no guides	no guides	no guides	4 × 13770	4 × 17965
Dynamic load rating of ball guide (Cz)	[N]	no guides	no guides	no guides	4 × 13770	4 × 17965
Distance between ball guide carriages (Lx)	[mm]	no guides	no guides	no guides	163	185
Distance between ball guide carriages (Ly)	[mm]	no guides	no guides	no guides	105	164

Additional Technical Data

Linear Motion Systems with Ball Screw and Slide Guides

Technical Data

Parameter		WB40	WB60	M55	M75	M100	M75D	M100D
Geometrical moment of inertia of the profile (Iy)	[mm⁴]	$1{,}04 \times 10^5$	$6{,}1 \times 10^5$	$4{,}27 \times 10^5$	$1{,}9 \times 10^6$	$5{,}54 \times 10^6$	$1{,}9 \times 10^6$	$5{,}54 \times 10^6$
Geometrical moment of inertia of the profile (Iz)	[mm⁴]	$1{,}29 \times 10^5$	$7{,}0 \times 10^5$	$3{,}4 \times 10^5$	$1{,}15 \times 10^6$	$3{,}86 \times 10^6$	$1{,}15 \times 10^6$	$3{,}86 \times 10^6$
Friction factor of the guide system (μ)		0,3	0,3	0,15	0,15	0,15	0,15	0,15
Effiency ball nut unit composite nut unit		 0,8 -	 0,8 -	 0,8 0,5	 0,8 0,5	 0,8 0,5	 0,8 -	 0,8 -
Bending factor (b)		0,0005	0,0005	0,0005	0,0005	0,0005	0,0005	0,0005
Inertia of ball screw (jsp)	[kgm²/m]	$1{,}13 \times 10^{-5}$	$8{,}46 \times 10^{-5}$	$4{,}1 \times 10^{-5}$	$1{,}6 \times 10^{-4}$	$2{,}5 \times 10^{-4}$	$1{,}6 \times 10^{-4}$	$2{,}5 \times 10^{-4}$
Dynamic load rating of ball screw (Cx) 05 mm lead 05,8 mm lead 08 mm lead 10 mm lead 12,7 mm lead 20 mm lead 25 mm lead 32 mm lead	[N]	 4400 - - - - - -	 10500 - - - - 11600 - -	 9300 5420 - 15400 - 1900 - 2000	 10400 - - - 17960 10400 - -	 12500 - - 20600 - - 11800 -	 10400 - - - - 10400 - -	 12500 - - 20100 - - 11800 -

Linear Motion Systems with Belt Drive and Ball Guides

Technical Data

Parameter		WH40	WM60Z	WM80Z	M55	M75	M100	MLSM80Z
Geometrical moment of inertia of the profile (Iy)	[mm⁴]	$12{,}6 \times 10^4$	$5{,}62 \times 10^5$	$1{,}85 \times 10^6$	$4{,}59 \times 10^5$	$1{,}9 \times 10^6$	$5{,}54 \times 10^6$	$3{,}77 \times 10^6$
Geometrical moment of inertia of the profile (Iz)	[mm⁴]	$15{,}3 \times 10^4$	$5{,}94 \times 10^5$	$1{,}94 \times 10^6$	$3{,}56 \times 10^5$	$1{,}15 \times 10^6$	$3{,}86 \times 10^6$	$4{,}71 \times 10^7$
Friction factor of the guide system (μ)		0,05	0,1	0,1	0,02	0,02	0,02	0,1
Effiency of the unit		0,85	0,85	0,85	0,95	0,95	0,95	0,85
Bending factor (b)		0,0005	0,0005	0,0005	0,0005	0,0005	0,0005	0,0005
Specific mass of belt	[kg/m]	0,032	0,074	0,14	0,09	0,16	0,31	0,517
Inertia of pulleys (Jsyn)	[kgm²]	$8{,}8 \times 10^{-6}$	$2{,}13 \times 10^{-5}$	$1{,}12 \times 10^{-4}$	$1{,}7 \times 10^{-5}$	$6{,}8 \times 10^{-5}$	$8{,}5 \times 10^{-5}$	$5{,}077 \times 10^{-4}$
Dynamic load rating of ball guide (Cy)	[N]	2 × 2650	2 × 12964	4 × 18723 (2 × 18723)[1]	2 × 2717	2 × 8206	2 × 13189	4 × 17965
Dynamic load rating of ball guide (Cz)	[N]	2 × 3397	2 × 11934	2 × 17919	2 × 3484	2 × 15484	2 × 24885	4 × 17965
Distance between ball guide carriages (Lx)	[mm]	72	-	-	78	96	140	185
Distance between ball guide carriages (Ly)	[mm]	-	35	49,75	-	-	-	164

[1] Value in brackets = for short carriage.

Additional Technical Data

Linear Motion Systems with Belt Drive and Slide Guides

Technical Data

Parameter		M50	M55	M75	M100
Geometrical moment of inertia of the profile (Iy)	[mm^4]	2,61 × 10^5	4,59 × 10^5	1,9 × 10^6	5,54 × 10^6
Geometrical moment of inertia of the profile (Iz)	[mm^4]	2,44 × 10^5	3,56 × 10^5	1,15 × 10^6	3,86 × 10^6
Friction factor of the guide system (μ)		0,15	0,15	0,15	0,15
Effiency of the unit		0,85	0,85	0,85	0,85
Bending factor (b)		0,0005	0,0005	0,0005	0,0005
Specific mass of belt	[kg/m]	0,086	0,09	0,16	0,31
Inertia of pulleys (Jsyn)	[kgm^2]	3,1 × 10^{-5}	1,7 × 10^{-5}	6,8 × 10^{-5}	8,5 × 10^{-5}

Linear Motion Systems with Belt Drive and Wheel Guides

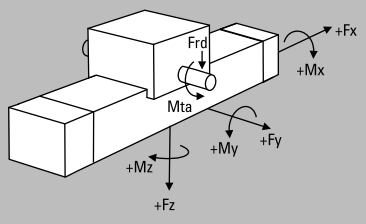
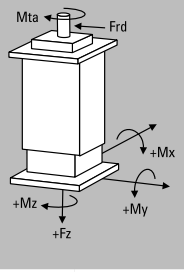
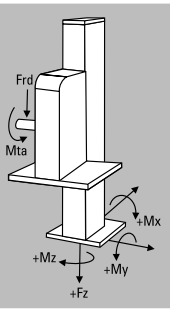
Technical Data

Parameter		WH50	WH80	WH120	MLSH60Z	MLSH80Z
Geometrical moment of inertia of the profile (Iy)	[mm^4]	3,3 × 10^5	1,93 × 10^6	6,69 × 10^6	1,29 × 10^6	4,05 × 10^6
Geometrical moment of inertia of the profile (Iz)	[mm^4]	2,65 × 10^5	1,8 × 10^6	6,88 × 10^6	1,2 × 10^7	4,84 × 10^7
Friction factor of the guide system (μ)		0,1	0,1	0,1	0,1	0,1
Effiency of the unit		0,85	0,85	0,85	0,85	0,85
Bending factor (b)		0,0005	0,0005	0,0005	0,0005	0,0005
Specific mass of belt	[kg/m]	0,055	0,21	0,34	0,119	0,517
Inertia of pulleys (Jsyn)	[kgm^2]	1,928 × 10^{-5}	2.473 × 10^{-4}	1,004 × 10^{-3}	4,604× 10^{-5}	5,077 × 10^{-4}
Dynamic load rating of wheel guide (Cy)	[N]	-	-	-	4 × 1266	4 × 6192
Dynamic load rating of wheel guide (Cz)	[N]	4 × 1270	4 × 3670	4 × 16200	4 × 1266	4 × 6192
Distance between carriage wheels (Lx)	[mm]	198	220	180	109	210
Distance between carriage wheels (Ly)	[mm]	39	65	97	102,5	155,5

Additional Technical Data

Linear Lifting Systems

Technical Data

Parameter		WHZ50	WHZ80	Z2	Z3	ZB
Geometrical moment of inertia of the profile (Ix)	[mm⁴]	-	-	$1{,}87 \times 10^{7}$	$1{,}87 \times 10^{7}$	$1{,}01 \times 10^{6}$
Geometrical moment of inertia of the profile (Iy)	[mm⁴]	$3{,}3 \times 10^{5}$	$1{,}93 \times 10^{6}$	$2{,}19 \times 10^{7}$	$2{,}19 \times 10^{7}$	$1{,}7 \times 10^{6}$
Geometrical moment of inertia of the profile (Iz)	[mm⁴]	$2{,}65 \times 10^{5}$	$1{,}8 \times 10^{6}$	-	-	-
Dynamic load rating of ball screw (Fx)	[N]	belt drive	belt drive	-	-	-
Dynamic load rating of ball screw (Fz) ball screw ø 25 lead 10 mm ball screw ø 25 lead 25 mm ball screw ø 32 lead 10 mm	[N			 21248 11182 47200	 21248 11182 47200	 belt drive
Friction factor of the guide system (μ)		0,1	0,1	0,15	0,15	0,02
Effiency of the unit		0,85	0,85	0,8	0,8	0,95
Specific mass of belt	[kg/m]	0,055	0,119	-	-	0,56
Inertia of pulleys (Jsyn)	[kgm²]	$6{,}906 \times 10^{-5}$	$5{,}026 \times 10^{-4}$	-	-	$2{,}73 \times 10^{-3}$
Inertia of ball screw (jsp) ball screw ø 25 lead 10 ball screw ø 25 lead 25 ball screw ø 32 lead 10	[kgm²/m]	 - - -	 - - -	 $2{,}1 \times 10^{-4}$ $2{,}6 \times 10^{-4}$ $6{,}43 \times 10^{-4}$	 $2{,}1 \times 10^{-4}$ $2{,}6 \times 10^{-4}$ $6{,}43 \times 10^{-4}$	 - - -
Dynamic load rating of ball guide (Cx)	[N]	-	-	slide guide	slide guide	13100
Dynamic load rating of ball guide (Cy)	[N]	4 × 1270	4 × 3670	slide guide	slide guide	13100
Distance between ball guide carriages (Lx)	[mm]	198	220	-	-	20
Distance between ball guide carriages (Ly)	[mm]	39	65	slide guide	slide guide	255
Distance between ball guide carriages (Lz)	[mm]	-	-	slide guide	slide guide	255
Definition of forces						

Additional Technical Data

Linear Rod Units

Technical Data

Parameter		WZ60	WZ80
Geometrical moment of inertia of the profile (Iy)	[mm^4]	$5{,}8 \times 10^5$	$1{,}85 \times 10^6$
Geometrical moment of inertia of the profile (Iz)	[mm^4]	$5{,}9 \times 10^5$	$1{,}94 \times 10^6$
Friction factor of the guide system (μ)		0,1	0,1
Effiency of the unit		0,8	0,8
Inertia of ball screw (jsp)	[kgm^2/m]		
05 mm lead		$8{,}46 \times 10^{-5}$	$2{,}25 \times 10^{-4}$
10 mm lead		-	$2{,}25 \times 10^{-4}$
20 mm lead		$8{,}46 \times 10^{-5}$	$2{,}25 \times 10^{-4}$
25 mm lead		-	-
32 mm lead		-	-
40 mm lead		-	-
50 mm lead		$8{,}46 \times 10^{-5}$	$2{,}25 \times 10^{-4}$
Dynamic load rating of ball screw (Cx)	[N]		
05 mm lead		10500	12300
10 mm lead		-	13200
20 mm lead		11600	13000
25 mm lead		-	-
32 mm lead		-	-
40 mm lead		-	-
50 mm lead		8400	15400
Dynamic load rating of ball guide (Cy)	[N]	2 × 12964	2 × 18723
Dynamic load rating of ball guide (Cz)	[N]	2 × 11943	2 × 17919
Distance between ball guide carriages (Lx)	[mm]	-	-
Distance between ball guide carriages (Ly)	[mm]	35	50
Dynamic rating of the ball bushing	[N]	8300	13700

Drive Calculations

Screw Driven Linear Motion Systems

Feed Force Formula [N]

$$F_x = m \times g \times \mu$$

F_x = feed force [N]
m = total mass to be moved [kg] [1]
g = acceleration due to gravity [m/s²]
μ = friction factor specific for each unit

Acceleration Force Formula [N]

$$F_a = m \times a$$

F_a = acceleration force [N]
m = mass to be operated [kg]
a = acceleration [m/s²] [2]

Power Formula [kW]

$$P = \frac{M_A \times n_{max} \times 2 \times 3{,}14}{60 \times 1000}$$

P = required power [kW]
M_A = required drive moment [Nm]
n_{max} = maximum required rotational speed [rpm]

Drive Moment Formulas [Nm]

$$M_A = M_{load} + M_{trans} + M_{rot} + M_{idle}$$

$$M_{load} = \frac{F_x \times p}{2 \times 3{,}14 \times 1000}$$

$$M_{trans} = \frac{F_a \times p}{2 \times 3{,}14 \times 1000}$$

$$M_{rot} = j_{sp} \times \frac{2 \times 3{,}14 \times n_{max} \times a \times 2}{V_{max} \times 60 \times 1000}$$

M_{idle} = see table for unit in question

M_A = required drive moment [Nm]
M_{load} = moment as a result of various loads [N]
M_{trans} = translational acceleration moment [Nm]
M_{rot} = rotational acceleration moment [Nm]
M_{idle} = carriage/rod idle torque [Nm] [3]
F_x = feed force [N]
p = screw lead [mm]
F_a = maximum required acceleration force [N]
j_{sp} = inertia of ball screw per meter [kgm²/m] [4]
n_{max} = maximum required rotational speed [rpm]
a =maximum required acceleration [m/s²]
V_{max} = maximum required linear speed [m/s]

[1] The total mass is the mass of all masses to be moved (objects to be moved, carriage(s)/rod, screw).

[2] In vertical applications, the mass acceleration must be added to the acceleration due to gravity g (9,81 m/s²).

[3] This value can be found in the carriage idle torque tables for each linear motion system.

[4] This value can be found in the additional technical data tables.

Drive Calculations

Belt Driven Linear Motion Systems

Feed Force Formula [N]

$$F_x = m \times g \times \mu$$

F_x = feed force [N]
m = total mass to be moved [kg] [1]
g = acceleration due to gravity [m/s²]
μ = friction factor specific for each unit

Acceleration Force Formula [N]

$$F_a = m \times a$$

F_a = acceleration force [N]
m = mass to be operated [kg]
a = acceleration [m/s²] [2]

Power Formula [kW]

$$P = \frac{M_A \times n_{max} \times 2 \times 3{,}14}{60 \times 1000}$$

P = required power [kW]
M_A = required drive moment [Nm]
n_{max} = maximum required rotational speed [rpm]

Drive Moment Formulas [Nm]

$$M_A = M_{load} + M_{trans} + M_{rot} + M_{idle}$$

$$M_{load} = \frac{F_x \times d_o}{1000 \times 2}$$

$$M_{trans} = \frac{F_a \times d_o}{1000 \times 2}$$

$$M_{rot} = J_{syn} \times \frac{2 \times 3{,}14 \times n_{max}}{60} \times \frac{a}{V_{max}}$$

M_{idle} = see table for unit in question

M_A = required drive moment [Nm]
M_{load} = moment as a result of various loads [N]
M_{trans} = translational acceleration moment [Nm]
M_{rot} = rotational acceleration moment [Nm]
M_{idle} = carriage/rod idle torque [Nm] [3]
F_x = feed force [N]
d_o = pulley diameter [mm] [4]
F_a = maximum required acceleration force [N]
J_{syn} = idle torque of pulleys [kgm²] [5]
n_{max} = maximum required rotational speed [rpm]
a = maximum required acceleration [m/s²]
V_{max} = maximum required linear speed [m/s]

[1] The total mass is the mass of all masses to be moved (objects to be moved, carriage(s)/rod, belt).

[2] In vertical applications, the mass acceleration must be added to the acceleration due to gravity g (9,81 m/s²).

[3] This value can be found in the carriage idle torque tables.

[4] This value can be found in the performance specifications tables for each linear motion system.

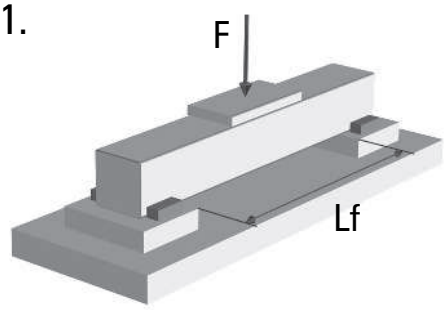
[5] This value can be found in the additional technical data tables.

Deflection Calculations

How to calculate the deflection of the profile

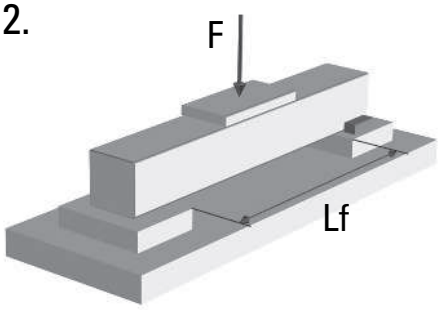
Load Cases

1.



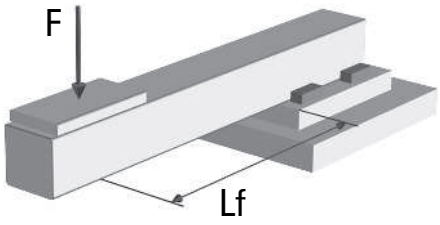
Profile supported in both ends.
Profile fixed at both sides.

2.



Profile supported in both ends.
Profile fixed at one side.

3.



Profile supported in one end.
Profile fixed at one side.

Permissible Profile Deflection Formula [mm]

$$f_h = L_f \times b$$

f_h = permissible profile deflection [mm]
L_f = length of profile being bent [mm]
b = bending factor [1]

Profile Deflection Formulas [mm]

Load Case 1.

$$f_{max} = \frac{m'_{100} \times g \times L_f^4}{100 \times 384 \times E_{Al} \times I_y} + \frac{(m_{ext} \times m_c) \times g \times L_f^3}{192 \times E_{Al} \times I_y}$$

Load Case 2.

$$f_{max} = \frac{m'_{100} \times g \times L_f^4}{100 \times 185 \times E_{Al} \times I_y} + \frac{(m_{ext} \times m_c) \times g \times L_f^3}{48 \times \sqrt{5} \times E_{Al} \times I_y}$$

Load Case 3.

$$f_{max} = \frac{m'_{100} \times g \times L_f^4}{100 \times 8 \times E_{Al} \times I_y} + \frac{(m_{ext} \times m_c) \times g \times L_f^3}{3 \times E_{Al} \times I_y}$$

f_{max} = deflection of the profile [mm]
m'_{100} = weight of every 100 mm of stroke [kg] [2]
m_{ext} = external load on carriage [kg]
m_c = weight of carriage(s) [kg] [2]
g = acceleration due to gravity [m/s^2]
E_{Al} = elastic modulus of aluminium (70000 N/mm^2)
I_y = geometrical moment of inertia of the profile in Y direction [mm^4] [1]

Conclusion Formulas

$f_h > f_{max}$ = deflection OK

$f_h < f_{max}$ = deflection not OK, L_f must be shorter

[1] This value can be found in the additional technical data tables.

[2] This value can be found in the performance specifications tables for each unit.

Deflection Calculations

Examples of calculations of the profile deflection

Example 1

Type of linear motion system:
WH80

Load case:
Case 1 - profile supported in both ends and fixed at both sides.

Load to be moved by carriage:
m_{ext} = 150 kg

Distance between supports:
L_f = 600 mm

Specific unit data:
m'_{100} = 0,93 kg
m_c = 2,75 kg
E_{Al} = 70000 N/mm^2
I_y = 1,93 × 10^6 mm^4
b = 0,0005

Calculated values:
f_h = 0,3 mm
f_{max} = 0,013 mm

Conclusion:
$f_h > f_{max}$ = deflection OK

Example 2

Type of linear motion system:
M55 (MF06B)

Load case:
Case 2 - profile supported in both ends and fixed at one side.

Load to be moved by carriage:
m_{ext} = 100 kg

Distance between supports:
L_f = 600 mm

Specific unit data:
m'_{100} = 0,53 kg
m_c = 1,2 kg
E_{Al} = 70000 N/mm^2
I_y = 4,59 × 10^5 mm^4
b = 0,0005

Calculated values:
f_h = 0,3 mm
f_{max} = 0,063 mm

Conclusion:
$f_h > f_{max}$ = deflection OK

Example 3

Type of linear motion system:
WM80

Load case:
Case 3 - profile supported and fixed at one end.

Load to be moved by carriage:
m_{ext} = 120 kg

Distance between supports:
L_f = 400 mm

Specific unit data:
m'_{100} = 1,08 kg
m_c = 4,26 kg
E_{Al} = 70000 N/mm^2
I_y = 1,85 × 10^6 mm^4
b = 0,0003

Calculated values:
f_h = 0,12 mm
f_{max} = 0,203 mm

Conclusion:
$f_h > f_{max}$ = deflection not OK

Ordering

How to Order

When ordering a Thomson linear motion system it is necessary to first make sure that the proper sizing and selection has been done. The demand on your system will impact on your choice of stroke length, profile size, belt or screw drive, environmental protection demands etc.

The load and speed demand will tell you the configuration of gearboxes drive shafts and motor attachment accessories that are necessary. You will also need to evaluate what accessories that are necessary, such as mounting brackets, gearboxes, switches, sensors and feedback devices.

We will assist you in the sizing and selection work and determining of part numbers but it is important that you are aware of the demand and need of your specific application in order to enable us to supply you with the correct linear unit.

On the following pages you will find the ordering keys for the different linear motion systems shown in earlier chapters. These keys are self-explanatory and by following the examples you can quickly and easily learn about the different options and versions available. Please also visit www.thomsonlinear.com/selectors where you can find a product advisor that makes the selection and ordering process much easier, or contact us for further support.

Ordering Keys

Linear Motion Systems with Ball Screw Drive and Ball Guides

WM40S, WM40D, WM60S, WM60D, WM60X, WM80S, WM80D, WM120D

Your Code							
	1	2	3	4	5	6	7
Example	WM06D	020	-02545	-03715	A	Z	-0520

1. Type of unit
WM04S = WM40S unit with single ball nut
WM04D = WM40D unit with double ball nuts
WM06S = WM60S unit with single ball nut
WM06D = WM60D unit with double ball nuts
WM06X = WM60X unit with left/right screw
WM08S = WM80S unit with single ball nut
WM08D = WM80D unit with double ball nuts
WM12D = WM120D unit with double ball nuts

2. Screw lead[1]
005 = 5 mm
010 = 10 mm
020 = 20 mm
040 = 40 mm
050 = 50 mm

3. Maximum stroke (S max)
- ••••• = distance in mm

4. Total length of unit (L tot)
- ••••• = distance in mm

5. Drive shaft configuration[2]
A = single shaft without key way
C = single shaft with key way
G = double shafts, first without key way and second for encoder
I = double shafts, first with key way and second for encoder

6. Type of carriage[3]
N = single standard carriage
S = single short carriage
L = single long carriage
Z = double standard carriages
Y = double short carriages
M = double long carriages

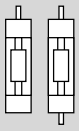
7. Distance between double carriages
- 0000 = always for single carriages
- •••• = distance in mm

[1] See teble below for available combinations of units and ball screw leads.

Type of unit	Available screw leads [mm]				
	5	10	20	40	50
WM04S	x				
WM04D	x				
WM06S	x		x		x
WM06D	x		x		x
WM06X	x				
WM08S	x	x	x		x
WM08D	x	x	x		x
WM12D	x	x	x	x	

[2] See below for the definition of shafts.

Single Double



[3] See table below for available combinations of units and carriage types.

Type of unit	Available carriage types					
	N	S	L	Z	Y	M
WM04S	x			x		
WM04D			x			x
WM06S		x			x	
WM06D	x		x	x		
WM06X	x	x	x			
WM08S		x			x	
WM08D	x		x	x		
WM12D	x		x	x		

Note! for ordering of options type EN, ES, KRG, RT, ADG and MGK, see accessory index on page 125.

Ordering Keys

Linear Motion Systems with Ball Screw Drive and Ball Guides

WV60, WV80, WV120

Your Code							
	1	2	3	4	5	6	7
Example	WV08D	020	-02745	-03295	G	N	-0000

1. Type of unit
WV06D = WV60 unit
WV08D = WV80 unit
WV12D = WV120 unit

2. Ball screw lead[1]
005 = 5 mm
010 = 10 mm
020 = 20 mm
040 = 40 mm
050 = 50 mm

3. Maximum stroke (S max)
- •••••= distance in mm

4. Total length of unit (L tot)
- •••••= distance in mm

5. Drive shaft configuration[2]
A = single shaft without key way
C = single shaft with key way
G = double shafts, first without key way and second for encoder
I = double shafts, first with key way and second for encoder

6. Type of carriage
N = single standard carriage

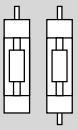
7. Distance between double carriages
- 0000 = always for single carriages

[1] See table below for available combinations of units and ball screw leads.

Type of unit	Available screw leads [mm]				
	5	10	20	40	50
WV60	x		x		x
WV80	x	x	x		x
WV120	x	x	x	x	

[2] See below for the definition of shafts.

Single Double



Note! for ordering of options type EN, ES, KRG, RT, ADG and MGK, see accessory index on page 125.

Ordering Keys

Linear Motion Systems with Ball Screw Drive and Ball Guides

MLSM60D, MLSM80D

Your Code							
	1	2	3	4	5	6	7
Example	MLSM06D	020	-03800	-04645	C	L	-0000

1. Type of unit
MLSM06D = MLSM60 unit
MLSM08D = MLSM80 unit

2. Ball screw lead
005 = 5 mm
010 = 10 mm
020 = 20 mm
040 = 40 mm
050 = 50 mm

3. Maximum stroke (S max)
- ••••• = distance in mm

4. Total length of unit (L tot)
- ••••• = distance in mm

5. Drive shaft configuration[2]
A = single shaft without key way
C = single shaft with key way
G = double shafts, first without key way and second for encoder
I = double shafts, first with key way and second for encoder

6. Carriage configuration
N = single standard carriage
L = single long carriage
Z = double standard carriages

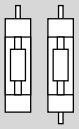
7. Distance between double carriages
- 0000 = always for single carriages
- •••• = distance in mm

[1] See table below for available combinations of units and ball screw leads.

Type of unit	Available screw leads [mm]				
	5	10	20	40	50
MLSM06D	x		x		x
MLSM08D	x	x	x	x	

[2] See below for the definition of shafts.

Single Double



Ordering Keys

Linear Motion Systems with Ball Screw Drive and Slide Guides

WB40, WB60

Your Code							
	1	2	3	4	5	6	7
Example	WB40S	005	-00500	-00700	C	N	0

1. Type of unit
WB04S = WB40 unit with ball screw
WB04T = WB40 unit with lead screw
WB06S = WB60 unit with ball screw
WB06T = WB60 unit with lead screw

2. Screw lead and screw type[1]
004 = 4 mm, lead screw
005 = 5 mm, ball screw
008 = 8 mm, lead screw
020 = 20 mm, ball screw

3. Maximum stroke (S max)
- ••••• = distance in mm

4. Total length of unit (L tot)
- ••••• = distance in mm

5. Drive shaft configuration[2]
A = single shaft without key way
C = single shaft with key way
G = double shafts, first without key way and second for encoder
I = double shafts, first with key way and second for encoder

6. Carriage configuration
N = single standard carriage

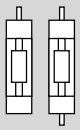
7. Number of screw supports[3]
0 = no screw supports
1 = one pair of screw supports
2 = two pairs of screw supports
3 = three pairs of screw support

[1] See table below for available combinations of units and screw leads.

Type of unit	Available screw leads [mm]			
	4	5	8	20
WB04S		x		
WB04T	x		x	
WB06S		x		x
WB06T			x	

[2] Se below for the definition of shafts.

Single Double



[3] WB40 units can not have any screw supports at all (allways 0 in this position) while WB60 can have any of the stated possibilities.

Ordering Keys

Linear Motion Systems with Ball Screw Drive and Slide Guides

M55, M75, M100

Your Code							
	1	2	3	4	5	6	7
Example	MG07	K057	C	35	S	305	+S1

1. Type of unit
MG06 = M55 unit
MG07 = M75 unit
MG10 = M100 unit

2. Ball screw type, lead and tolerance class[2]
C057 = composite nut, 5 mm, T7
K057 = ball nut, 5 mm, T7
KU57 = ball nut, 5,08 mm, T7
C109 = composite nut, 10 mm, T9
K107 = ball nut, 10 mm, T7
K109 = ball nut, 10 mm, T9
K129 = ball nut, 12,7 mm, T9
K207 = ball nut, 20 mm, T7
C257 = composite nut, 25 mm, T7
K257 = ball nut, 25 mm, T7
K259 = ball nut, 25 mm, T9
C329 = composite nut, 32 mm, T9

3. Type of carriages
A = single standard carriage
C = double standard carriages

4. Distance between carriages (Lc)
00 = for all single standard carriage units
•• = distance in cm between carriages

5. Screw supports
X = no screw supports
S = single screw supports
D = double screw supports

6. Ordering length (L order)
••• = distance in cm

7. Protection option[1]
+S1 = S1 wash down protection

[1] Leave position blank if no additional protection is required.
[2] See table below for available combinations of units and ball screw type, lead and tolerance.

Ball screw type	Type of unit		
	M55	M75	M100
C057		x	
K057	x	x	x
KU57	x		
C109			x
K107	x		x
K109			x
K129		x	
K207	x	x	
C257			x
K257			x
K259			x
C329	x		

Ordering Keys

Linear Motion Systems with Ball Screw Drive and Slide Guides

M75D, M100D

Your Code							
	1	2	3	4	5	6	7
Example	MG10	D107	A	00	X	355	

1. Type of unit
MG07 = M75D unit
MG10 = M100D unit

2. Ball screw type, lead and tolerance class[2]
D057 = pre-loaded ball nut, 5 mm, T7
D107 = pre-loaded ball nut, 10 mm, T7
D207 = pre-loaded ball nut, 20 mm, T7
D257 = pre-loaded ball nut, 25 mm, T7

3. Type of carriages
A = single standard carriage
C = double standard carriages

4. Distance between carriages (Lc)
00 = for all single standard carriage units
•• = distance in cm between carriages

5. Screw supports
X = no screw supports
S = single screw supports
D = double screw supports

6. Ordering length (L order)
••• = distance in cm

7. Protection option[1]
+S1 = S1 wash down protection

[1] Leave position blank if no protection option required.
[2] See below table for available combinations of units and ball screw type, lead and tolerance.

Ball screw type	Type of unit	
	M75	M100
D057	x	x
D107		x
D207	x	
D257		x

Ordering Keys

Linear Motion Systems with Belt Drive and Ball Guides

WH40						
Your Code						
	1	2	3	4	5	6
Example	WH04Z100	-01400	-01755	H	L	-0400

1. Type of unit
WH04Z100 = WH40 unit

2. Maximum stroke (S max)
- ••••• = distance in mm

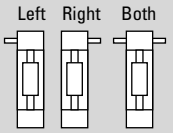
3. Total length of unit (L tot)
- ••••• = distance in mm

4. Drive shaft configuration[1]
A = shaft on left side without key way
B = shaft on right side without key way
C = shaft on left side with key way
D = shaft on right side with key way
E = shaft on left side without key way and shaft on right side with key way
F = shaft on left side with key way and shaft on right side without key way
G = shaft on left side without key way and shaft on right side for encoder
H = shaft on left side for encoder and shaft on right side without key way
I = shaft on left side with key way and shaft on right side for encoder
J = shaft on left side for encoder and shaft on right side with key way
L = shaft on both sides without key way
M = shaft on both sides with key way
W = hollow shaft on both sides with clamping unit

5. Carriage configuration
N = single standard carriage
L = single long carriage
Z = double standard carriages

6. Distance between double carriages
- 0000 = always for single carriages
- •••• = distance in mm

[1] See below for the definition of shafts.



Note! for ordering of options type EN, ES, KRG, RT, ADG and MGK, see accessory index on page 125.

Ordering Keys

Linear Motion Systems with Belt Drive and Ball Guides

WM60Z, WM80Z

Your Code						
	1	2	3	4	5	6
Example	WM08Z170	-02545	-03715	D	L	-0000

1. Type of unit
WM06Z120 = WM60Z unit
WM08Z170 = WM80Z unit

2. Maximum stroke (S max)
- ••••• = distance in mm

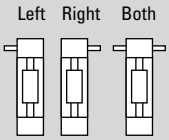
3. Total length of unit (L tot)
- ••••• = distance in mm

4. Drive shaft configuration[1]
A = shaft on left side without key way
B = shaft on right side without key way
C = shaft on left side with key way
D = shaft on right side with key way
E = shaft on left side without key way and shaft on right side with key way
F = shaft on left side with key way and shaft on right side without key way
G = shaft on left side without key way and shaft on right side for encoder
H = shaft on left side for encoder and shaft on right side without key way
I = shaft on left side with key way and shaft on right side for encoder
J = shaft on left side for encoder and shaft on right side with key way
L = shaft on both sides without key way
M = shaft on both sides with key way
V = hollow shaft on both sides for Micron DT/DTR planetary gear option

5. Carriage configuration[2]
N = single standard carriage
S = single short carriage
L = single long carriage
Z = double standard carriages
Y = double short carriages

6. Distance between double carriages
- 0000 = always for single carriages
- •••• = distance in mm

[1] See below for the definition of shafts.



[2] See table below for available combinations of units and carriage types.

Type of unit	Available carriage types				
	N	S	L	Z	Y
WM06Z		x			x
WM08Z	x	x	x	x	x

Ordering Keys

Linear Motion Systems with Belt Drive and Ball Guides

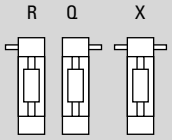
M55, M75, M100						
Your Code						
	1	2	3	4	5	6
Example	MF06B105	A	00	X	450	+S1

1. Type of unit
MF06B105 = M55 unit
MF07B130 = M75 unit
MF10B176 = M100 unit

2. Type of carriages
A = single standard carriage
C = double standard carriages

3. Distance between carriages (Lc)
00 = for all single standard carriage units
•• = distance in cm between carriages

4. Drive shaft configuration
R = shaft on the side as shown in picture
Q = shaft on the side as shown in picture
X = shaft on both sides



5. Ordering length (L order)
••• = distance in cm

6. Protection option[1]
+S1 = S1 wash down protection

[1] Leave blank if no protection option required.

Ordering Keys

Linear Motion Systems with Belt Drive and Ball Guides

MLSM80Z						
Your Code						
	1	2	3	4	5	6
Example	MLSM08Z200	-05000	-05570	A	N	-0000

1. Type of unit
MLSM08Z200 = MLSM80 unit

2. Maximum stroke (S max)
- ••••• = distance in mm

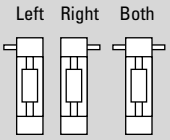
3. Total length of unit (L tot)
- ••••• = distance in mm

4. Drive shaft configuration[1]
A = shaft on left side without key way
B = shaft on right side without key way
C = shaft on left side with key way
D = shaft on right side with key way
E = shaft on left side without key way and shaft on right side with key way
F = shaft on left side with key way and shaft on right side without key way
G = shaft on left side without key way and shaft on right side for encoder
H = shaft on left side for encoder and shaft on right side without key way
I = shaft on left side with key way and shaft on right side for encoder
J = shaft on left side for encoder and shaft on right side with key way
L = shaft on both sides without key way
M = shaft on both sides with key way

5. Carriage configuration
N = single standard carriage
L = single long carriage
Z = double standard carriages

6. Distance between double carriages
- 0000 = always for single carriages
- •••• = distance in mm

[1] See below for the definition of shafts.



Ordering Keys

Linear Motion Systems with Belt Drive and Slide Guides

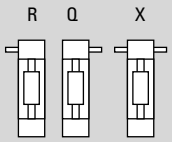
M50

Your Code				
	1	2	3	4
Example	MG05B130	A00	R	560

1. Type of unit
MG05B130 = M50 unit

2. Type of carriage
A00 = single standard carriage

3. Drive shaft configuration
R = shaft on the side as shown in picture
Q = shaft on the side as shown in picture
X = shaft on both sides



4. Ordering length (L order)
••• = distance in cm

M55, M75, M100

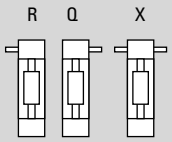
Your Code						
	1	2	3	4	5	6
Example	MG06B105	A	00	X	450	+S2

1. Type of unit
MG06B105 = M55 unit
MG07B130 = M75 unit
MG10B176 = M100 unit

2. Type of carriages
A = single standard carriage
C = double standard carriages

3. Distance between carriages (Lc)
00 = for all single standard carriage units
•• = distance in cm between carriages

4. Drive shaft configuration
R = shaft on the side as shown in picture
Q = shaft on the side as shown in picture
X = shaft on both sides



5. Ordering length (L order)
••• = distance in cm

6. Protection option[1]
+S1 = S1 wash down protection
+S2 = S2 chemical protection

[1] Leave blank if no protection option required.

Ordering Keys

Linear Motion Systems with Belt Drive and Wheel Guides

WH50, WH80, WH120

Your Code						
	1	2	3	4	5	6
Example	WH08Z200	-02300	-02710	J	L	-0000

1. Type of unit
WH05Z120 = WH50 unit
WH08Z200 = WH80 unit
WH12Z260 = WH120 unit

2. Maximum stroke (S max)
- ••••• = distance in mm

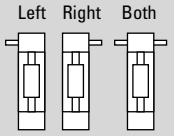
3. Total length of unit (L tot)
- ••••• = distance in mm

4. Drive shaft configuration[1]
A = shaft on left side without key way
B = shaft on right side without key way
C = shaft on left side with key way
D = shaft on right side with key way
E = shaft on left side without key way and shaft on right side with key way
F = shaft on left side with key way and shaft on right side without key way
G = shaft on left side without key way and shaft on right side for encoder
H = shaft on left side for encoder and shaft on right side without key way
I = shaft on left side with key way and shaft on right side for encoder
J = shaft on left side for encoder and shaft on right side with key way
K = hollow shaft on both sides without clamping unit
L = shaft on both sides without key way
M = shaft on both sides with key way
V = hollow shaft on both sides for Micron DT/DTR planetary gear option
W = hollow shaft on both sides with clamping unit

5. Carriage configuration
N = single standard carriage
L = single long carriage
Z = double standard carriages

6. Distance between double carriages
- 0000 = always for single carriages
- •••• = distance in mm

[1] See below for the definition of shafts.



Note! for ordering of options type EN, ES, KRG, RT, ADG and MGK, see accessory index on page 125.

Ordering Keys

Linear Motion Systems with Belt Drive and Wheel Guides

MLSH60Z, MLSH80Z						
Your Code						
	1	2	3	4	5	6
Example	MLSH06Z135	-04500	-05580	D	Z	-0600

1. Type of unit
MLSH06Z135 = MLSH60 unit
MLSH08Z200 = MLSH80 unit

2. Maximum stroke (S max)
- ••••• = distance in mm

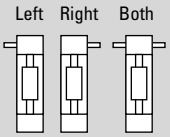
3. Total length of unit (L tot)
- ••••• = distance in mm

4. Drive shaft configuration[1]
A = shaft on left side without key way
B = shaft on right side without key way
C = shaft on left side with key way
D = shaft on right side with key way
E = shaft on left side without key way and shaft on right side with key way
F = shaft on left side with key way and shaft on right side without key way
G = shaft on left side without key way and shaft on right side for encoder
H = shaft on left side for encoder and shaft on right side without key way
I = shaft on left side with key way and shaft on right side for encoder
J = shaft on left side for encoder and shaft on right side with key way
L = shaft on both sides without key way
M = shaft on both sides with key way

5. Carriage configuration
N = single standard carriage
L = single long carriage
Z = double standard carriages

6. Distance between double carriages
- 0000 = always for single carriages
- •••• = distance in mm

[1] See below for the definition of shafts.



Ordering Keys

Linear Lifting Systems

WHZ50, WHZ80

Your Code						
	1	2	3	4	5	6
Example	WHZ08Z200	-01000	-01410	A	N	-0000

1. Type of unit
WHZ05Z120 = WHZ50 unit
WHZ08Z200 = WHZ80 unit

2. Maximum stroke (S max)
- ••••• = distance in mm

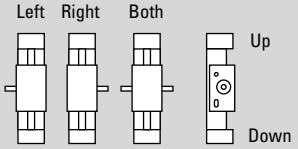
3. Total length of unit (L tot)
- ••••• = distance in mm

4. Drive shaft configuration[1]
A = shaft on left side without key way
B = shaft on right side without key way
C = shaft on left side with key way
D = shaft on right side with key way
E = shaft on left side without key way and shaft on right side with key way
F = shaft on left side with key way and shaft on right side without key way
G = shaft on left side without key way and shaft on right side for encoder
H = shaft on left side for encoder and shaft on right side without key way
I = shaft on left side with key way and shaft on right side for encoder
J = shaft on left side for encoder and shaft on right side with key way
L = shaft on both sides without key way
M = shaft on both sides with key way
V = hollow shaft on both sides for Micron DT/DTR planetary gear option
W = hollow shaft on both sides with clamping unit

5. Carriage configuration
N = single standard carriage
L = single long carriage
Z = double standard carriages

6. Distance between double carriages
- 0000 = always for single carriages
- •••• = distance in mm

[1] See below for the definition of shafts and up and down.



Note! for ordering of options type EN, ES, KRG, RT, ADG and MGK, see accessory index on page 125.

Z2, Z3

Your Code				
	1	2	3	4
Example	MGZ3K	25259	-250	450

1. Type of unit
MGZ2K = Z2 unit
MGZ3K = Z3 unit

2. Ball screw diameter, lead and tolerance class
25109 = 25 mm, 10 mm, T9
25259 = 25 mm, 25 mm, T9
32207 = 32 mm, 20 mm, T7

3. Minimum retracted length (L min)
- ••• = distance in cm

4. Maximum extended length (L max)
••• = distance in cm

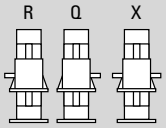
Ordering Keys

Linear Lifting Systems

ZB			
Your Code			
	1	2	3
Example	MF-ZB200A00	X	150

1. Type of unit
MF-ZB200A00 = ZB unit

2. Drive shaft configuration
R = shaft on the side as shown in picture
Q = shaft on the side as shown in picture
X = shaft on both sides



3. Ordering length (L order)
••• = distance in cm

Ordering Keys

Linear Rod Units

WZ60, WZ80

Your Code						
	1	2	3	4	5	6
Example	WZ06S	20	-00350	-00780	C	N

1. Type of unit
WZ06 = WZ60 unit
WZ08 = WZ80 unit

2. Ball screw lead
05 = 5 mm
10 = 10 mm
20 = 20 mm
50 = 50 mm

3. Maximum stroke (S max)
- ••••• = distance in mm

4. Total length of unit (L tot)
- •••• = distance in mm

5. Drive shaft configuration
A = shaft without key way
C = shaft with key way

6. Extension tube configuration
N = standard

[1] See table below for available combinations of units and screw leads.

Type of unit	Available screw leads [mm]			
	5	10	20	50
WZ06	x		x	x
WZ08	x	x	x	x

Note! for ordering of options type EN, ES, KRG, RT and MGK, see accessory index on page 125.

Ordering Keys

Non Driven Linear Motion Systems

WH40N, WH50N, WH80N, WH120N

Your Code						
	1	2	3	4	5	6
Example	WH04N000	-04500	-04640	K	N	-0000

1. Type of unit
WH04N000 = WH40N unit
WH05N000 = WH50N unit
WH08N000 = WH80N unit
WH12N000 = WH120N unit

2. Maximum stroke (S max)
- ••••• = distance in mm

3. Total length of unit (L tot)
- ••••• = distance in mm

4. Drive shaft configuration[1]
K = no shaft

5. Carriage configuration
N = single standard carriage
L = single long carriage
Z = double standard carriages

6. Distance between double carriages
- 0000 = always for single carriages
- •••• = distance in mm

WM40N, WM60N, WM80N, WM120N

Your Code						
	1	2	3	4	5	6
Example	WM08N000	-07010	-07210	K	N	-0000

1. Type of unit
WM04N000 = WM40N unit
WM06N000 = WM60N unit
WM08N000 = WM80N unit
WM12N000 = WM120N unit

2. Maximum stroke (S max)
- ••••• = distance in mm

3. Total length of unit (L tot)
- ••••• = distance in mm

4. Drive shaft configuration
K = no shaft

5. Type of carriage[1]
N = single standard carriage
S = single short carriage
L = single long carriage
Z = double standard carriages
Y = double short carriages

6. Distance between double carriages
- 0000 = always for single carriages
- •••• = distance in mm

[1] See table below for available combinations of units and carriage types.

Type of unit	Available carriage types				
	N	S	L	Z	Y
WM04N000	x		x	x	
WM06N000	x	x	x	x	x
WM08N000	x	x	x	x	x
WM12N000	x		x	x	

Ordering Keys

Non Driven Linear Motion Systems

M75N, M100N

Your Code						
	1	2	3	4	5	6
Example	MG10N000	A	00	X	450	

1. Type of unit
MG07N000 = M75N unit with slide guides
MG10N000 = M100N unit with slide guides
MF07N000 = M75N unit with ball guides
MF10N000 = M100N unit with ball guides

2. Type of carriages
A = single standard carriage
C = double standard carriages

3. Distance between carriages (Lc)
00 = for all single standard carriage units
•• = distance in cm between carriages

4. Screw supports
X = no screw supports

5. Ordering length (L order)
••• = distance in cm

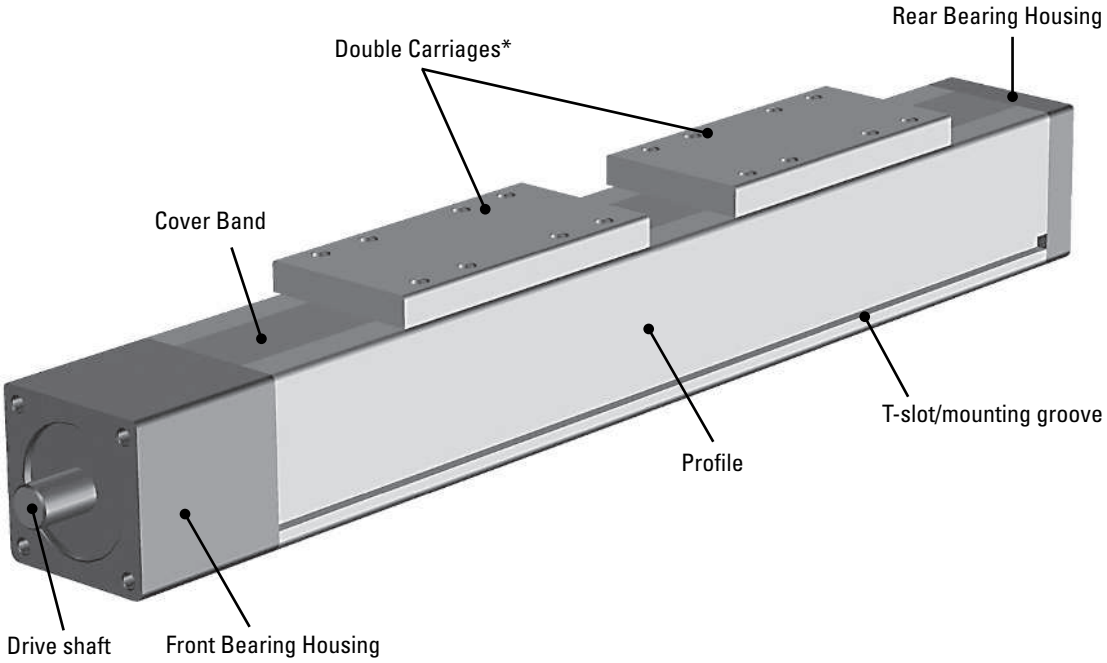
6. Protection option[1]
+S1 = wash down protection

[1] Leave blank if no protection option required.

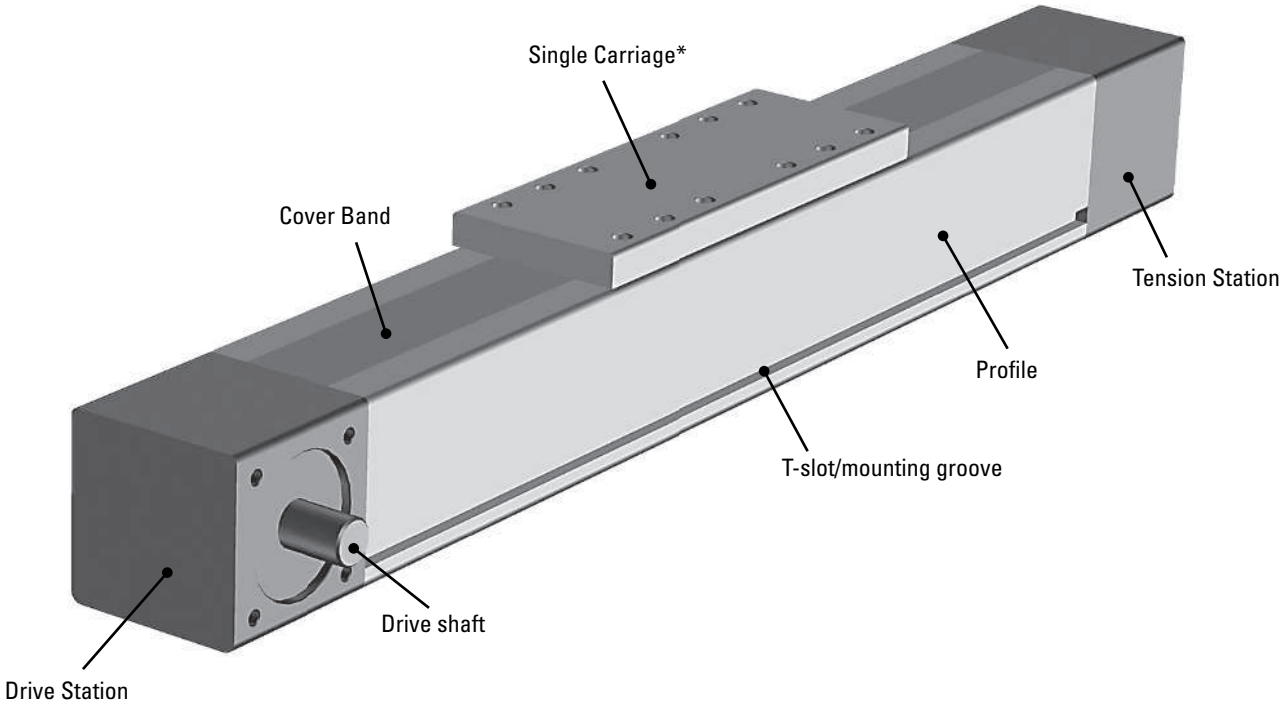
Terminology

Basic Linear Motion System Terminology

Screw Driven Unit



Belt Driven Unit



* Both screw and belt driven units can have single or double carriages.

Glossary

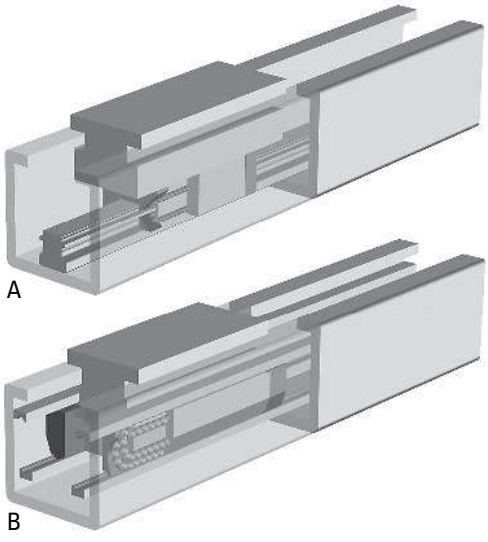
A - Belt D

Acceleration
Acceleration is a measure of the rate of speed change going from standstill (or a lower speed) to a higher speed. Please contact customer service if your application is critical to which acceleration rate is acceptable or needed.

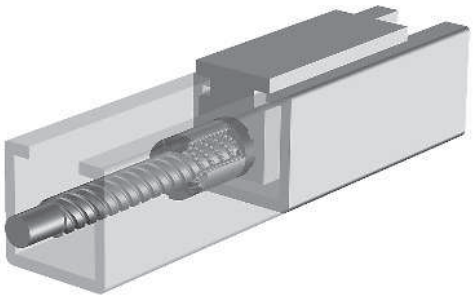
Accuracy
There are several types of accuracy and many different factors that will affect the overall accuracy of a system. Also see “Repeatability”, “Positioning Accuracy”, “Resolution”, “Lead Accuracy” and “Backlash”.

Backlash
Backlash is the stack up of tolerances (play) within the leadscrew/belt transmission assembly and gearing which creates a dead band when changing directions. The result is that the motor can rotate some before any motion can be seen on the carriage when reversing the direction of the motor rotation. The backlash varies depending of the liner motion system model.

Ball Guides
A ball guide consists of a ball rail and a ball bushing. The ball rail is made of hardened steel and runs along the inside of the profile. The ball bushing is attached to the carriage of the unit and contains balls that roll against the rail. The balls in the bushing can be recirculating or have fixed ball positions depending on the type of ball guide. The recirculating type has a longer life and better load capability while the fixed type typically is much smaller. Thomson uses three major types of ball guides in its linear motion systems. Either the compact single rail type with recirculating ball bushing (A), the stronger double rail type also with recirculating ball bushings (B) or the fixed ball position ball bushings type (not shown) which require very little space and are used in the smallest units. Ball guides offer high accuracy, high loads and medium speed.



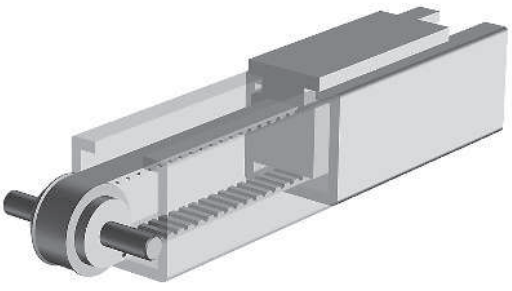
Ball Screw Drive
A ball screw is made up of a rotating screw and a moving ball nut. The ball nut is attached to the carriage of the unit. It does not have a normal thread, instead balls circulate inside the nut making it work as an efficient ball bearing that travels along the screw. Ball screws come in a large variety of leads, diameters and tolerance classes. The tolerance class (T3, T5, T7 or T9) indicates the lead tolerance of the screw. The lower the number, the higher the tolerance. High load capability and high accuracy are typical features of ball screw driven units.



Bearing Housing
Screw driven units has two bearing housings, front and rear. The front bearing housing has a drive shaft while the rear has none. Sometimes however the rear housing can have an optional output shaft which is used to connect to an encoder.

Bell House Flange
A bell house flange is used when a motor should be connected directly to the drive shaft of a linear motion system, i.e when it is direct driven. The bell house has the bolt pattern of the motor flange in one end and the bolt pattern of the drive shaft flange in the other while the two shafts are joined by a coupling. Also see “Direct Drive”.

Belt Drive
A belt drive consists of a toothed belt which is attached to the carriage of the unit. The belt runs between two pulleys positioned at either end of the profile. One pulley is attached to the motor via the drive shaft in the drive station while the other is mounted in a tension station. The belts are made of plastic reinforced with steel cords. High speeds, long stroke, low noise and low overall weight are typical features of belt driven units.



Glossary

Belt G - C

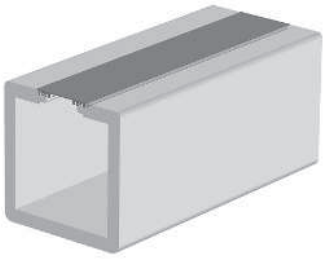
Belt Gear
A belt gear consist of a timing belt that runs between two pulley wheels of different diameter. The difference between the diameters determines the gear ratio. Belt gears are quiet, have medium accuracy and require no maintenance but are susceptible to belt breakage under overload conditions.

Brake
None of the units are equipped with a brake or are self-locking which means that a vertical unit will drop the carriage/load if no external brake (such as a brake in the motor, etc.) is applied to the drive shaft.. In the case of belt driven units care must be taken as the carriage/load will drop immediately in the case of a belt breakage. This is particularly important in vertical applications. You also may want to incoorporate a brake in to the system to ensure fast and secure stops at an emergency stop or a power failure. In this case the brake should be of the failsafe type, i.e. a brake that are engaged when power is off and lifted when it is on.

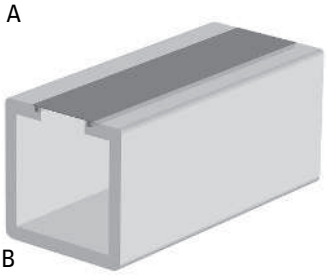
Carriage
The carriage is the moving member which travel along the profile of the unit to which the load is attached. Some units can have multiple carriages in order to distribute the weight of the load over a greater distance, this will however reduce the available stroke for a given profile length. There are also units having the option of short or long carriage. The short can carry less weight than a standard one but has a slightly longer stroke for a given profile length while the longer works the other way around. It is possible to fix the carriage(s) to the foundation and let the profile act as the moving member if so desired. This is often the case in vertical applications where you let the profile lift and lower the load.

CE Certificate
Linear motion systems do not need and do therefore not have any CE certification. All Thomson linear motion systems are however designed in accordance with the CE regulations and comes with a manufacturers declaration to prove this. Once the linear motion system is used or made in to a machine it is the responsability of the end customer to make sure the entire machine that the linear motion system is a part of is in accordance with the applicable CE regulations, produce the documents that proves this and apply a CE mark to the machine.

Cover Band
Cover bands are used on some units to protect them from the ingress of foreign objects through the opening in the profile where the carriage runs and can be made of plastic (A) or stainless steel (B). In the case of plastic the cover band seals the profile by snapping into small grooves running along the carriage opening. In the case of stainless steel the cover band seal the profile magnetically using magnet strips mounted on each side of the carriage opening. Some units also have a self-adjusting cover band tensioning mechanism that eleminates any slack in the cover band that can occur from temperaure changes, thus improving the sealing degree and the expected life of the cover band.

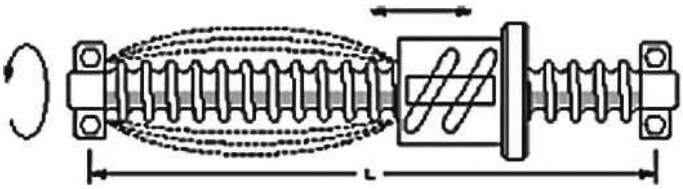


A



B

Critical Speed
All ball screws have a critical speed where the screw starts to vibrate and eventually bend or warp the screw . The excact limit is a function of how tlong the screw is and the speed. For some units this means that the allowed maximum speed found in the performance specifications can be higher than the critical speed when the stroke exceeds a certain distance. In this case, either the speed must be reduced to the critical speed, the amount of stroke must be reduced, or you must use the screw support option if the unit in quiestion allows this. Otherwise you must select another unit that can manage the speed at that stroke. The critical speed limits can be found in the “Critical Speed” diagrams on the prodcut pages of the units that this concern.



Customization
Despite the large range of linear motion systems offered by Thomson you may not find the exact unit to suit your application. But whatever your need is, Thomson are ready to help you to customize a unit according to your requirements. Please contact customer service for more information.

Cycle
One cycle is when the carriage has travelled back and forth over the complete stroke of the unit one time.

Glossary

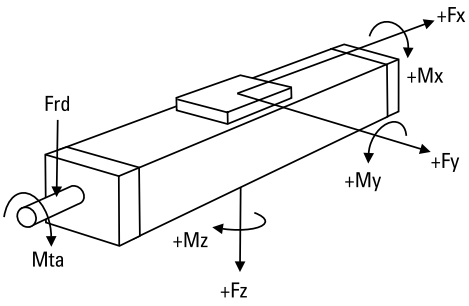
D - E

Deceleration

Deceleration is a measure of the rate of speed change going from a higher speed to a lower speed (or standstill). Please contact customer service if your application is critical to which deceleration rate is acceptable or needed.

Definition of Forces

The designations of the forces that acts on the unit are defined on the product page of each unit in the "Definition of Forcs" drawing (see example below). Please always use the same definitions whenever communicating with Thomson.



Deflection of the Profile

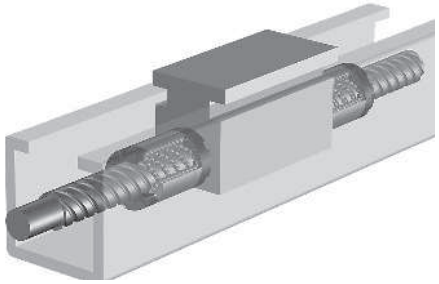
Some units require support along the whole profile whilst some are self supporting over a specified span. Further details can be found on the product data pages. The recommended support intervals should be followed to minimise deflection of the unit. The maximum distance between the support points is shown on the product data pages. The deflection of the unit can also be calculated using the information in the "Additional data and calculations" section.

Direct Drive

Direct drive means that there is no gearing between the motor and the drive shaft of the linear motion system. Instead the motor is connected to the unit directly via a coupling and an bell house adapter flange. Also see "Bell House Flange".

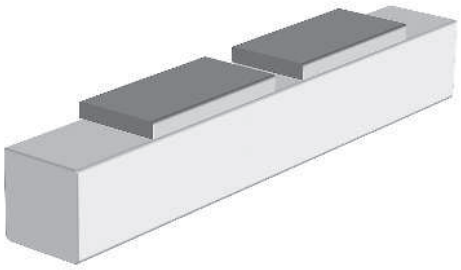
Double Ball Nuts

Using double ball nuts will increase the repeatability of the unit. The ball nuts are installed so that they are pre-tensioned against each other eleminating the play between the nuts and the screw. A double nut unit will have a slightly shorter stroke for a given overall length.



Double Carriages

Double carriage units have two carriages which gives them higher load capabilites than single carriage units. When ordering a double carriage unit the distance between the two carriages needs to be defined. This distance is called L_A or Lc depending on the model.



Drive Shaft

The drive shaft is the is the shaft to which the motor is connected, either directly, via a bell house flange or via a gear box. There are many sizes and types of drive shafts, such as shafts with or without key way or hollow shafts, depending on the type and size of the unit. Belt driven units can often have two drive shafts (same or different type and size), one on each side of the drive station, while screw driven only have on pointing out of the end of the unit. Customized drive shafts are possible, please contact customer service for more information.

Drive Station

The drive station is the mechanical assembly in one of the ends of a belt driven unit where the drive shaft is situated.

Duty Cycle

All units are designed for a 100% duty cycle. However, where the unit runs at extreme load, speed, acceleration and temperature or for long operating periods the expected life time may be reduced.

Encoder Feedback

Encoders provide a digital output signal in the form of a square shaped pulse train that can be used to determine the position of the extension tube. The encoder signal in a servo motor system is connected to the motion control so that it can control the servo drive and hence close the position feedback loop.

End of Stroke Limit Switches

If a unit runs at speed to the ends of its stroke there is a risk of damage. Damage can be prevented by using end of stroke limit switches to detect and engage a brake and/or cut power to the motor when the unit nears the end of the unit. You must ensure that there is sufficient distance between the end of stroke limit switch and the end of the unit, to allow the carriage to come to a complete stop before colliding with the end. The required stopping distance depends on the speed and the load and will have to be calculated for each application. The stopping distance must be taken into account when defining the necessary stroke.

Glossary

G - M

Guides
Guides are in essence a form of linear bearings on which the carriage(s) travel. Thomson uses three main types of guides that all have different characteristics and which to choose depends on the demands of the application. Alos see “Ball Guides”, “Slide Guides” and “Wheel Guides”.

Idle Torque
Idle torque is the torque needed to move the carriage with no load in it by rotating the drive shaft. The idle torque will vary with the input speed and the idle torque tables on the product pages gives a value for some speeds. The value given in the table is for a unit having a single carriage of standar length. If you need the exact value for another speed, multiple carriages or short/long carriages , please contact our customer service.

Inertia
Inertia is the property of an object to resist speed changes and is dependant on the shape and the mass of the object. The inertia is important when sizing and selecting and also when tuning a servo system to optimum performance. Consult customer service for more information.

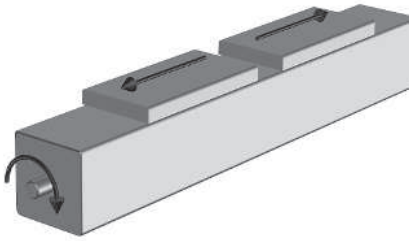
Input Shaft
The input shaft is the shaft to wich the power source (motor) is connected to on a gear box. Primary shaft is another term for this. Sometimes the drive shaft on a linear unit also is refered to as the input shaft.

Input Speed
Input speed is the rotational speed that the drive shaft/input shaft of a linear motion system or a gear box is subjected to.

Installation and Service Manual
Each linear motions system has an installation and service manual to answer typical questions about mounting and servicing the unit.

Lead Accuracy
Lead accuracy is a measure of how accurate the lead of a ball screw is. For a ball screw with a lead of 25 mm, the screw should in theory move the nut 25 mm per each revolution. In reallity there will be a deviation between the expected traveling distance and what is actually achieved. The deviation is typically for a ball screw 0,05 mm per 300 mm of stroke. Contact customer service for more information.

Left/right Moving Carriages
Units with left/right moving carriages have two carriages moving in opposite directions when the drive shaft is rotated. This type of unit has a ball screw where half of the screw has a left hand thread and the other half a right hand thread.



Lifetime Expectancy
When determining the lifetime for a linear motion system it is necessary to evaluate all forces and moments that are acting on the unit. The data and formulas given in this catalogue serve as a basis for this. For a more detailed lifetime calculation please use our sizing and selection software. Please contact us for further guidance.

Linear Lifting System
A linear lifting system is in essence a linear motion system specially designed for vertical lifting applications. Some units can be used in horizontal applications as well under certain criterias. Please contact us if you plan to mount a lifting unit in any other position than vertically with the load carrying plate pointing down.

Linear Motion System
A linear motion system is a mechanical assembly that translates the rotating motion of a motor to the linear motion of a carriage that travel along a load supporting beam/profile. Other names for linear motion systems are linear units, linear drive units and rodless actuators among others.

Load Rating
There are many types of load ratings that all needs to be considered. Normally when you speak about the load you refer to the load that the carriage will move; which is the dynamic load. But there may also be static, side, moment and forces from acceleration, deceleration, gravity and friction that are all equally important. For some units the load and load torque values are given for both the complete unit and the guiding system. The values for the complete unit are the values under which the unit can operate. The values for the guiding system should only be used when comparing different units and do not describe the actual performance of the complete unit.

Maintenance
Most units require lubrication. General lubrication requirements can be found in the general specifications table on the product data pages. The lubrication intervals, grease qualities and specific lubrication instructions can be found in the installation and service manual of each unit. No other regular maintenance is needed except for normal cleaning and inspection. Units with a cover band may also require irregular cover band replacement due to wear. The belt in belt driven units should not require re-tensioning under normal operating conditions.

Manufacturers Declaration
All Thomson linear motion systems comes with a manufacturers declaration to prove that it is built according to the CE regulations.

Mounting
Most units can be mounted in any direction. Any restrictions on mounting positions are shown on the product presentation pages at the beginning of each product category chapter. Even where units may be mounted in any direction there are some considerations. None of the units are self-locking which means that a vertical unit will drop the carriage/load if no

Glossary

N - Sc

external brake (such as a brake in the motor, etc.) is applied to the drive shaft of the unit. In the case of belt driven units care must be taken as the carriage/load will drop immediately in the case of a belt breakage. This is particularly important in vertical applications. All ball screw driven units are equipped with a safety nut to prevent the carriage/load being released in case of ball breakage.

Non Driven Linear Motion Systems

A non driven linear motion system has no drive shaft or any type of transmission. In reality a non driven linear motion system is a guide that has the same look and outer dimensions as the driven version. Normally a non driven unit is used together with a parallel working driven unit that are mechanically linked where the non driven unit help to share to load with the driven one.

Non Guided Linear Motion Systems

A non guided linear motion system has a drive shaft and a ball screw but no guides. In reality a non guided linear motion system is a enclosed ball screw assembly with a carriage that has the same look and outer dimensions as the driven version. Using a non guided unit requires some kind of external guide to which the carriage can be attached.

Operation and Storage Temperature

Operational temperature limits can be found in the performance tables on the product data pages. Units can be stored or transported within the same temperature range. Please contact us if the unit will be exposed to higher/lower temperatures than recommended during storage or transportation.

Output Shaft

The output shaft is the shaft on a gear box that is connected to object being driven by the gear box. Another term for output shaft is secondary shaft.

Packages and Multi Axis Kits

Thomson can offer complete pre-defined packages (linear motion system, gear and servo motor assembled and shipped with servo drive and cables) as well as mounting kits for the creation of two and three axis systems Please contact us for further information.

Positioning Accuracy

Positioning accuracy is the error between the the expected and actual position and is the sum of all factors that will reduce the accuracy (i.e. repeatability, backlash, resolution, screw/belt accuracy, and the accuracy of the motor, drive and motion control system). Some of these factors, such as backlash and lead accuracy, can sometimes be compensated for in the software of the motion control system being used. Also see “Accuracy”.

Position Feedback

The position of the carriage/rod/lifting profile can be obtained in many ways. The most common way is to equip the unit with an encoder or to use a motor which has a built in feed back device (encoder, resolver, etc.). To many units there are encoders or/and encoder mounting kits available. See the accessory chapter.

Repeatability

Repeatability is the ability for a positioning system to return to a location when approaching from the same distance, at the same speed and deceleration rate. Some of the factors that affect the repatability are the angular repeatability of the motor, drive and motion control system, system friction and changes in load, speed and deceleration.

Resolution

Resolution is the smallest move increment that the system can perform. Some of the factors that affect the resolution are the angular repeatability of the motor, drive and motion control system, system friction, the drive train reduction, the lead/type of the ball screw/belt and changes in load, speed and deceleration.

Resolver

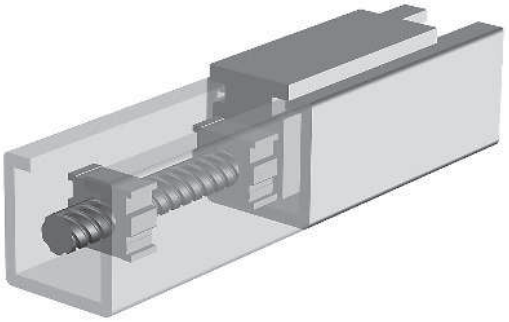
A resolver is basically a type of rotary electrical transformer used for measuring degrees of rotation and are commonly used on AC servo motors as a feedback device to control the commutation of the motor windings. The resolver is mounted to the end of motor shaft and when the motor rotates the resolver will transmit the position and direction of the rotor to the servo drive which then can control the motor. Most servo drives for AC servo motors on the market today can convert the resolver signal in to a pulse train (encoder signal simulation) which can be used by a motion control to determine and control the position of the motor. Also see “Encoder Feedback”.

RoHS Compliance

The RoHS directive stands for “the restriction of the use of certain hazardous substances in electrical and electronic equipment”. This directive bans the placing on the EU market of new electrical and electronic equipment containing more than agreed levels of lead, cadmium, mercury, hexavalent chromium, polybrominated biphenyl (PBB) and polybrominated diphenyl ether (PBDE) flame retardants. All linear motion systems and accessories sold in the EU are RoHS compliant.

Screw Supports

Screw supports allow screw driven units to travel at high speed even when stroke becomes longer. The supports reduce the unsupported length of the screw, that otherwise would be subjected to vibrations. Screw supports come in single (one screw support on each side of the carriage) or double (two supports on each side) versions. Screw support units will have a slightly shorter stroke for a given overall length.

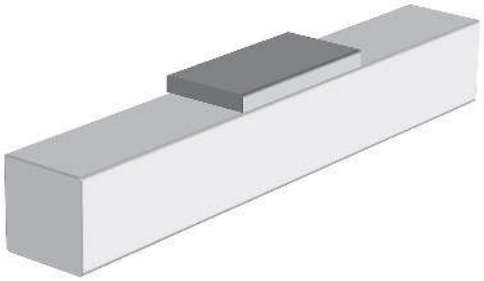


Glossary

Si - W

Single Carriage

Single carriage units have one carriage. Some linear motion system models also have the option of long or short single carriage. The long carriage handle higher loads but will have a longer overall length for a given stroke.

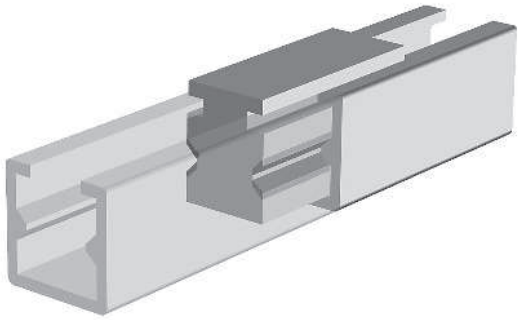


Sizing and Selection

This catalog can give you an overview of what Thomson can offer you and an indication of which products that may suit your application. But in order to get the best solution it is neccessary to know your specific application and to carry out detailed sizing and selection calculations. Please contact customer service for further help.

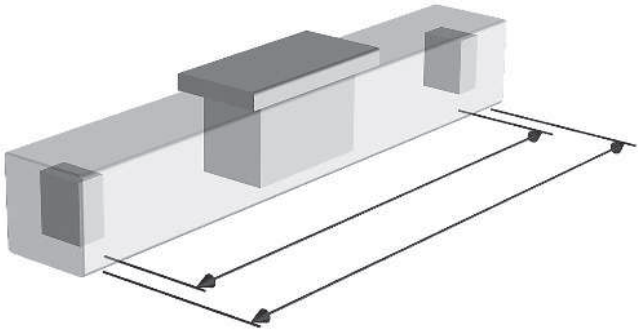
Slide Guides

A slide guide consist of a guide attached to the inside of the profile and a slide bushing attached to the carriage. The guide can be made of different materials (e.g. polished hardened steel, anodized aluminium) while the bushing is made of a polymer material. There are two types of bushings, fixed and prism. Prism bushings can move in relation to the guide which results in longer life and higher load capabilities. Slide bushings are silent, simple, reliable and robust and can be used in dirty and dusty environments. They are also resistant to shock loads, have a long life expectancy and require little or no maintenance.



Stroke

The theoretical maximum stroke (S max) is the length that the carriage can travel from one end of the unit to the other. However, using the maximum stroke means that the carriage will collide with the ends of the profile. The practical stroke is therefore shorter. We recommend that you specify a unit that have at least 100 mm longer stroke than the maximum stroke you need so that the unit can stop before colliding with the ends and also allow for some adjustment of the unit postition at the mounting.

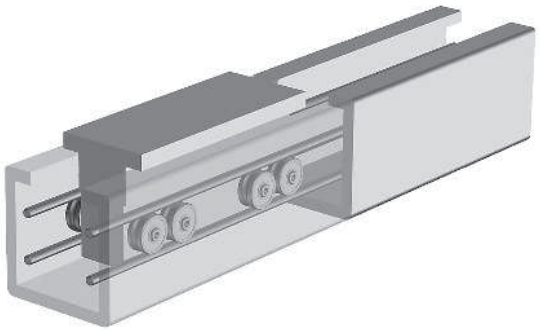


Tension Station

The tension station is the mechanical assembly situated in the opposite end of the drive station on a belt driven unit. The tension station has a mechanism that allows the belt pulley position to be adjusted thus changing the tension of the belt. Adjustment of the belt tension is normally only necessary when replacing a broken or worn out belt with a new.

Wheel Guides

A wheel guide consists of ball bearing wheels that run on a hardened steel rail. Wheel guides are a simple and robust guiding method offering high speeds, high loads and medium accuarcy.



Working Environment

All units are designed for use in normal industrial environments. Units which have an open profile (i.e. have no cover band) are more sensitive to dust, dirt and fluids. These units require some kind of cover if they are used in environments where dust, dirt or fluids are present. Enhanced wash-down or chemical protection can be ordered for our closed profile units. Please refer to the accessory pages. In all cases where a unit will be exposed to aggressive chemicals, heavy vibrations or other potentially harmful processes we recommend that you contact us for further advice.

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